

Basis for Automatic Service Composition

Daniela Berardi *
Giuseppe De Giacomo
Massimo Mecella

*Dipartimento di Informatica e Sistemistica
"Antonio Ruberti"*

Università di Roma "La Sapienza"

`{berardi,degiacomo,mecella}@dis.uniroma1.it`

** now at **Innovazione Italia**
Italian Ministry for Technological Innovation*

Instructors

- **Daniela Berardi**

Research Interests:

- AI: Knowledge Representation, Reasoning about Action, Planning
- Software Engineering: Conceptual Modeling
- Services: Modeling and Composition
- Applications: e-Health Systems

- **Giuseppe De Giacomo**

Research Interests:

- AI: Knowledge Representation, Reasoning about Action, Planning, Cognitive Robotics
- Databases: Databases with Incomplete Information, Data Integration, Semantic Interoperability
- Dynamic Systems: Reasoning on Dynamic Systems, Process Verification and Synthesis
- Services: Composition

- **Massimo Mecella**

Research Interests:

- Software Architectures: Cooperative Information Systems for e-Government and e-Business
- Information Systems: Workflow Management, Data Quality
- Distributed Systems: Middleware and Mobile Applications
- Services: Modeling, Compatibility and Substitution, Composition and Orchestration

Outline

- Part 1 (Massimo Mecella)
 - Basic Concepts
 - Relevant Technologies and Abstractions
- Part 2 (Daniela Berardi)
 - State of the Art of the Research in Composition
 - Classification of Different Approaches
- Part 3 (Giuseppe De Giacomo)
 - Basic Research Perspective
 - The Roman Approach

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Basic Concepts

e-Services, Web Services, Services ... (1)

- An e-Service is often defined as an **application accessible via the Web**, that provides a set of functionalities to businesses or individuals. What makes the e-Service vision attractive is the ability to automatically discover the e-Services that fulfill the users' needs, negotiate service contracts, and have the services delivered where and when users needs them

Guest editorial. In [VLDBJ01]

- e-Service: **an application component** provided by an organization in order to be assembled and reused in a distributed, Internet-based environment; an application component is considered as an e-Service if it is: (i) **open**, that is independent, as much as possible, of specific platforms and computing paradigms; (ii) **developed mainly for inter-organizations applications**, not only for intra-organization applications; (iii) **easily composable**; its assembling and integration in an inter-organizations application does not require the development of complex adapters.
e-Application: a distributed application which integrates in a cooperative way the e-Services offered by different organizations

M. Mecella, B. Pernici: Designing Wrapper Components for e-Services in Integrating Heterogeneous Systems. In [VLDBJ01]

e-Services, Web Services, Services ... (2)

A Web service is a **software system** identified by a URI, whose **public interfaces** and bindings are defined and described using XML. Its definition can be discovered by **other software systems**. These systems may then **interact with** the Web service in a manner prescribed by its definition, using XML based **messages** conveyed by Internet protocols

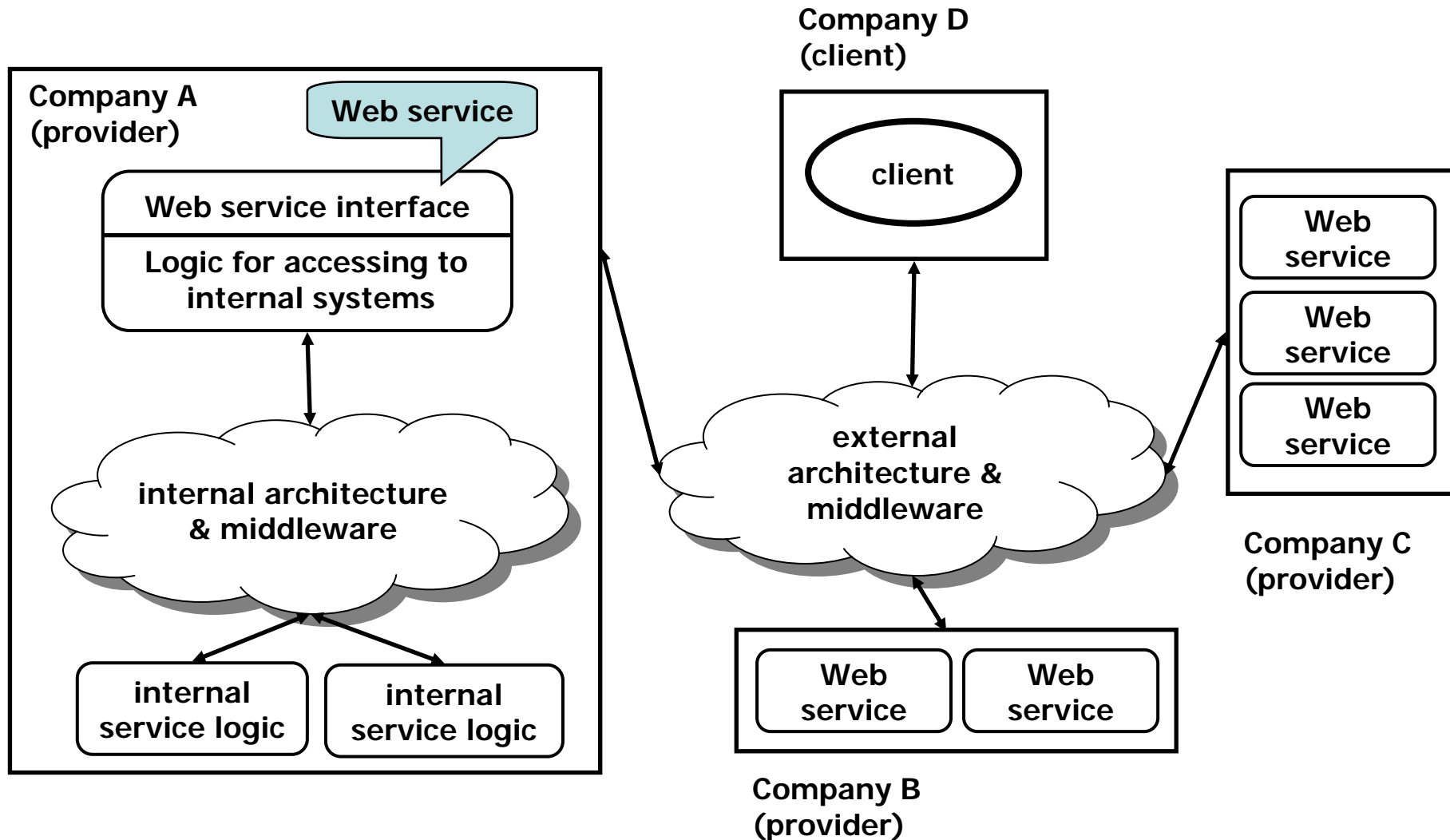
*Web Services Architecture Requirements,
W3C Working Group Note, 11 Feb. 2004,
<http://www.w3.org/TR/wsa-reqs/>*

e-Services, Web Services, Services ... (3)

- **Services are self-describing, open components that support rapid, low-cost composition of distributed applications.** Services are offered by service providers — organizations that procure the service implementations, supply their service descriptions, and provide related technical and business support. Since services may be offered by different enterprises and communicate over the Internet, they provide a distributed computing infrastructure for both intra and cross-enterprise application integration and collaboration. Service descriptions are used to advertise the service capabilities, interface, behavior, and quality. Publication of such information about available services provides the necessary means for discovery, selection, binding, and composition of services. In particular, the service capability description states the conceptual purpose and expected results of the service (by using terms or concepts defined in an application-specific taxonomy). The service interface description publishes the service signature (its input/output/error parameters and message types). The (expected) behavior of a service during its execution is described by its service behavior description. Finally, the Quality of Service (QoS) description publishes important functional and nonfunctional service quality attributes [...]. Service clients (end-user organizations that use some service) and service aggregators (organizations that consolidate multiple services into a new, single service offering) utilize service descriptions to achieve their objectives.
- **The application on the Web (including several aspects of the SOA) is manifested by Web services**

Guest editorial. In [CACM03]

Two Architectures (and Middlewares) (1)



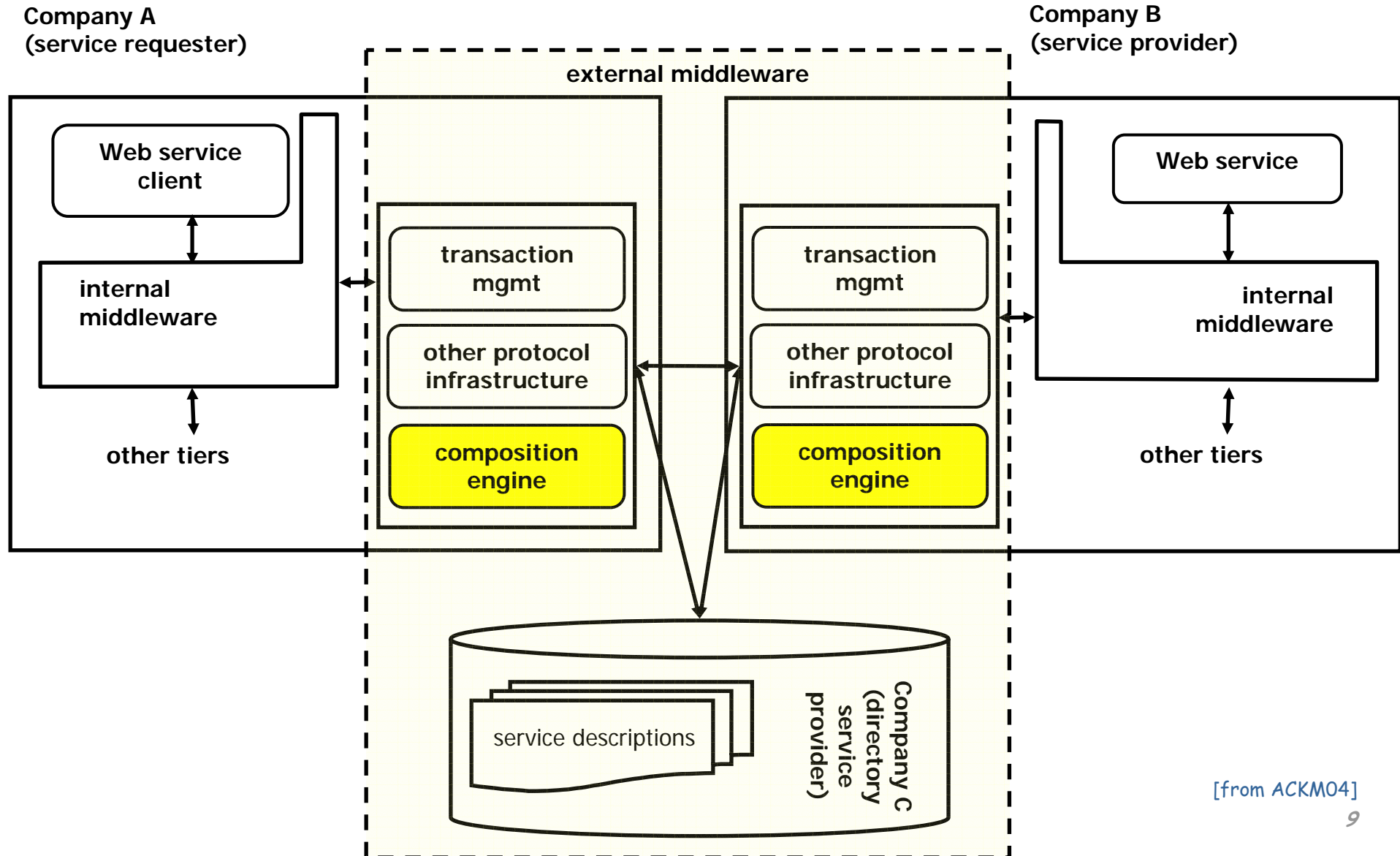
[from ACKM04]

WWW 2005 Tutorial (May 10, 2005 - Chiba, Japan)

Berardi, De Giacomo, Mecella

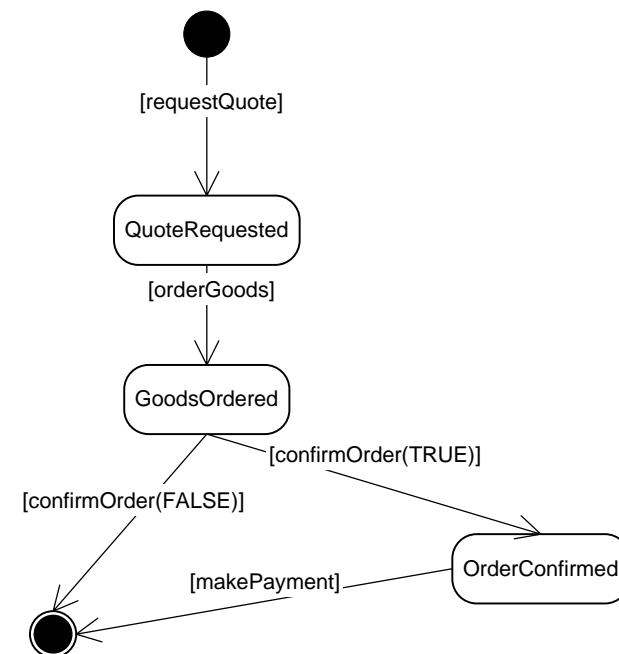
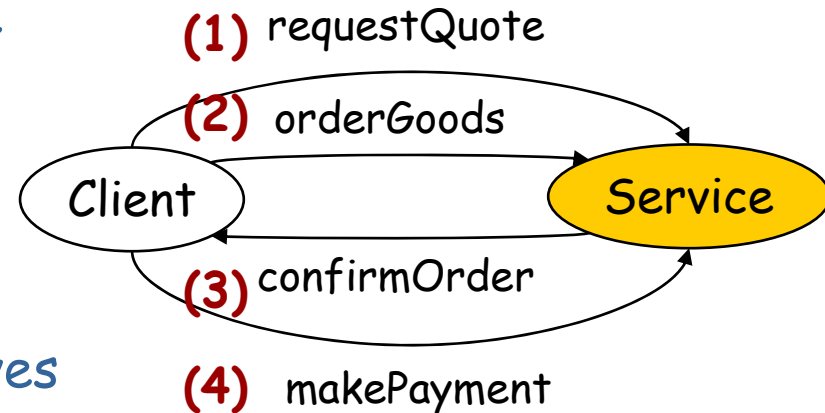
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Two Architectures (and Middlewares) (2)



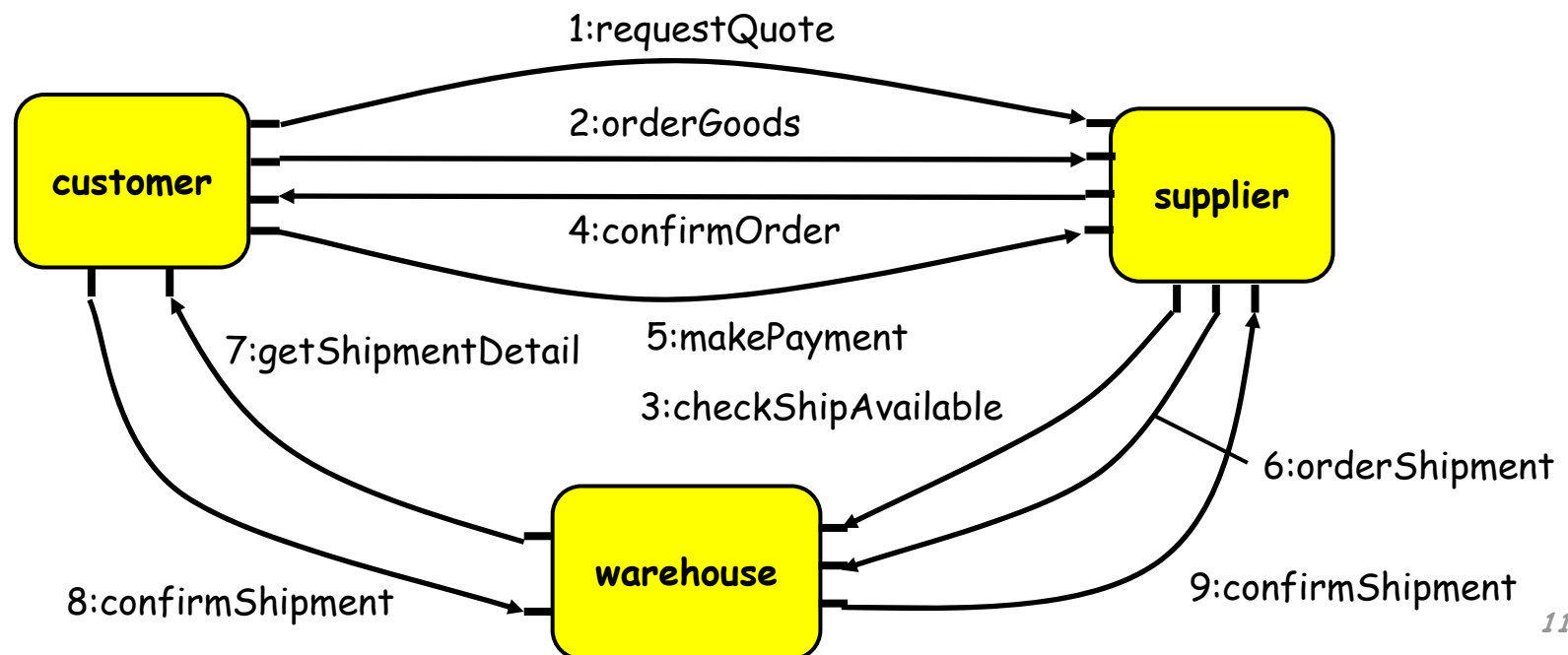
Services

- A service is characterized by the set of (atomic) **operations** that it exports ...
- ... and possibly by constraints on the possible **conversations**
 - Using a service typically involves performing sequences of operations in a particular order (**conversations**)
 - During a conversation, the client typically chooses the next operation to invoke (on the basis of previous results, etc.) among the ones that the service allows at that point

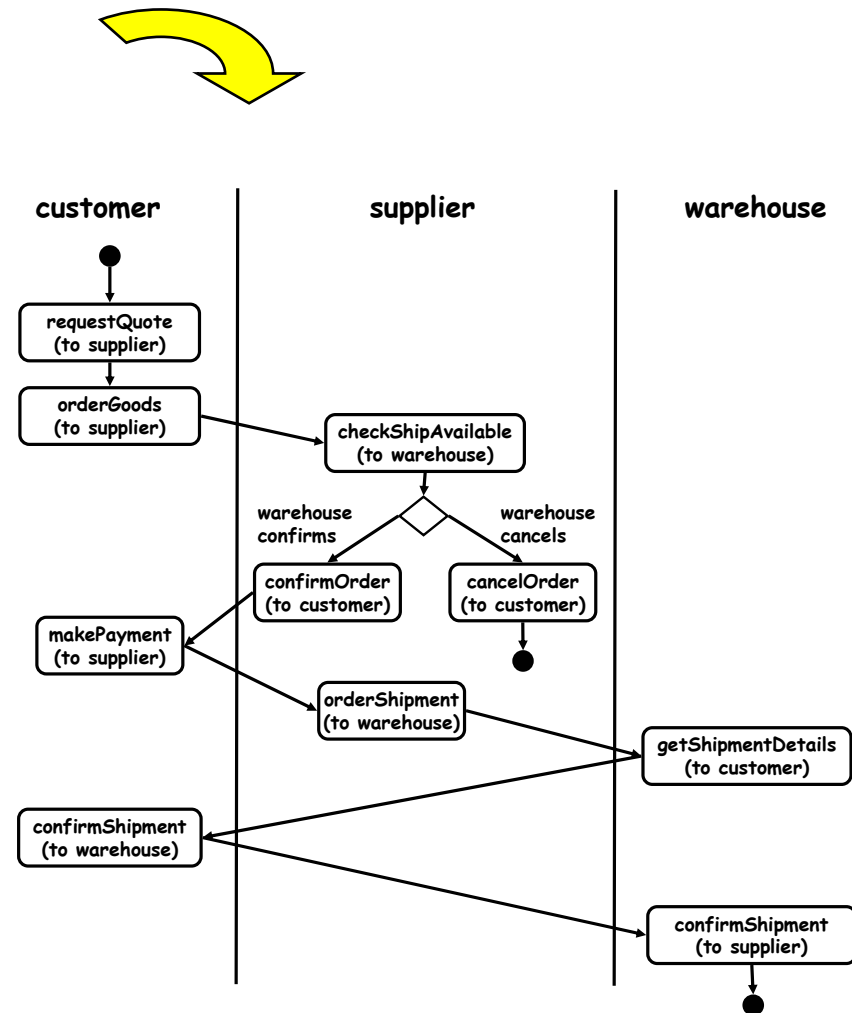
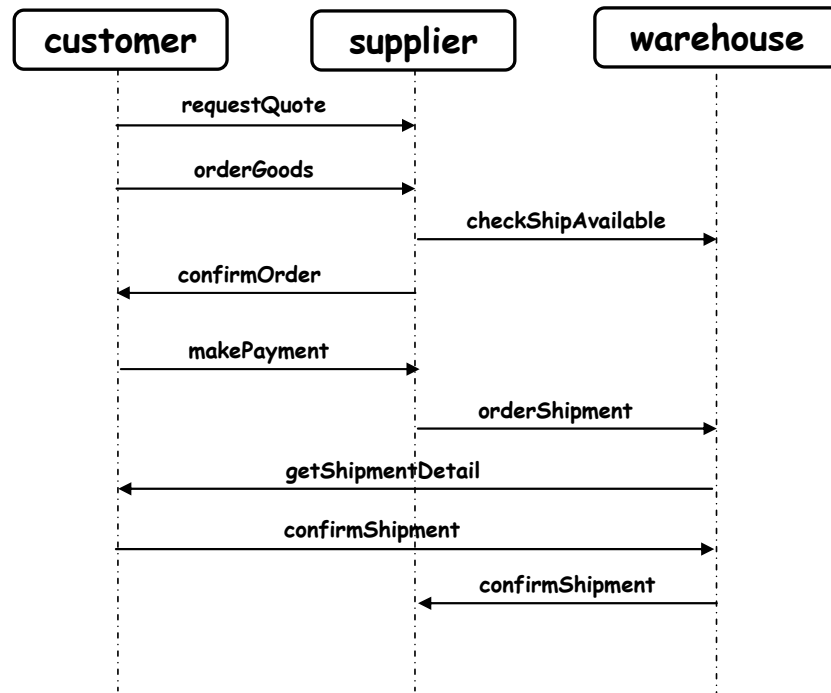


Choreography: Coordination of Conversations of N Services

- Global specification of the conversations of N **peer** services (i.e., multi-party conversations)
 - Roles
 - Message exchanges
 - Constraints on the order in which such exchanges should occur



Choreography: Coordination of Conversations of N Services



[from ACKM04]

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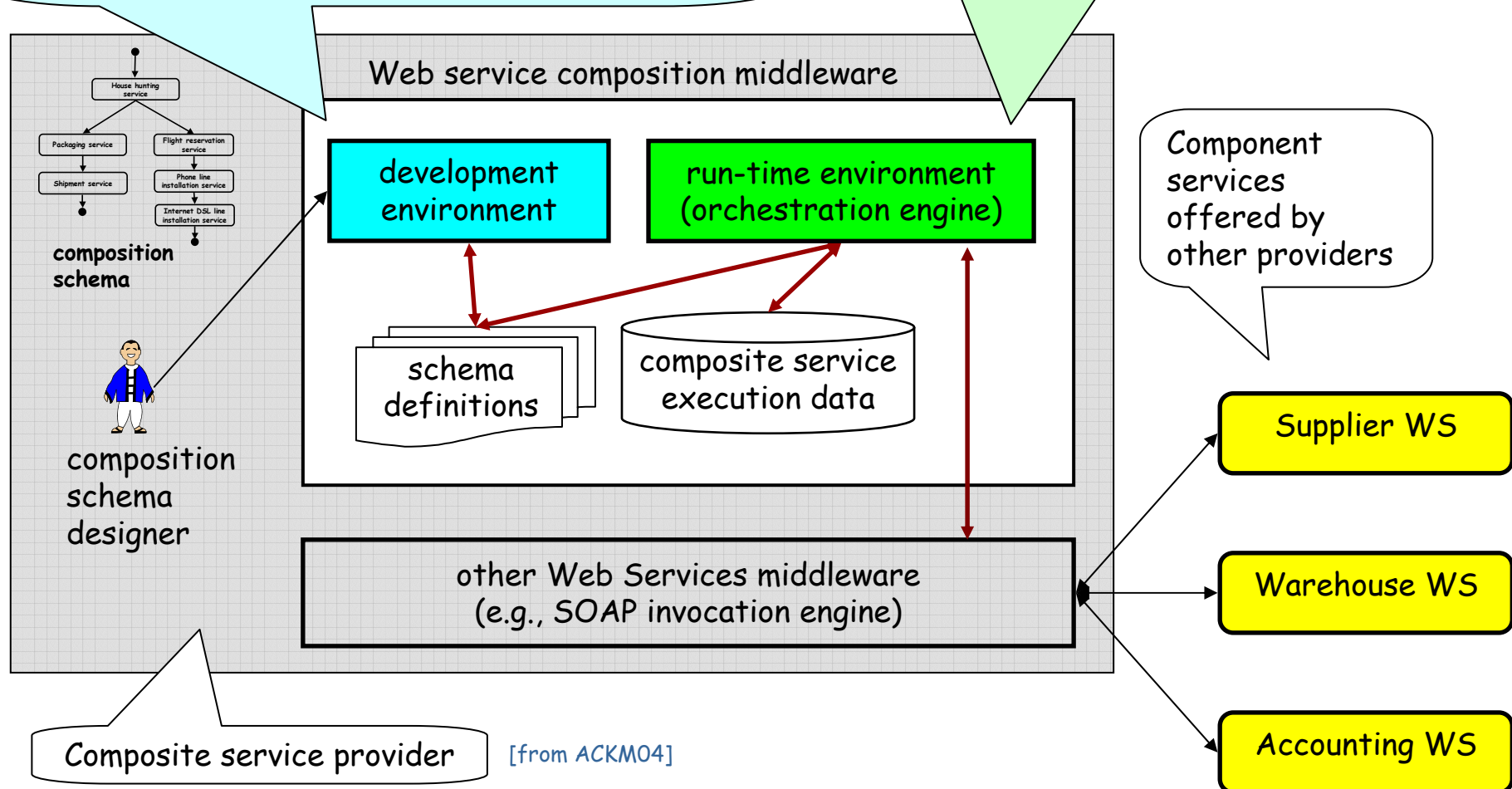
Composition

- Deals with the **implementation** of an application (in turn offered as a service) whose application logic **involves the invocation of operations offered by other services**
 - The new service is the *composite service*
 - The invoked services are the *component services*

The Composition Engine/Middleware

Through the development environment, a **composition schema** is **synthesized**, either manually or (semi-)automatically. A service composition model and a language (maybe characterized by a graphical and a textual representation) are adopted

Orchestration: the run-time environment executes the composite service business logic by invoking other services (through appropriate protocols)



Synthesis and Orchestration

- (Composition) Synthesis: building the specification of the composite service (i.e., the composition schema)
 - Manual
 - Automatic
- Orchestration: the run-time management of the composite service (invoking other services, scheduling the different steps, etc.)
 - Composition schema is the "program" to be executed
 - Similarities with WfMSs (Workflow Management Systems)

Composition Schema

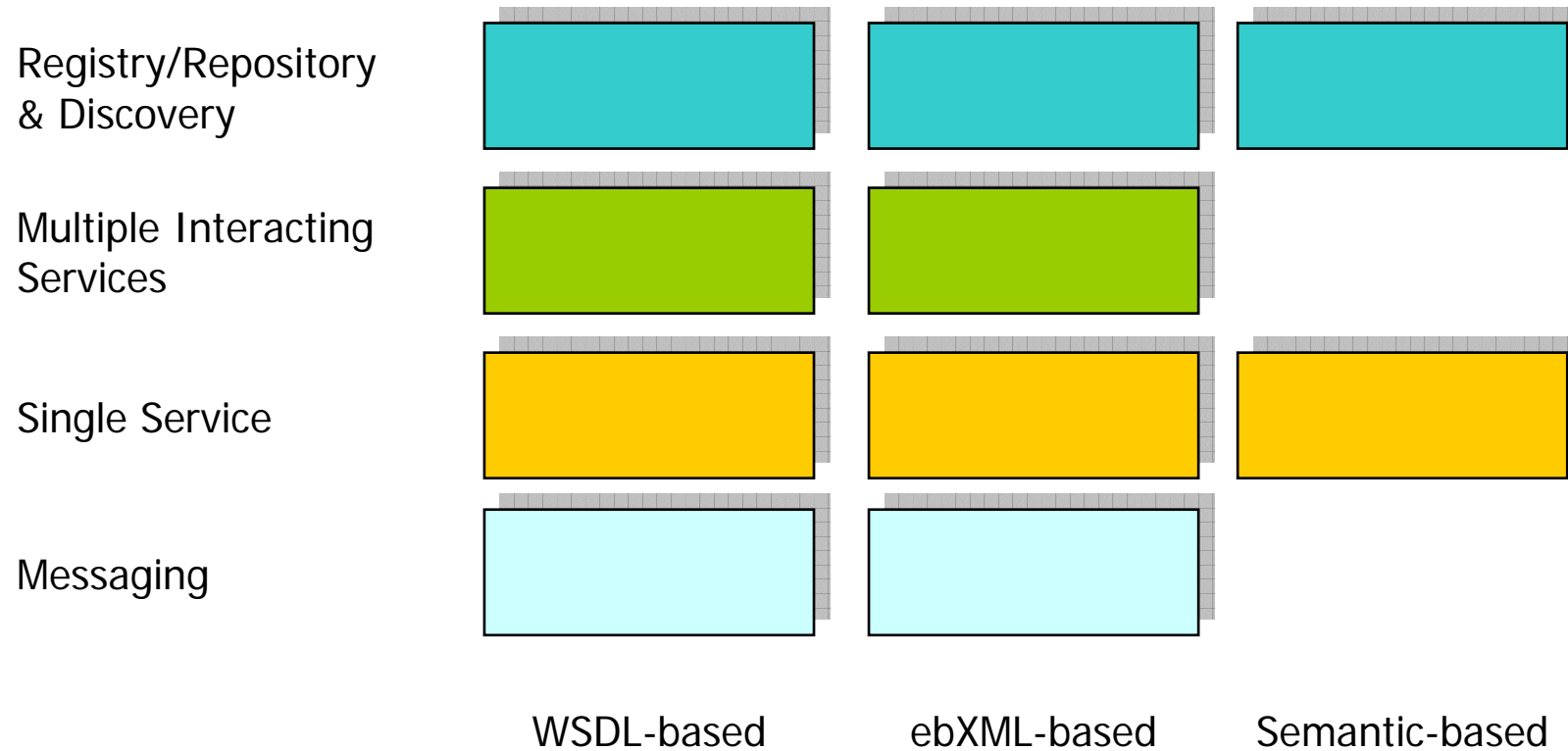
- A composition schema specifies the "process" of the composite service
 - The "workflow" of the service
- Different clients, by interacting with the composite service, satisfy their specific needs (reach their goals)
 - A specific execution of the composition schema for a given client is an orchestration instance

Choreography (Coordination) vs. Composition (Orchestration)

- Composition is about implementing new services
 - From the point of view of the client, a composite service and a basic (i.e., implemented in a traditional programming language) one are indistinguishable
- Choreography is about global modeling of N peers, for proving correctness, design-time discovery of possible partners and run-time bindings
- N.B.: There is a strong relationship between a service internal composition and the external choreographies it can participate in
 - if A is a composite service that invokes B, the A's composition schema must reflect the coordination protocol governing A - B interactions
 - in turn, the composition schema of A determines the coordination protocols that A is able to support (i.e., the choreographies it can participate in)

Relevant Technologies and Abstractions

The "Stacks" of Service Technologies



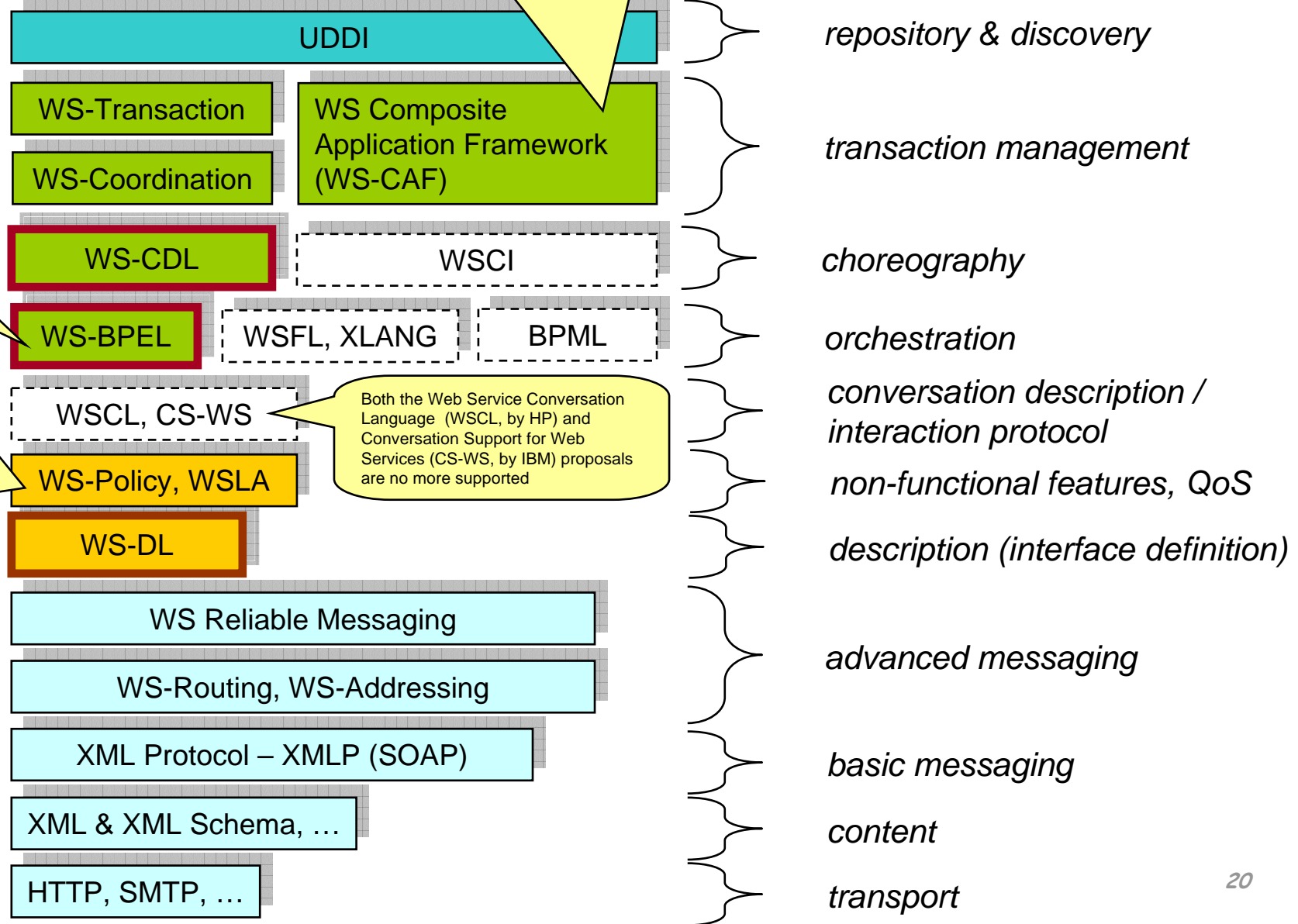
The WSDL-based "Stack"

Includes 3 specifications:
 (i) Web Service Context (WS-CTX)
 (ii) Web Service Coordination Framework (WS-CF)
 (iii) Web Service Transaction Management (WS-TXM)

Formerly BPEL4WS (BPEL for short)

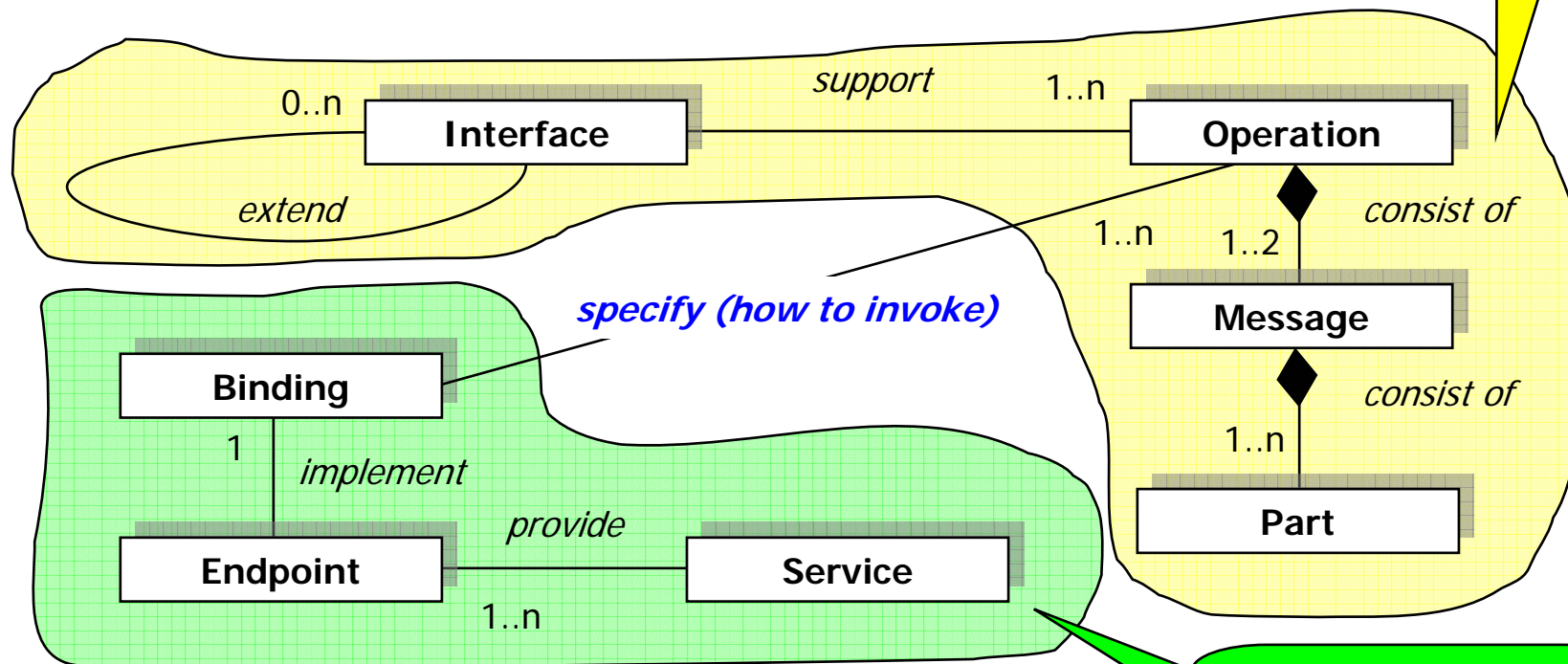
(i) formerly also WSEL (Web Service Endpoint Language) by IBM
 (ii) also the research/academic proposal Web Service Offering Language [WSOL]

Both the Web Service Conversation Language (WSCL, by HP) and Conversation Support for Web Services (CS-WS, by IBM) proposals are no more supported



Web Service Definition Language (WS-DL)

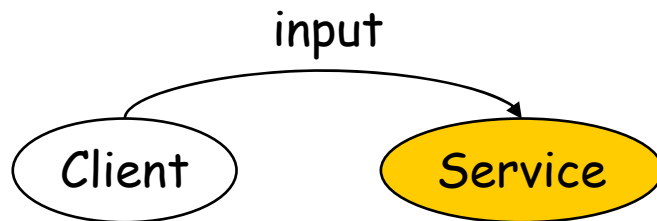
- WS-DL (v2.0) provides a framework for defining
 - Interface: operations and input/output formal parameters
 - Access specification: protocol bindings (e.g., SOAP)
 - Endpoint: the location of service



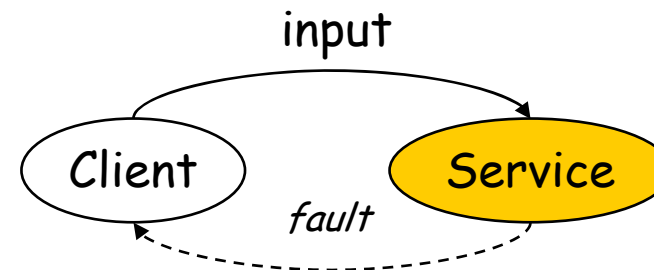
Service interface (abstract definition)

Service implementation (concrete definition)

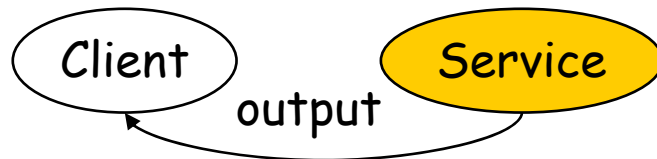
Message Exchange Patterns (1)



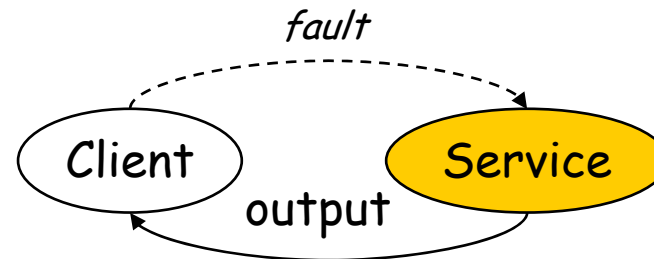
in-only (no faults)



robust in-only (message triggers fault)

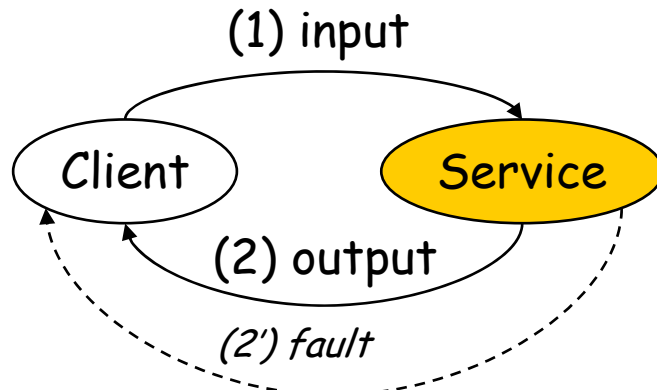


out-only (no faults)

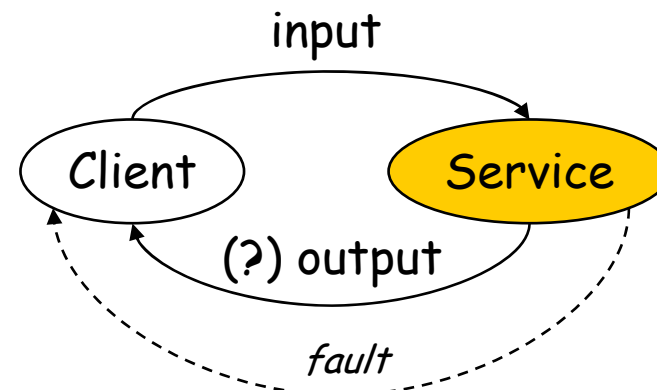


robust out-only (message triggers fault)

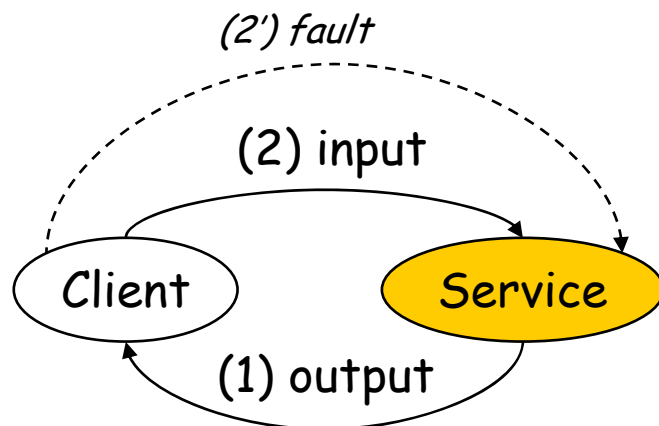
Message Exchange Patterns (2)



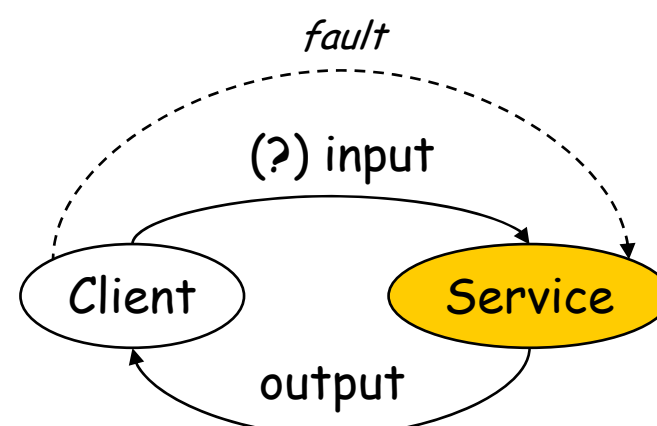
in-out (fault replaces message)



in-optional-out (message triggers fault)



out-in (fault replaces message)



out-optional-in (message triggers fault)

An Example (1)

```
<definitions ... >
```

```
  <types>
```

```
    <element name="ListOfSong_Type">
```

```
      <complexType><sequence>
```

```
        <element minOccurs="0" maxOccurs="unbound"  
          name="SongTitle" type="xs:string"/>
```

```
      </sequence></complexType>
```

```
    </element>
```

```
    <element name="SearchByTitleRequest">
```

```
      <complexType><all>
```

```
        <element name="containedInTitle"  
          type="xs:string"/>
```

```
      </all></complexType>
```

```
    </element>
```

```
    <element name="SearchByTitleResponse">
```

```
      <complexType><all>
```

```
        <element name="matchingSongs"
```

```
          xsi:type="ListOfSong_Type"/>
```

```
      </all></complexType>
```

```
    </element>
```

Definition of a
message and its
formal
parameters

An Example (2)

```
<element name="SearchByAuthorRequest">
  <complexType><all>
    <element name="authorName"
      type="xs:string"/>
  </all></complexType>
</element>
<element name="SearchByAuthorResponse">
  <complexType><all>
    <element name="matchingSongs"
      xsi:type="ListOfSong_Type"/>
  </all></complexType>
</element>
<element name="ListenRequest">
  <complexType><all>
    <element name="selectedSong"
      type="xs:string"/>
  </all></complexType>
</element>
```

An Example (3)

```
<element name="ListenResponse">
  <complexType><all>
    <element name="MP3fileURL" type="xs:string"/>
  </all></complexType>
</element>
<element name="ErrorMessage">
  <complexType><all>
    <element name="cause" type="xs:string"/>
  </all></complexType>
</element>
</types>
```

An Example (4)

Definition of a service interface

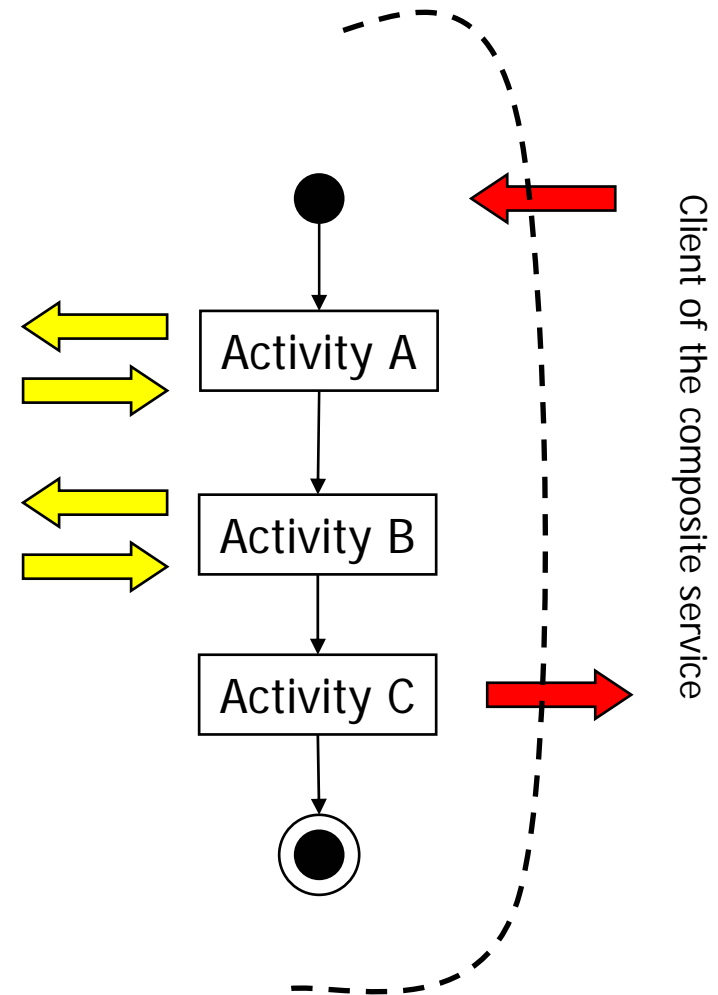
```
<interface name="MP3ServiceType">
  <operation name="search_by_title" pattern="in-out">
    <input message="SearchByTitleRequest"/>
    <output message="SearchByTitleResponse"/>
    <outfault message="ErrorMessage"/>
  </operation>
  <operation name="search_by_author" pattern="in-out">
    <input message="SearchByAuthorRequest"/>
    <output message="SearchByAuthorResponse"/>
    <outfault message="ErrorMessage"/>
  </operation>
  <operation name="listen" pattern="in-out">
    <input message="ListenRequest"/>
    <output message="ListenResponse"/>
    <outfault message="ErrorMessage"/>
  </operation>
</interface>
</definitions>
```

Definition of an operation and its message exchange pattern



Business Process Execution Language for Web Services (WS-BPEL)

- Allows specification of composition schemas of Web Services
 - Business processes as coordinated interactions of Web Services
 - Business processes as Web Services
- Allows abstract and executable processes
- Influenced from
 - Traditional flow models
 - Structured programming
 - Successor of WSFL and XLANG
- Component Web Services described in WS-DL (v1.1)



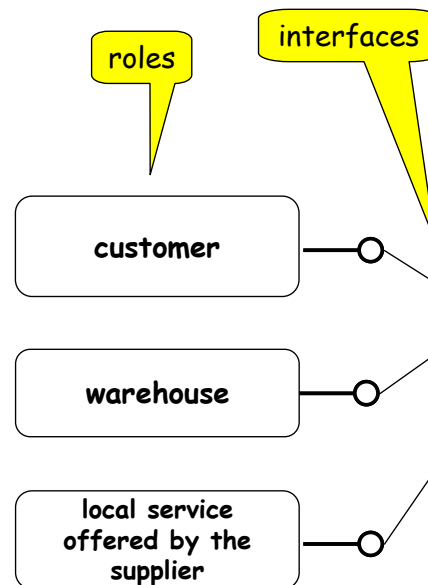
WS-BPEL Specification

An XML document specifying

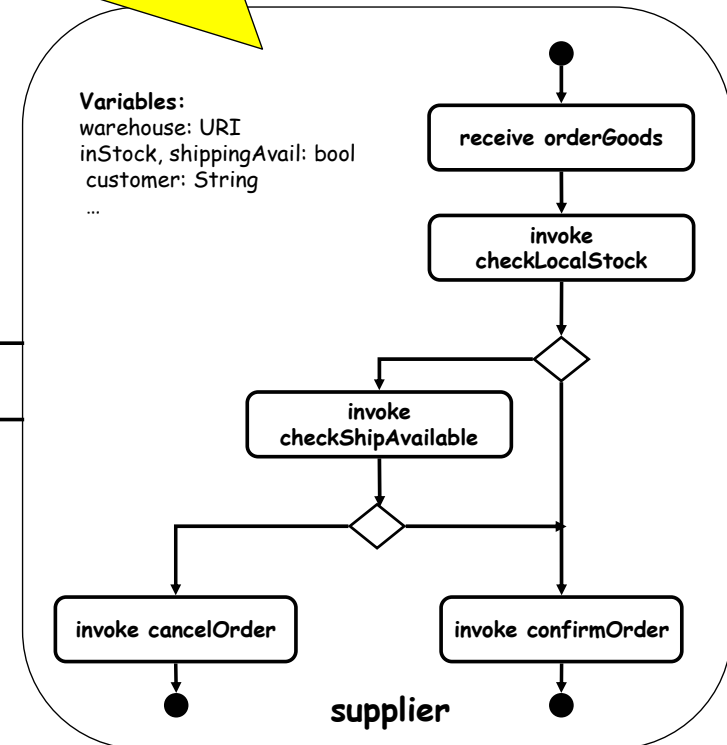
- Roles exchanging messages with the composite service/process
- The (WSDL) interfaces supported by such roles

• The orchestration of the process

- Variables and data transfer
- Exception handling
- Correlation information



Orchestration
- variables and data transfers,
- exception handling,
- correlation information (for instance routing)



Process Model (Activities)

- Primitive
 - **invoke**: to invoke a Web Service (in-out) operation
 - **receive**: to wait for a message from an external source
 - **reply**: to reply to an external source message
 - **wait**: to remain idle for a given time period
 - **assign**: to copy data from one variable to another
 - **throw**: to raise exception errors
 - **empty**: to do nothing
- Structured
 - **sequence**: sequential order
 - **switch**: conditional routing
 - **while**: loop iteration
 - **pick**: choices based on events
 - **flow**: concurrent execution (synchronized by **links**)
 - **scope**: to group activities to be treated "transactionally" (managed by the same fault handler, within the same transactional context)

A link connects exactly one source activity S to exactly one target activity T; T starts only after S ends. An activity can have multiple incoming (possibly with join conditions) and outgoing links. Links can be guarded

Process Model

(Data Manipulation and Exception Handling)

- Blackboard approach
 - a blackboard of variables is associated to each orchestration instance (i.e., a shared memory within an orchestration instance)
 - variables are not initialized at the beginning; they are modified (read/write) by assignments and messages
 - manipulation through XPath
- Try-catch-throw approach
 - definition of fault handlers
 - ... but also event handlers and compensation handlers (for managing transactionality as in the SAGA model)

Choreography

(As Reported in Literature: Classical Ballet Style)

- Consider a dance with more than one dancer
 - Each dancer has a set of steps that they will perform. They orchestrate their own steps because they are in complete control of their domain (their body)
 - A choreographer ensures that the steps all of the dancers make is according to some overall, pre-defined scheme. This is a choreography
 - The dancers have no control over the steps they make: their steps must conform to the choreography
 - The dancers have a single view-point of the dance
 - The choreographer has a multi-party or global view-point of the dance

Choreography

(A Possible Evolution: Jam Session Style)

- Consider a jazz band with many players
 - There is a rhythm and a main theme. This is the choreography
 - Each player executes his piece by improvising variations over the main theme and following the given rhythm
 - The players still have a single view-point of the music; in addition they have full control over the music they play
 - There is a multi-party or global view-point of the music, but this is only a set of "sketchy" guidelines

WS-BPEL vs. WS-CDL

- Orchestration/WS-BPEL is about describing and executing a single peer
- Choreography/WS-CDL is about describing and guiding a global model (N peers)
- You should derive the single peer from the global model by projecting based on participant

WS-CDL Basics (1)

- **Participants & Roles**

- **Role type**

- Enumerate the observable behavior that a collaborating participant exhibits
- Behavior type specifies the operations supported
 - Optional WSDL interface type

- **Relationship type**

- Specify the mutual commitments, in terms of the Roles/Behavior types, **two** collaborating participants are required to provide
- Note: all multi-party relationships are transformed into binary ones

- **Participant type**

- Enumerate a set of one or more Roles that a collaborating participant plays

WS-CDL Basics (2)

- Channels
 - A channel realizes a *dynamic* point of collaboration, through which collaborating participants interact
 - Where & how to communicate a message
 - Specify the *Role/Behavior* and the *Reference* of a collaborating participant
 - Identify an *Instance* of a Role
 - Identify an instance of a conversation between two or more collaborating participants
 - A conversation groups a set of related message exchanges
- One or more channel(s) *MAY* be passed around from a Role to one or more other Role(s), possibly in a daisy fashion through one or more intermediate Role(s), creating new points of collaboration dynamically
 - A Channel type *MAY* restrict the types of Channel(s) allowed to be exchanged between the Web Services participants, through this Channel
 - A Channel type *MAY* restrict its usage, by specifying the number of times a Channel can be used

WS-CDL Basics (3)

- **Activities** are the building blocks of a choreography
 - Basic Activity
 - **Interaction**: message exchange between participants
 - Only in-out and in-only
 - **Assign**: within one role, assign the value of a variable to another one
 - Variables can be about information (exchanged documents), states and channels
 - **No action**: do null
 - Ordering structure
 - **Sequence** (P.Q)
 - **Parallel** (P | Q)
 - **Choice** (P + Q)
 - **Perform**: a complete, separately defined choreography is performed
 - Basis for scalable modeling

Attention: a choreography performing another one is referred to as "choreography composition" in the standard

WS-CDL Basics (4)

- A Choreography combines all previous elements, forming a collaboration unit of work
 - Enumerate all the binary relationships interactions act in
 - Localize the visibility of variables
 - Using variable definitions
 - Prescribe alternative patterns of behavior
 - Using work/units and reactions
 - Enable Recovery
 - Using work/units and reactions
 - Backward: handle exceptional conditions
 - Forward: finalize already completed activities

OWL-S (formely DAML-S)

- An emerging standard to add semantics
 - An upper ontology for **describing properties & capabilities** of Web Services using OWL
- **Enable** automation of various activities (e.g., service discovery & selection)



OWL-S Service Profile

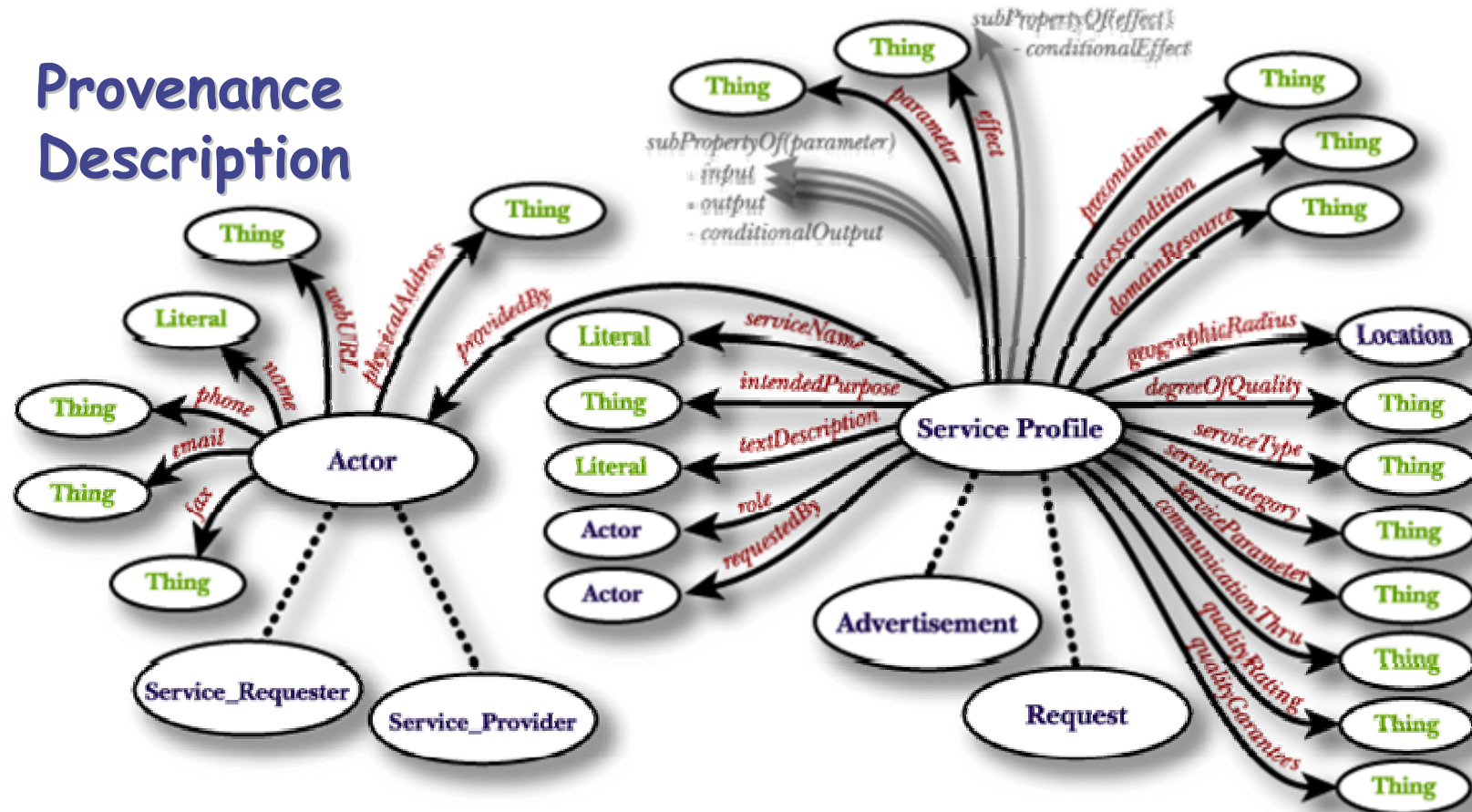
(What it does)

- High-level characterization/summary of a service
 - Provider & participants
 - Capabilities
 - Functional attributes (e.g., QoS, region served)
- Used for
 - Populating service registries
 - A service can have many profiles
 - Automated service discovery
 - Service selection (matchmaking)
- One can derive:
 - Service advertisements
 - Service requests

OWL-S Service Profile

Capability Description

Provenance Description



Functional Attributes

[from DAML-S]

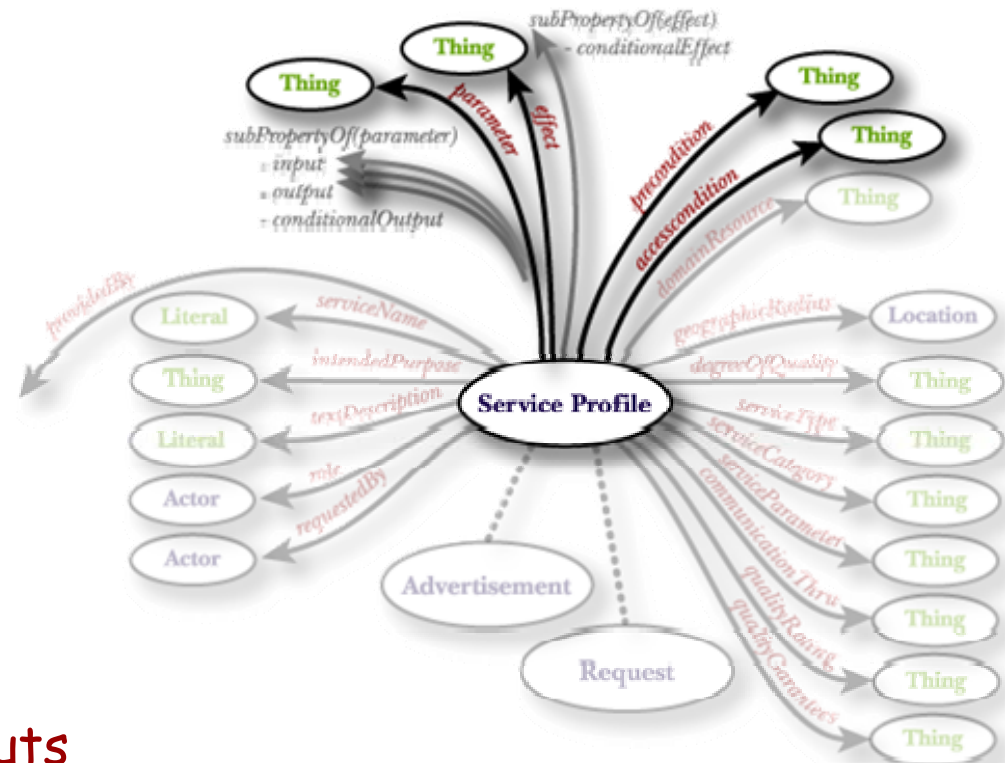
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Capability Description

- Specification of what the service provides
 - High-level functional representation in terms of:
 - preconditions
 - inputs
 - (conditional) outputs
 - (conditional) effects

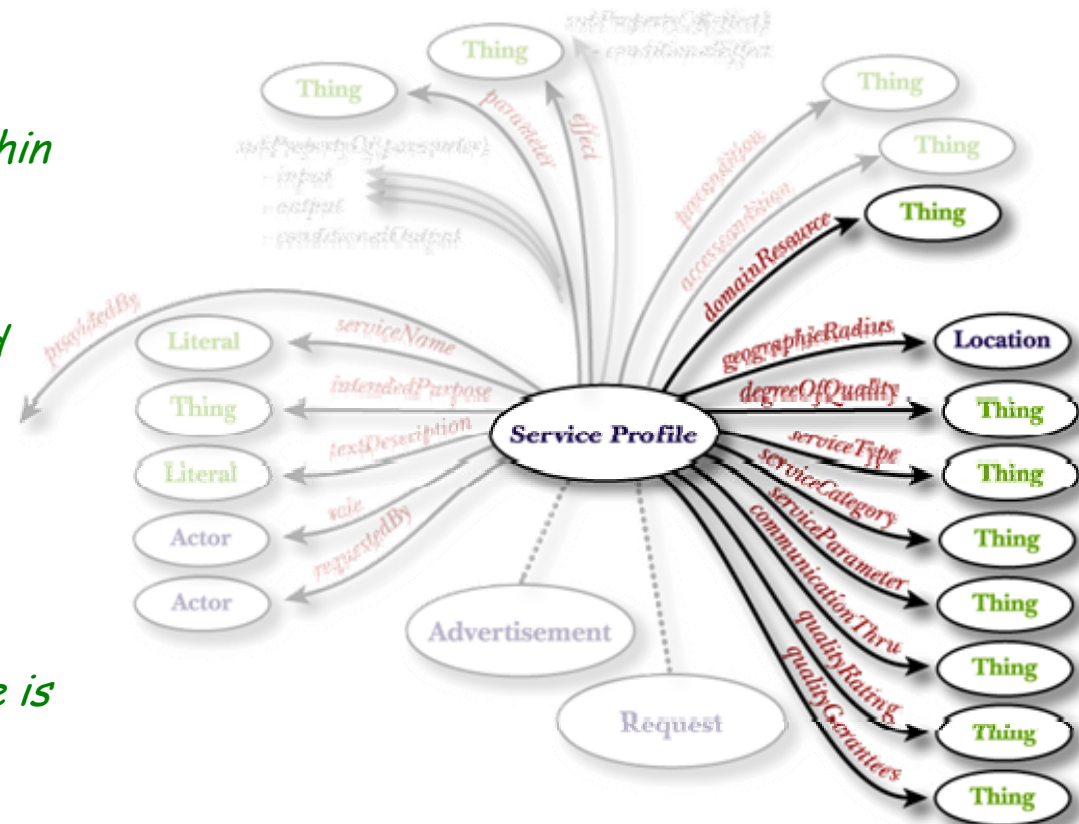


- **Inputs**
 - Set of necessary inputs that the requester should provide to invoke the service
- **(Conditional) Outputs**
 - Results that the requester should expect after interaction with the service provider is completed
- **Preconditions**
 - Set of conditions that should hold prior to service invocation
- **(Conditional) Effects**
 - Set of statements that should hold true if the service is invoked successfully
 - Often refer to real-world effects, e.g., a package being delivered, or a credit card being debited

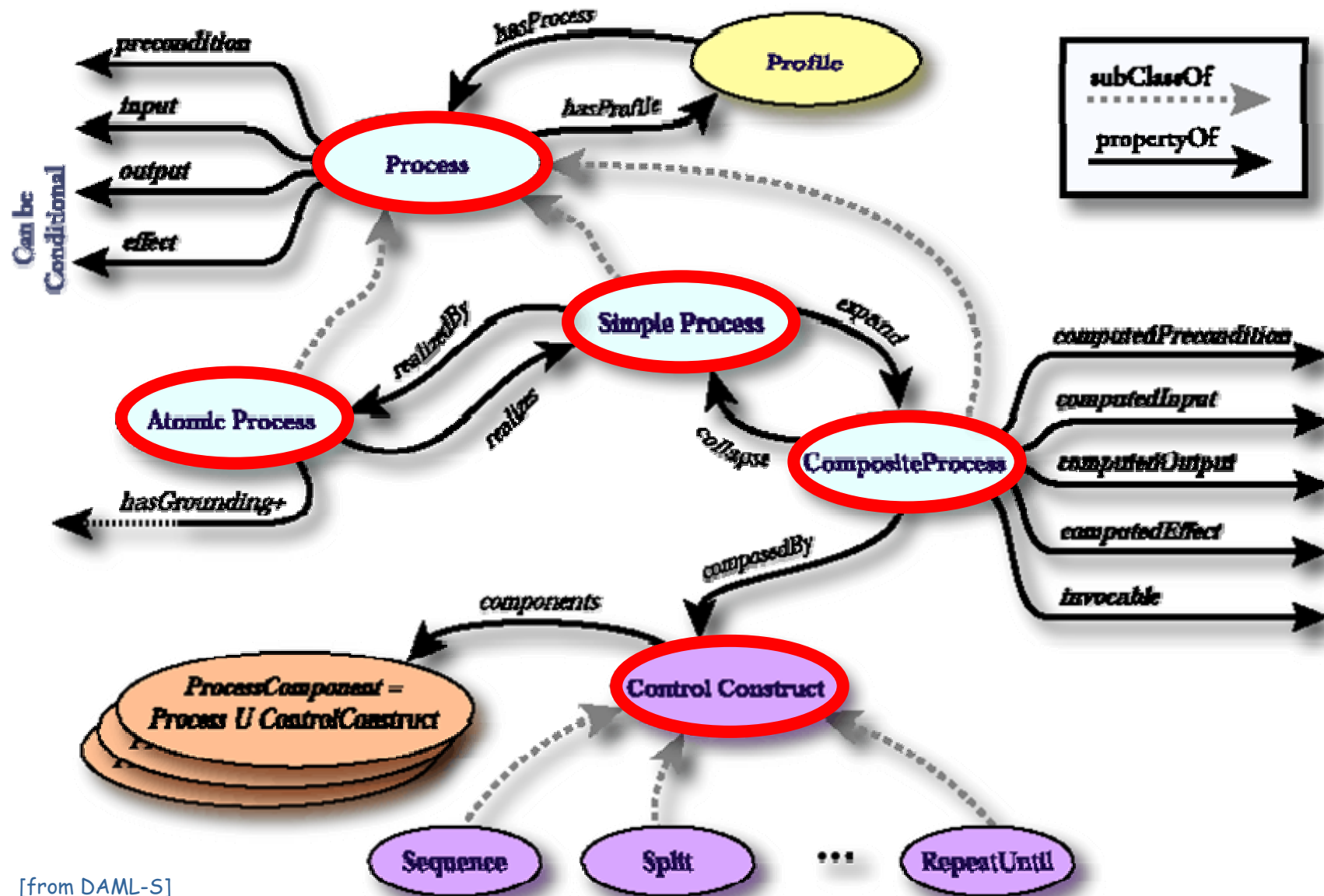
Functional Attributes

Provide supporting information about the service, including:

- geographical scope
Pizza Delivery only within the Pittsburgh area
- quality descriptions and guarantees
Stock quotes delivered within 10 secs
- service types, service categories
Commercial / Problem Solving, etc.
- service parameters
Average Response time is currently ...



OWL-S Service Model (How it works)



OWL-S Process Ontology

- **Atomic processes:** directly invocable, no subprocesses, executed in a single step
- **Composite processes:** consist of other (non-composite or composite) processes
- **Simple processes:** a virtual view of atomic process or composite process (as a "black box")

Process Model

- Constructs for complex processes
 - Sequence
 - Concurrency: Split; Split+Join; Unordered
 - Choice
 - If-Then-Else
 - Looping: Repeat-Until; Iterate (non-deterministic)
- Data Flow
 - No explicit variables, no internal data store
 - Predicate "sameValues" to match input of composite service and input of subordinate service
- Less refined than, e.g., WS-BPEL

Enhancements

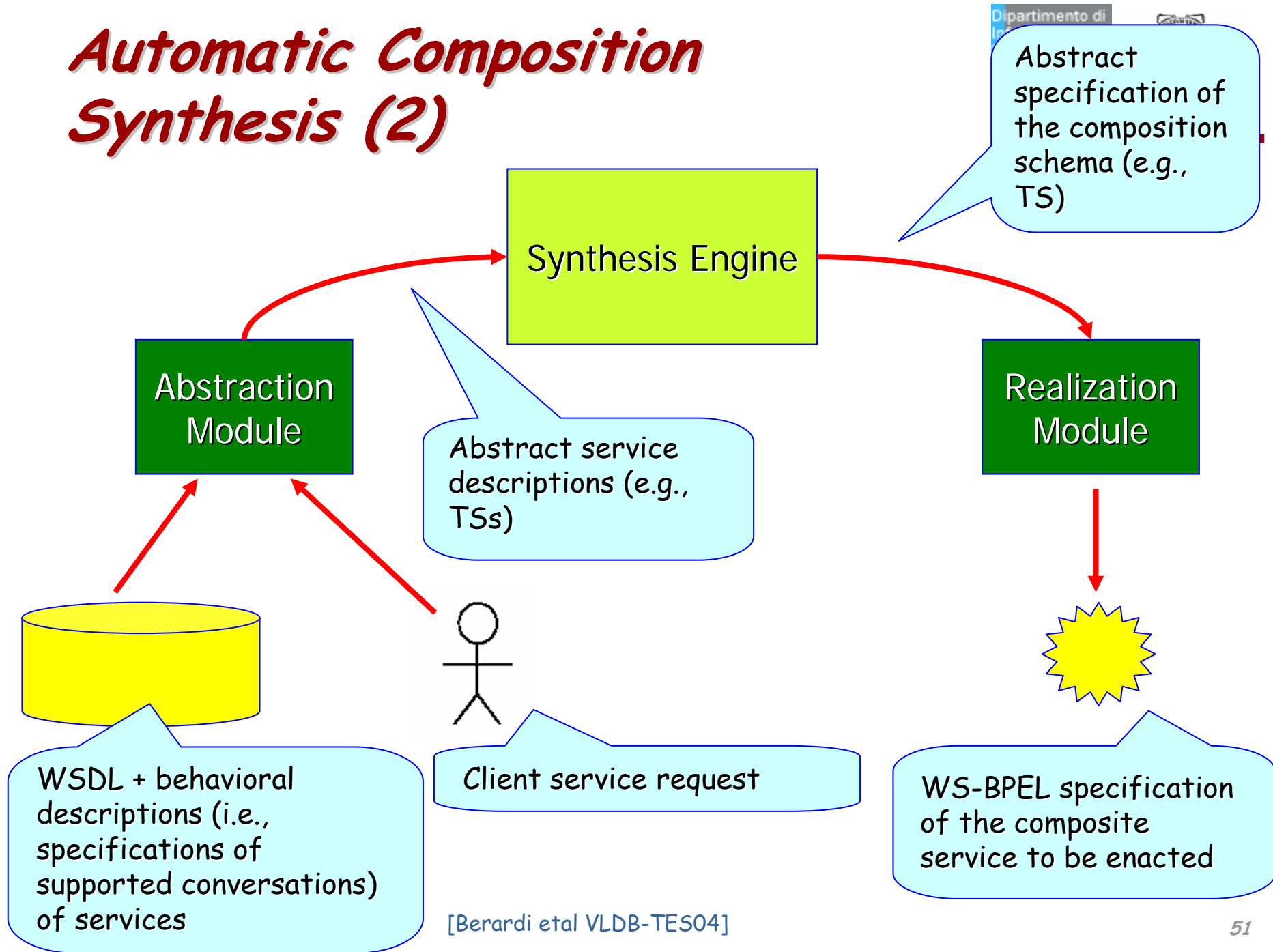
- Recent proposals aim at improving and detailing process modeling and dynamic semantics ...
 - WSMO (Web Service Modeling Ontology)
 - SWSL (Semantic Web Service Language)
- ... work in progress !!

Introducing Automatic Composition

Automatic Composition Synthesis (1)

- Given:
 - a set (S_1, \dots, S_n) of component services
 - a client service request T
- Automatically build:
 - a composition schema CS that fulfills T by suitably orchestrating (S_1, \dots, S_n)

Automatic Composition Synthesis (2)

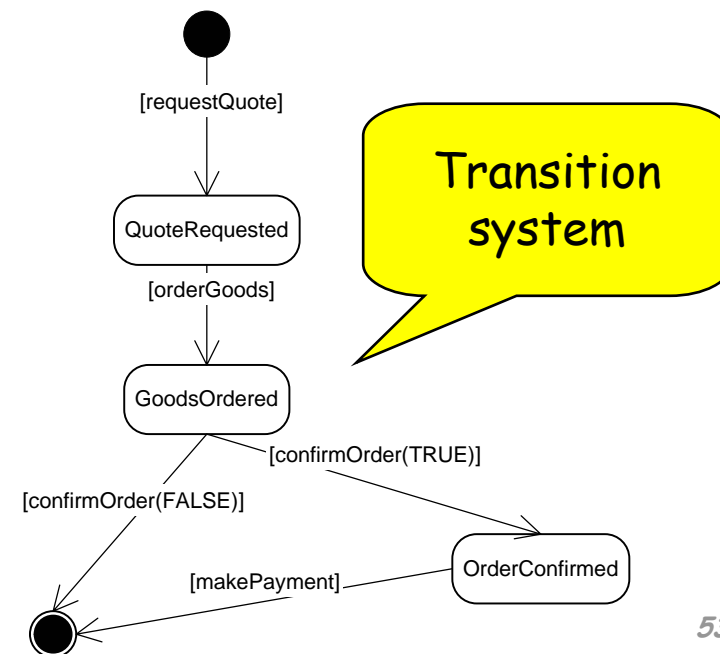
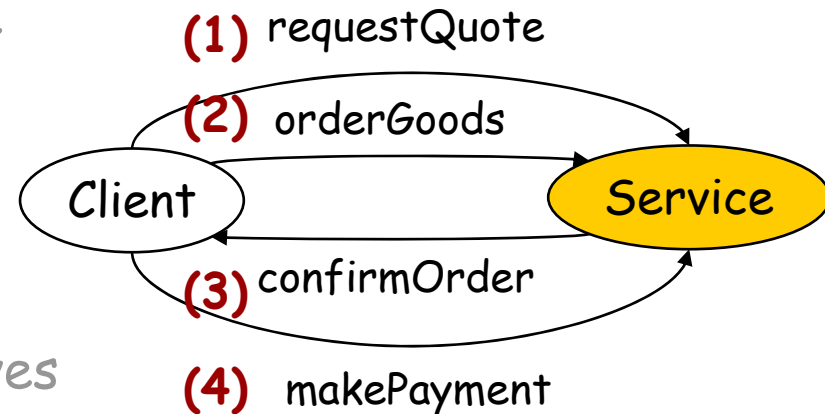


Abstracting over Technologies

Modeling Services as
Transition Systems

Services

- A service is characterized by the set of (atomic) operations that it exports ...
- ... and possibly by constraints on the possible **conversations**
 - Using a service typically involves performing sequences of operations in a particular order (conversations)
 - During a conversation, the client typically chooses the next operation to invoke (on the basis of previous results, etc.) among the ones that the service allows at that point



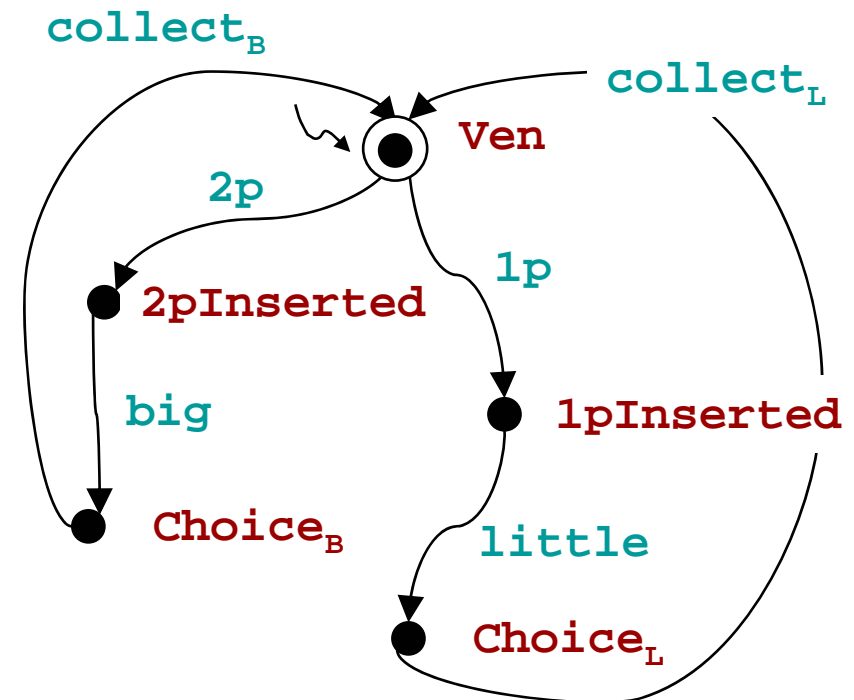
Transition Systems

- A transition system (TS) is a tuple

$$T = \langle A, S, S^0, \delta, F \rangle$$

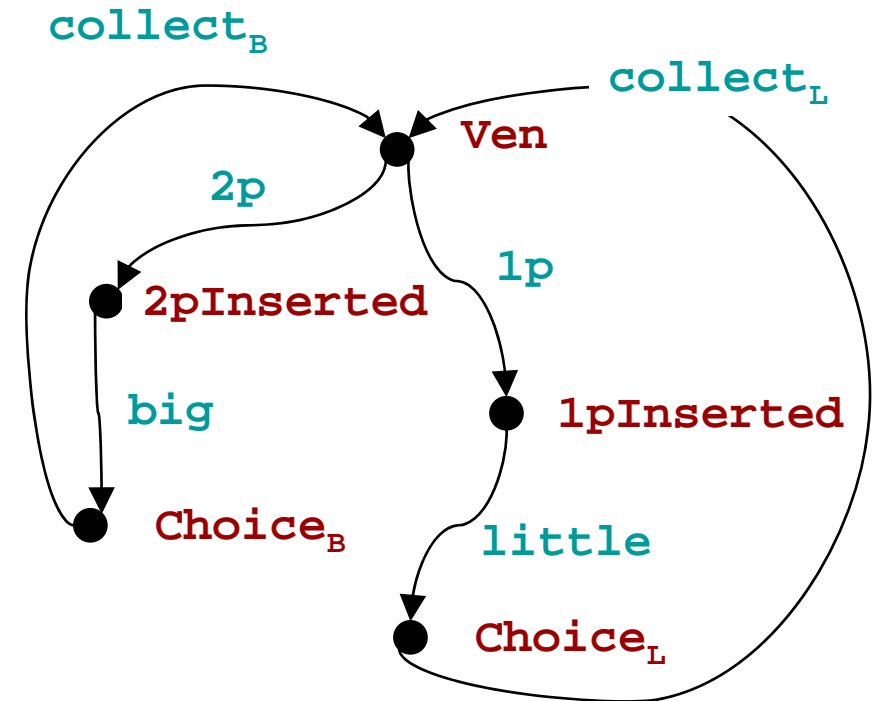
where:

- A is the set of actions
- S is the set of states
- $S^0 \subseteq S$ is the set of initial states
- $\delta \subseteq S \times A \times S$ is the transition relation
- $F \subseteq S$ is the set of final states



Process Algebras and TSs

- Process theory:
 - a process is a term of an algebraic language
 - a transition $E \rightarrow_a F$ means that process E may become F by performing (participating in, or accepting) action a
 - structured rules guide the derivation



- A graph:
 - nodes are process terms
 - labelled directed arcs between nodes

$$\text{Ven} = 2p.2p\text{Inserted} + 1p.1p\text{Inserted}$$

$$2p\text{Inserted} = \text{big}.Choice_B$$

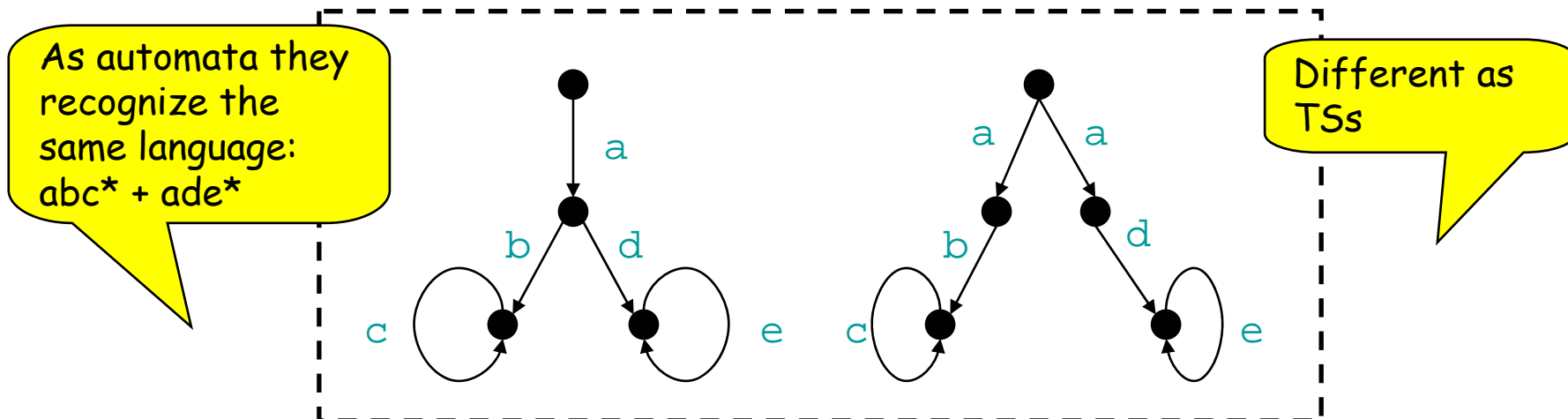
$$1p\text{Inserted} = \text{little}.Choice_L$$

$$Choice_B = \text{collect}_B.\text{Ven}$$

$$Choice_L = \text{collect}_L.\text{Ven}$$

Automata vs. Transition Systems

- Automata
 - define sets of runs (or traces or strings): (finite) length sequences of actions
- TSs
 - ... but I can be interested also in the alternatives "encountered" during runs, as they represent client's "choice points"



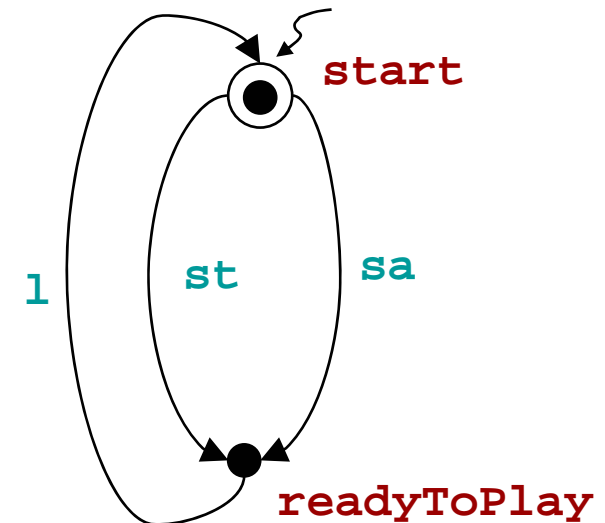
WS-DL is the Set of Actions

- A message exchange pattern (and the related operation) represents an **interaction** with the service client
 - an action that the service can perform by interacting with its client
- Abstracting from formal parameters, we can associate a different symbol to each operation ...
- ... thus obtaining the alphabet of actions

An Example

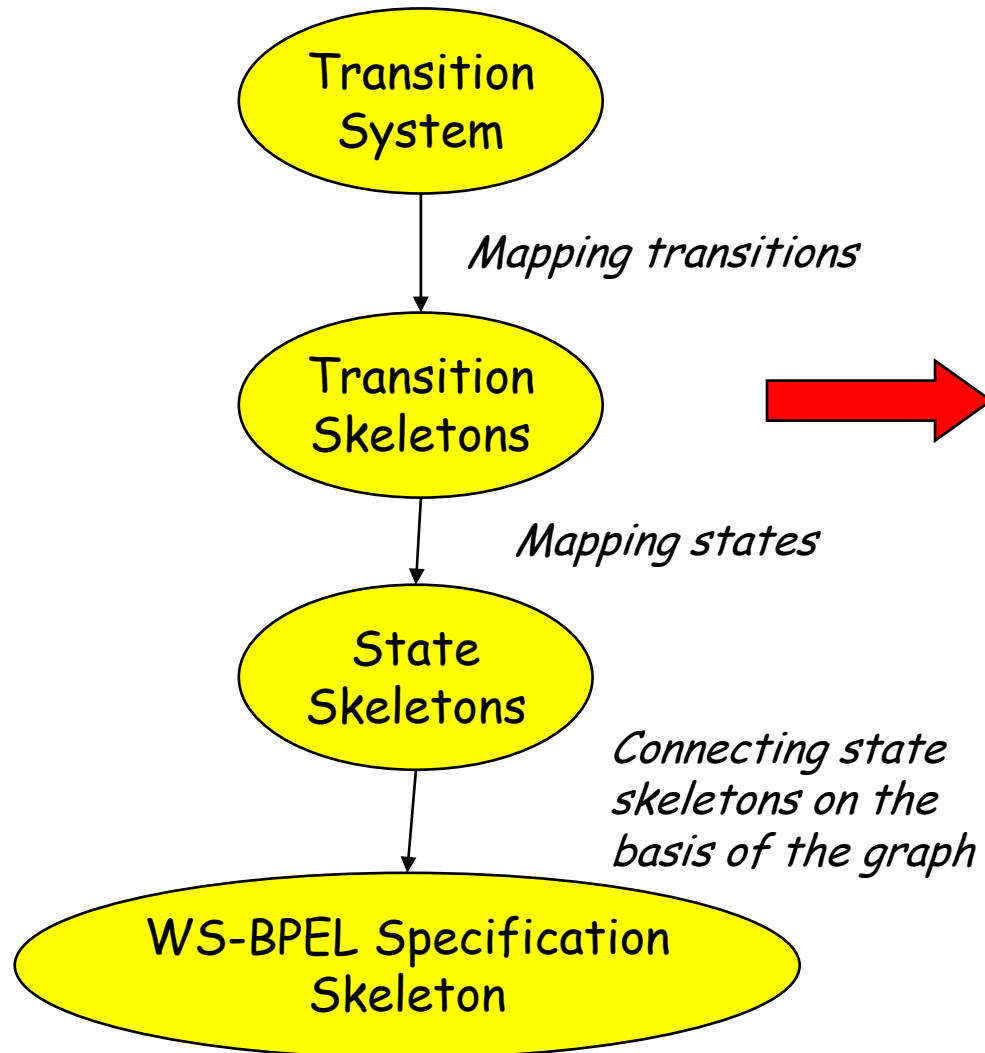
- The MP3ServiceInterface defines 3 actions:

- search_by_title / st
- search_by_author / sa
- listen / l



- Formally $A = \{st, sa, l\}$

From a TS to WS-BPEL (1)



```
<process name = "...">
  <partnerLinks>
    ...
  </partnerLinks>
  <variables>
    ...
  </variables>
  <flow>
    <links>
      ...
    </links>
    <!-- state skel. -->
    ...
    <!-- state skel. -->
  </flow>
</process>
```

From a TS to WS-BPEL (2)

Intuition [Baina etal CAISE04, Berardi etal VLDB-TE04]

1. Each transition corresponds to a WS-BPEL pattern consisting of (i) an `<onMessage>` operation (in order to wait for the input from the client of the composite service), (ii) followed by the effective logic of the transition, and then (iii) a final operation for returning the result to the client. Of course both before the effective logic and before returning the result, messages should be copied forth and back in appropriate variables
2. All the transitions originating from the same state are collected in a `<pick>` operation, having as many `<onMessage>` clauses as transitions originating from the state
3. The WS-BPEL file is built visiting the graph in depth, starting from the initial state and applying the previous rules.

N.B.: (1) and (2) works for in-out interactions (the ones shown in the following). Simple modifications are needed for in-only, robust-in-only and in-optional-out. The other kinds of interactions implies a proactive behaviour of the composite service, possibly guarded by `<onAlarm>` blocks.
(3) works for acyclic TS. See later for cycle management.

Transition Skeletons

```
<onMessage ... >  
  <sequence>  
    <assign>  
      <copy>  
        <from variable="input" ... />  
        <to variable="transitionData" ... />  
      </copy>  
    </assign>  
    <!-- logic of the transition -->  
    <assign>  
      <copy>  
        <from variable="transitionData" ... />  
        <to variable="output" ... />  
      </copy>  
    </assign>  
    <reply ... />  
  </sequence>  
</onMessage >
```

State Skeletons

- N transitions from state S_i are mapped onto:

```
<pick name = "Si">  
  <!-- transition #1 -->  
  <onMessage ... >  
    <!-- transition skeleton -->  
  </onMessage>  
  ... ..  
  <!-- transition #N -->  
  <onMessage ... >  
    <!-- transition skeleton -->  
  </onMessage>  
</pick>
```

Mapping the TS

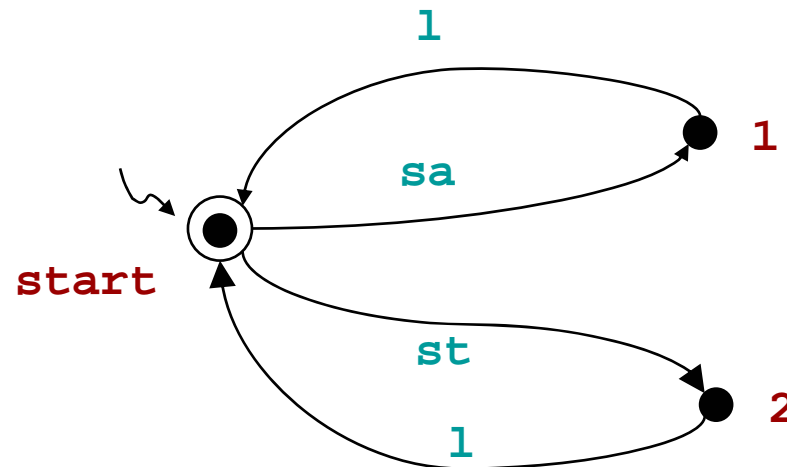
- All the `<pick>` blocks are enclosed in a surrounding `<flow>`; the dependencies are modeled as `<link>`s
 - `<link>`s are controlled by specific variables s_i -to- s_j that are set to TRUE iff the transition $S_i \rightarrow S_j$ is executed
 - Each state skeleton has many outgoing `<link>`s as states connected in output, each going to the appropriate `<pick>` block

Mapping Cyclic TSs

(Intuition)

- Identify all the cycles
- Enclose the involved state skeletons inside a `<while>` block controlled by a condition (`!exit`) (`exit` is a variable defined ad hoc)
 - `exit` is set to TRUE by any transition that "goes out" of the cycle
 - The overall `<while>` block is connected to other state skeletons by appropriate `<link>`s
- Special cases:
 - A state S with self-transitions can be represented as a `<pick>` block enclosed in a `<while>` block controlled by a condition (v_s) (the variable v_s is set to FALSE by other non self-transitions)
 - Cycles starting from the initial state should not be considered, as they can be represented as the start of a new instance

An Example (1)



<partnerLinks>

<!-- The "client" role represents the requester of this composite service -->

<partnerLink name="client"

partnerLinkType="tns:Transition"

myRole="MP3ServiceTypeProvider"

partnerRole="MP3ServiceTypeRequester"/>

<partnerLink name="service"

partnerLinkType="nws:MP3CompositeService"

myRole="MP3ServiceTypeRequester"

partnerRole="MP3ServiceTypeProvider"/>

</partnerLinks>

An Example (2)

```
<variables>
  <variable name="input" messageType="tns:listen_request"/>
  <variable name="output" messageType="tns:listen_response"/>
  <variable name="dataIn" messageType="nws:listen_request"/>
  <variable name="dataOut" messageType="nws:listen_response"/>
</variables>

  <pick>
    <onMessage partnerLink="client"
      portType="tns:MP3ServiceType"
      operation="listen"
      variable="input">
      <sequence>
        <assign>
          <copy>
            <from variable="input" part="selectedSong"/>
            <to variable="dataIn" part="selectedSong"/>
          </copy>
        </assign>
        ... ..
        <assign>
          <copy>
            <from variable="dataOut" part="MP3FileURL"/>
            <to variable="output" part="MP3FileURL"/>
          </copy>
        </assign>
        <reply name="replyOutput"
          partnerLink="client"
          portType="tns:MP3ServiceType"
          operation="listen"
          variable="output"/>
      </sequence>
    </onMessage>
    ... ..
  </pick>
```

An Example (3)



```
<process suppressJoinFailure = "no">
  <flow>
  <links>
    <link name="start-to-1"/>
    <link name="start-to-2"/>
  </links>

  <pick createInstance = "yes">
    <onMessage="sa">
      <sequence>
        <copy>...</copy>
        ...
        <copy>...</copy>
        <reply ... />
      </sequence>
    </onMessage>
    <onMessage="st">
      <sequence>
        <copy>...</copy>
        ...
        <copy>...</copy>
        <reply ... />
      </sequence>
    </onMessage>
    <source linkName="start-to-1" transitionCondition = "bpws:getVariableData('start-to-1') = 'TRUE' " />
    <source linkName="start-to-2" transitionCondition = "bpws:getVariableData('start-to-2') = 'TRUE' " />
  </pick>
</process>
```

A new instance is created in the initial state. This resolve also the presence of the cycles without the need of enclosing <while>

The <sa> transition skeleton should set variables:

```
start-to-1 = TRUE
start-to-2 = FALSE
```

The <st> transition skeleton should set variables:

```
start-to-1 = FALSE
start-to-2 = TRUE
```

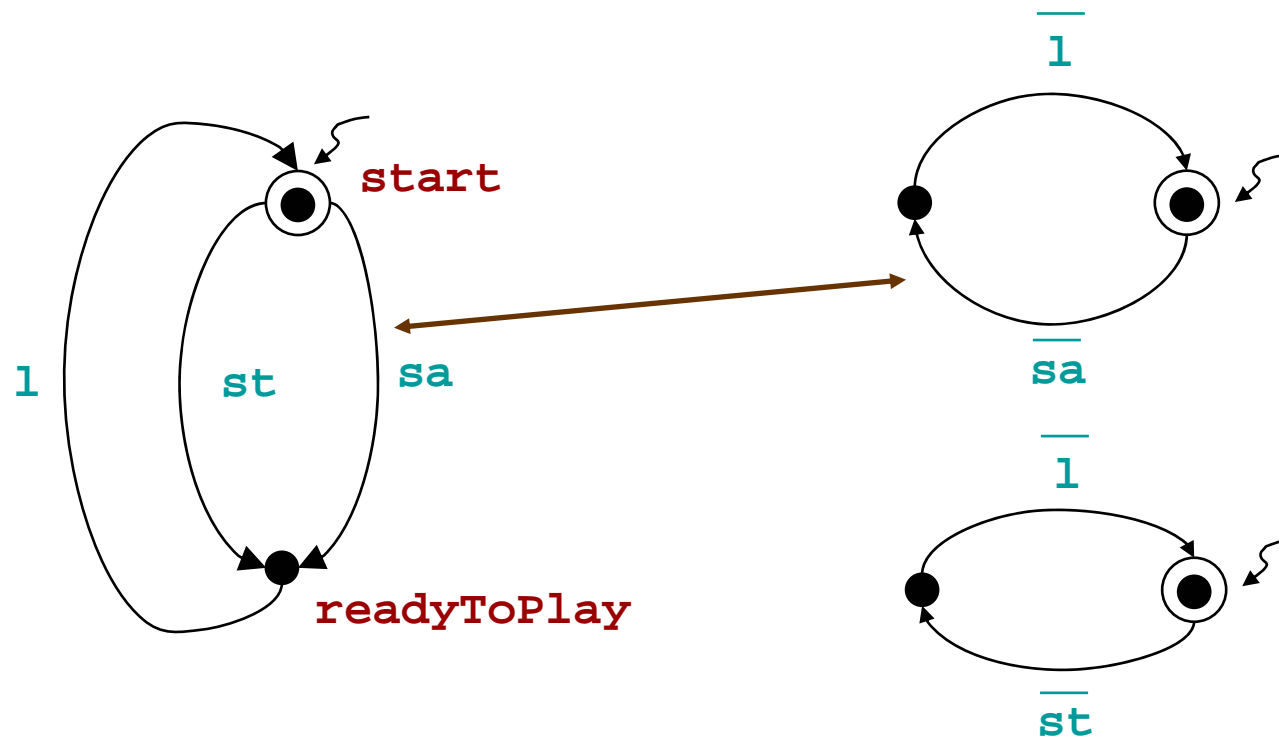
An Example (4)

```
<pick>
  <onMessage="">
    <sequence>
      <copy>...</copy>
      ...
      <copy>...</copy>
      <reply ... />
    </sequence>
  </onMessage>
  <target linkName="start-to-1" />
</pick>
<pick>
  <onMessage="">
    <sequence>
      <copy>...</copy>
      ...
      <copy>...</copy>
      <reply ... />
    </sequence>
  </onMessage>
  <target linkName="start-to-2" />
</pick>
</process>
```

TSs and Choreography

(only an intuition :-)

- A Choreography can be seen as the specification of a set of concurrent peers, each one exposing a TS, that fulfills the global model



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[WS-CAF] - Web Services Composite Application Framework, <http://developers.sun.com/techttopics/webservices/wscaf/>

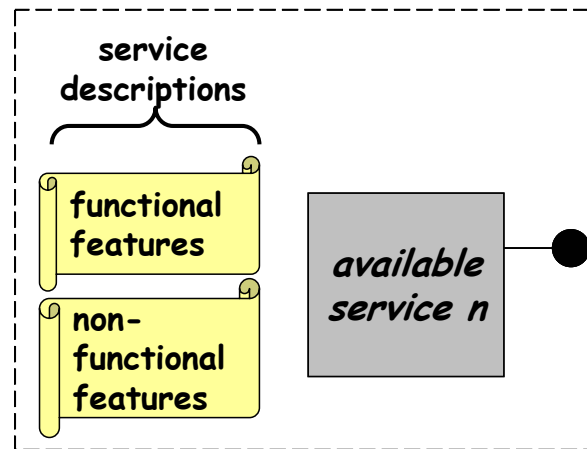
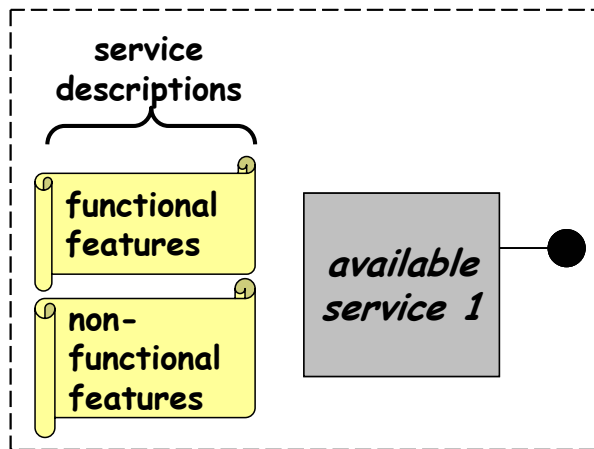
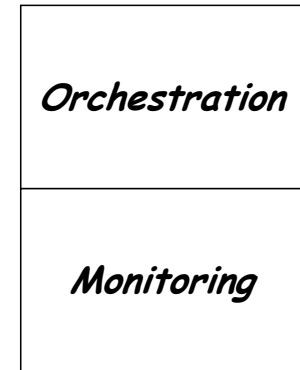
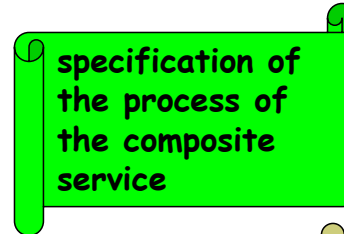
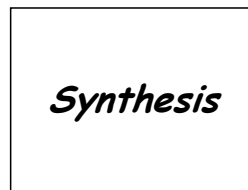
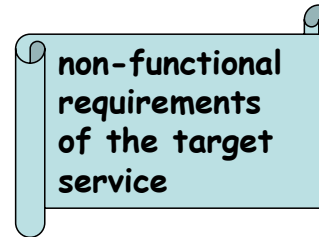
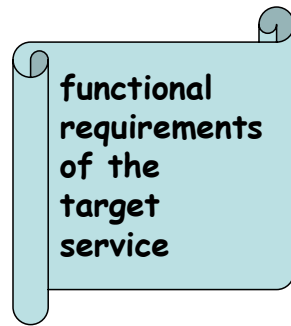
State of the Art on Service Composition

Service Composition System

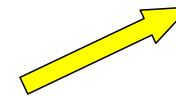
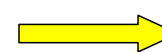
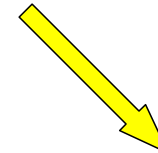
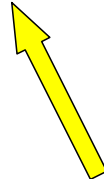
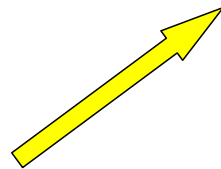


client

target service invocation



available service invocation



Service composition

1. Composition Synthesis:

Input:

- client request
- set of available services

Output:

- specification of composite service

2. Orchestration:

Input:

- specification of composite service

Output:

- coordination of available services according to the composition schema
- data flow and control flow monitoring

How to model client request ?

How to model available services ?

How to model the composite service ?

How to orchestrate the composite service ?

Service description

- Services export a **view of their behavior**

- I/O interface

- Data Access

- focus on data
- for information gathering

- Atomic Actions

- focus on actions
- world altering services

information
oriented services

services as
atomic actions

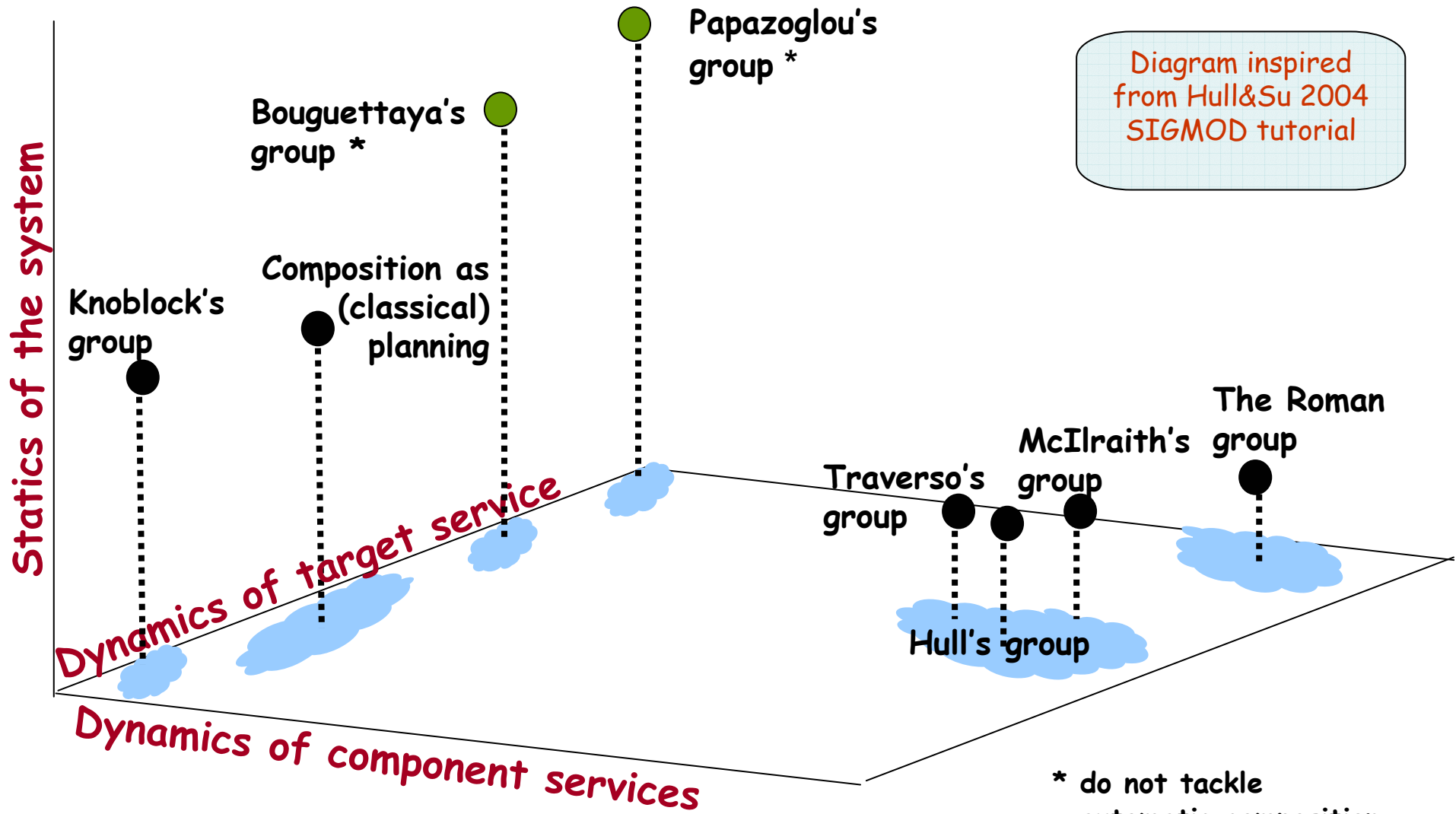
services as
processes

- Complex Behavioral Description

(typically represented using finite states, e.g., TSs)

The whole picture

Diagram inspired
from Hull&Su 2004
SIGMOD tutorial



Key dimensions in service composition (1)

1. **Statics of the composition system (i.e., static semantics):**
 - e.g, ontologies of services (for sharing semantics of data/information), inputs and outputs, etc.
2. **Dynamics of component services (i.e., dynamic semantics, process):**
 - e.g., behavioral features, complex forms of dataflow, transactional attitudes, adaptability to varying circumstances

Key dimensions in service composition (2)

3. Dynamics of the target service (i.e., dynamic semantics, process)

The target service exposed as:

atomic
action



process

- single step
- (set of) sequential steps
- (set of) conditional steps
- while/loops, running batch
- while/loops, running under an external control

Key dimensions in service composition: the 4th dimension

4. Degree of (in)completeness in the specification of:

- Static Aspects (of the composition system)
- Dynamic Aspects (of component services)
- Target service specification

For simplicity
not shown in
the following
slides

- Note: Orthogonal to previous dimensions

What is addressed from the technical point of view?

- Automatic composition techniques?
 - Which formal tools?
 - Sound and complete techniques?
 - Techniques/Problem investigated from computational point of view?

Analyzed works

- Papazoglou's group
 - Bouguettaya's group
 - Knoblock's group (information oriented services)
 - Composition as Planning (services as atomic actions)
 - Traverso's group
 - McIlraith's group
 - Hull's group
 - The Roman group
- (not automatic composition)
- (services as processes)

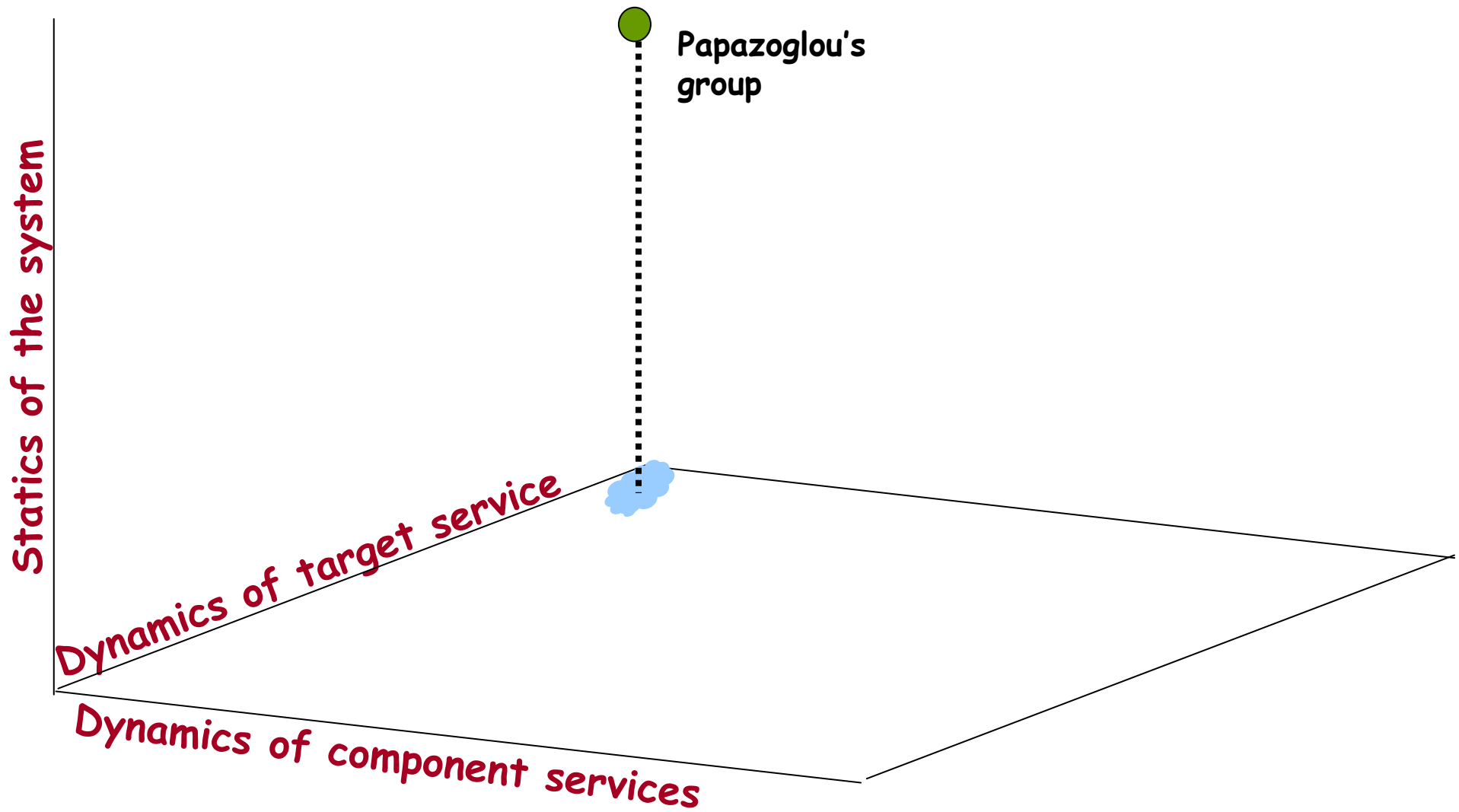
as called by Rick Hull
in his SIGMOD 2004
tutorial

Papazoglou's group

J. Yang and M.P. Papazoglou: Service Components for Managing the Life-cycle of Service Compositions, Information Systems 29 (2004), no. 2, 97 - 125

- available services: **I/O interfaces**
 - service component: simple or complex pre-existing service wrapped into a web component
 - they are stored in a service component class library
 - operations offered through a uniform interface
- composite service: **complex behavioral description**
 - set of service components (from service component class library) "glued" together by composition logics
 - composition logics defines execution order (either sequential or concurrent) of service components within composition, dependencies among input and output parameters, etc.
 - support for **manual** composition: designer specifies composite service using the Service Scheduling Language and the Service Composition Execution Language

Papazoglou's group



Bouguettaya's group

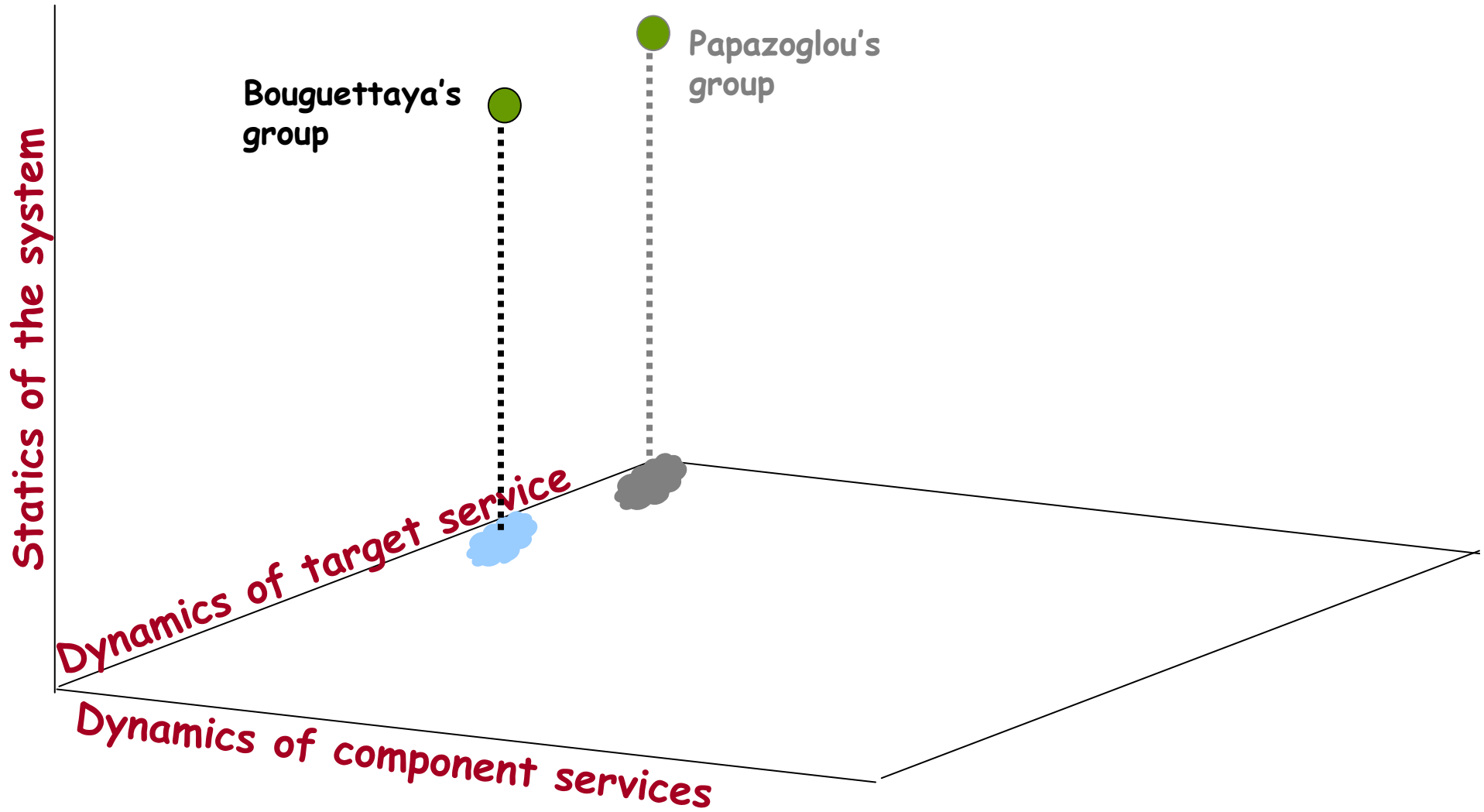
B. Medjahed, A. Bouguettaya, and A. K. Elmagarmid: Composing Web services on the Semantic Web, Very Large Data Base Journal 12 (2003), no. 4, 333-351

- available services: **atomic actions**
 - semantically described in terms of their I/O interfaces and non-functional properties such as their purpose, their category and their quality
 - Available services stored into an ontology on the basis of their non-functional properties

Bouguettaya's group

- client request:
 - expressed in the Composite Service Specification Language (CSSL): it specifies the sequence of desired operations that the composite service should perform and control flow between operations
- **service composition problem:**
 - **Input:** (i) I/O descr. of available services
(ii) client request expr. in CSSL
 - **Output:** composite service as **sequence of operations** (**semi-automatically**) obtained from the client specification by identifying, for each operation, the operation(s) of available services that matches it, on the basis of their I/O interface and non-functional features

Bouguettaya's group



Knoblock's group

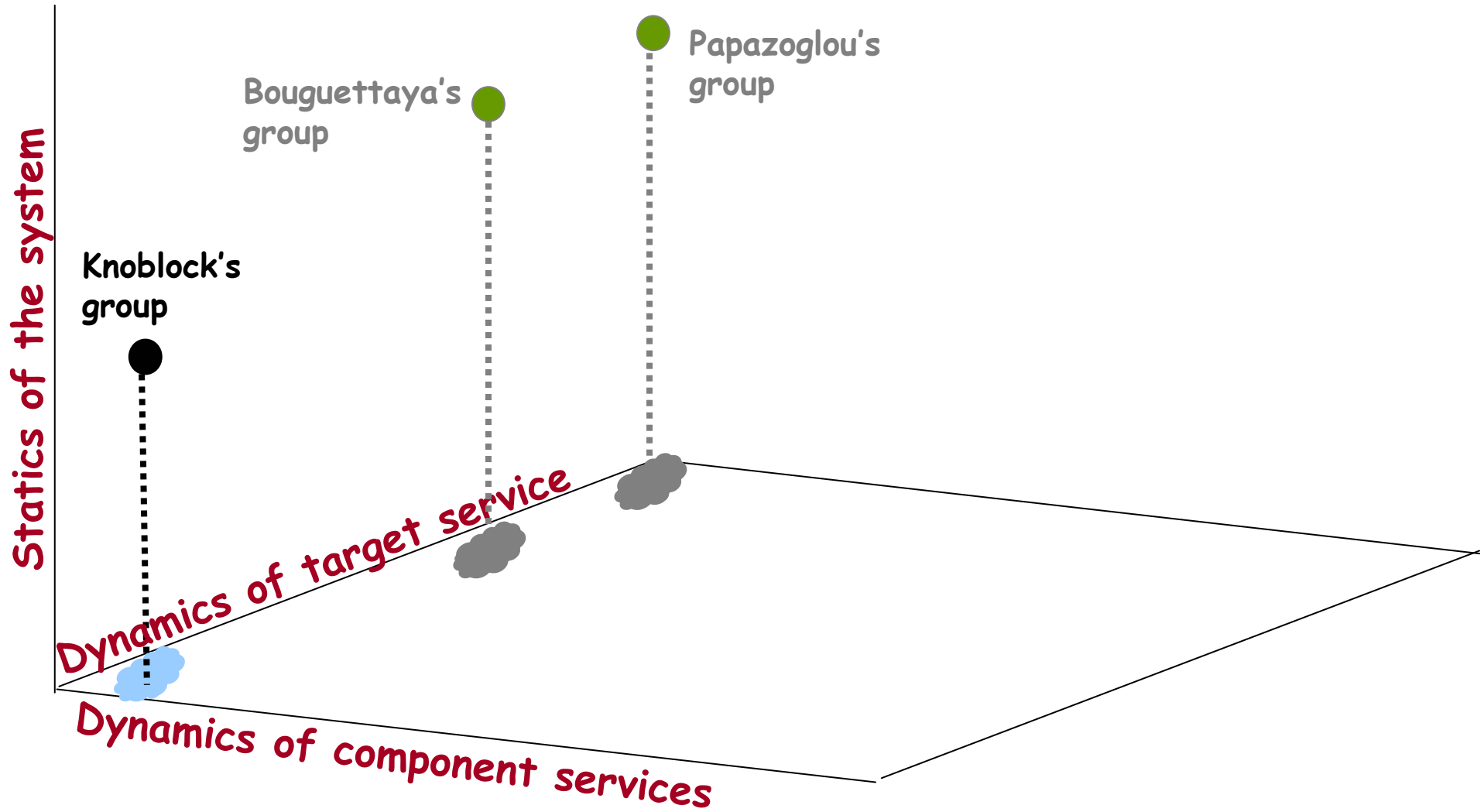
M. Michalowski, J.L. Ambite, S. Thakkar, R. Tuchinda, C.A. Knoblock, and S. Minton: Retrieving and semantically integrating heterogeneous data from the web. IEEE Intelligent Systems, 19 (2004), no. 3, pp.72 - 79

- available service: data query
 - basic idea: informative services as views over data sources
 - each service described in terms of I/O parameters (of course, the latter being provided by the data source), binding patterns and additional constraints on the source
- client request:
 - data query, expressed in terms of inputs provided by the client and requested outputs

Knoblock's group

- **service composition problem:**
 - **Input**: (i) available services modeled as data-sources, and (ii) client request as user query
 - **Output**: (automatically obtained) composite service as integration plan for a *generalized* user query, so that all the user queries that differ only for intensional input values can be answered by the same (composite) service. Integration plan as a sequence of source queries, taking binding pattern into account

Knoblock's group



Composition as Planning

- available services: atomic actions
- client request: client (propositional) goal
- **service composition problem**: planning problem
 - Input:
 - (i) client goal (also encodes initial condition)
 - (ii) available services as atomic actions
 - Output: composite service as a (possibly conditional) plan, i.e., sequence of actions that transform the initial state into a state satisfying the goal.
 - *Sirin, Parsia, Wu, Hendler & Nau [Sirin etal ICWS03]*
 - *ICAPS 2003 Planning for Web Services workshop [P4WS03]*
 - *ICAPS 2004 Planning for Web and Grid Services workshop [P4WGS04]*
- **NOTE**: the client has not influence over the control flow of the composite service

Example (1)

- Component Services
 - $S_1: \text{True} \rightarrow \{S_1:\text{bookFlight}\} \text{FlightBooked} \wedge \text{MayBookLimo}$
 $\text{MayBookLimo} \rightarrow \{S_1:\text{bookLimo}\} \text{LimoBooked}$
 - $S_2: \text{True} \rightarrow \{S_2:\text{bookHotel}\} \text{HotelBooked}$
 $\text{HotelBooked} \rightarrow \{S_2:\text{bookShuttle}\} \text{ShuttleBooked}$
 - $S_3: \text{True} \rightarrow \{S_3:\text{bookEvent}\} \text{EventBooked}$

- Ontology:
 - $\text{TravelSettledUp} \equiv \text{FlightBooked} \wedge \text{HotelBooked} \wedge \text{EventBooked}$
 - $\text{CommutingSettled} \equiv \text{ShuttleBooked} \vee \text{LimoBooked} \vee \text{TaxiAvailabilityChecked}$
 - ...

- Client Service Request:
 - Find a composition of the actions (i.e., a sequence, a program using such actions as basic instructions) such that a given property is fulfilled

Example (2)

- Component Services
 - $S_1: \text{True} \rightarrow \{S_1:\text{bookFlight}\} \text{FlightBooked} \wedge \text{MayBookLimo}$
 $\text{MayBookLimo} \rightarrow \{S_1:\text{bookLimo}\} \text{LimoBooked}$
 - $S_2: \text{True} \rightarrow \{S_2:\text{bookHotel}\} \text{HotelBooked}$
 $\text{HotelBooked} \rightarrow \{S_2:\text{bookShuttle}\} \text{ShuttleBooked}$
 - $S_3: \text{True} \rightarrow \{S_3:\text{bookEvent}\} \text{EventBooked}$
- Ontology:
 - $\text{TravelSettledUp} \equiv \text{FlightBooked} \wedge \text{HotelBooked} \wedge \text{EventBooked}$
 - $\text{CommutingSettled} \equiv \text{ShuttleBooked} \vee \text{LimoBooked} \vee$
 $\text{TaxiAvailabilityChecked}$
 - ...
- Client Service Request:
 - Starting from: $\neg \text{FlightBooked} \wedge \neg \text{HotelBooked} \wedge$
 $\neg \text{EventBooked} \wedge \neg \text{CommutingSettled}$
 - Achieve: $\text{TravelSettledUp} \wedge \text{CommutingSettled}$

Example (3)

- Component Services
 - $S_1: \text{True} \rightarrow \{S_1:\text{bookFlight}\} \text{FlightBooked} \wedge \text{MayBookLimo}$
 $\text{MayBookLimo} \rightarrow \{S_1:\text{bookLimo}\} \text{LimoBooked}$
 - $S_2: \text{True} \rightarrow \{S_2:\text{bookHotel}\} \text{HotelBooked}$
 $\text{HotelBooked} \rightarrow \{S_2:\text{bookShuttle}\} \text{ShuttleBooked}$
 - $S_3: \text{True} \rightarrow \{S_3:\text{bookEvent}\} \text{EventBooked}$
- Ontology:
 - $\text{TravelSettledUp} \equiv \text{FlightBooked} \wedge \text{HotelBooked} \wedge \text{EventBooked}$
 - $\text{CommutingSettled} \equiv \text{ShuttleBooked} \vee \text{LimoBooked} \vee \text{TaxiAvailabilityChecked}$
 - ...
- Client Service Request:

Starting from:

$$\neg \text{FlightBooked} \wedge \neg \text{HotelBooked} \wedge \neg \text{EventBooked} \wedge \neg \text{CommutingSettled}$$

achieve:

$$\text{TravelSettledUp} \wedge \text{CommutingSettled}$$
- Compositions:
 - $S_1:\text{bookFlight}; S_1:\text{bookLimo}; S_2:\text{bookHotel}; S_3:\text{bookEvent}$
 - $S_3:\text{bookEvent}; S_2:\text{bookHotel}; S_1:\text{bookFlight}; S_2:\text{bookShuttle}$

Another Example (1)

- Component Services:
 - S_1 : Registered $\rightarrow \{S_1:\text{bookFlight}\}$ FlightBooked
 \neg Registered $\rightarrow \{S_1:\text{register}\}$ Registered
 - S_2 : True $\rightarrow \{S_2:\text{bookHotel}\}$ HotelBooked
 HotelBooked $\rightarrow \{S_2:\text{bookShuttle}\}$ ShuttleBooked
 - S_3 : True $\rightarrow \{S_3:\text{bookEvent}\}$ EventBooked
- Ontology:
 - TravelSettedUp \equiv FlightBooked \wedge HotelBooked \wedge EventBooked
- Client Service Request:
 - Starting from:
 - \neg FlightBooked \wedge \neg HotelBooked \wedge \neg EventBooked
 - Achieve:
 - TravelSettedUp

Another Example (2)

Client Service Request:

- Starting from: $\neg \text{FlightBooked} \wedge \neg \text{HotelBooked} \wedge \neg \text{EventBooked}$
- Achieve: TravelSettedUp

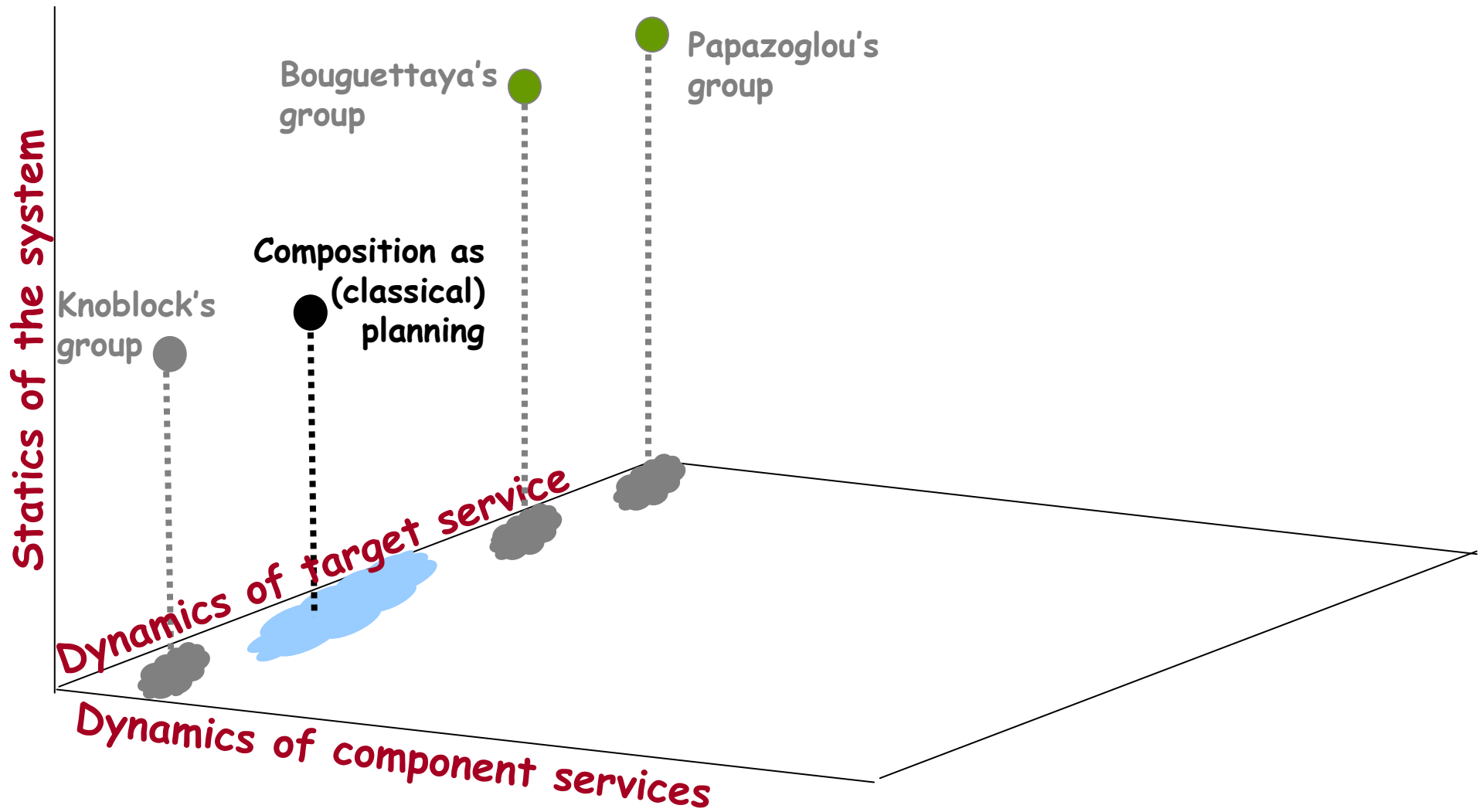
What about Registered?

The client does not know whether he/she/it is registered or not.

The composition must resolve this at runtime:

```
if ( $\neg$ Registered) {  
    S1:register;  
}  
S1:bookFlight;  
S2:bookHotel;  
S3:bookEvent
```

Composition as Planning



Planning is a Rich Area!!!

- Sequential Planning (plans are sequences of actions)
- Conditional Planning (plans are programs with if's and while's)
- Conformant Planning (plans the work in spite of incomplete -non observable- information)
- Knowledge Producing Actions/Sensing (distinction between truth and knowledge)
- Plan Monitoring
- Interleaving Deliberation and Execution
- Form of the Goals:
 - Achieve something
 - Achieve something while keeping something else
 - Temporal goals
 - Main goal + exception handling

References on Planning

- **Read and exploit planning and reasoning about actions literature!**

Books

Chapters on Planning and on Reasoning about Actions in any Artificial Intelligence textbook.

[GNT04] M. Ghallab, D. Nau, P. Traverso. Automated Planning: Theory and Practice. Morgan Kaufmann, 2004.

[Reiter02] R.Reiter: Knowledge in Action. MIT Press, 2002.

Interesting papers

[Levesque AAI/IAAI96] H. J. Levesque: What Is Planning in the Presence of Sensing? AAI/IAAI, Vol. 2 1996: 1139-1146

[Bacchus&Kabanza AAI/IAAI96] F. Bacchus, F. Kabanza: Planning for Temporally Extended Goals. AAI/IAAI, Vol. 2 1996: 1215-1222

[Giunchiglia&Traverso ECP99] F. Giunchiglia, P. Traverso: Planning as Model Checking. ECP 1999: 1-20

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[Bylander IJCAI91] Tom Bylander: Complexity Results for Planning. IJCAI 1991: 274-279

- **See how other service-researchers have used it!**

- Proceedings of P4WGS - ICAPS Workshop 2004
- Proceedings of P4WS - ICAPS Workshop 2003

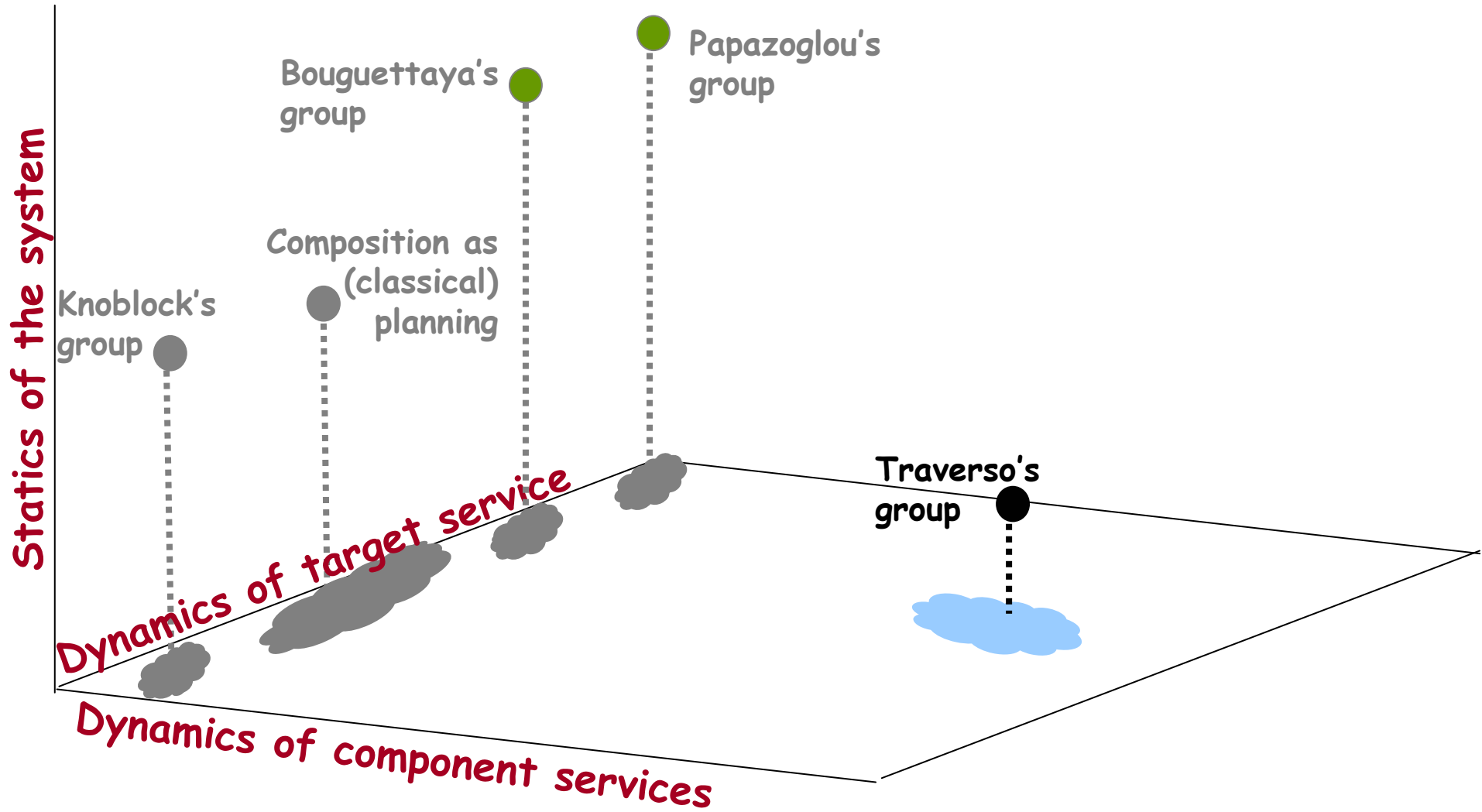
Traverso's group

- available services:
 - non-deterministic transition systems characterized by a set of initial states and by a transition relation that defines how the execution of each action leads from one state to a set of states
 - among such services, one represents the client
- client request (called global goal):
 - it specifies a main execution to follow, plus some side paths that are typically used to resolve exceptional circumstances e.g., **Do Φ else Try Ψ**

Traverso's group

- **service composition problem:** (extended) planning problem
 - Input: (i) a set of services, including the one representing the client (behavior), and (ii) the global goal,
 - Output: a plan that specifies how to coordinate the execution of various services in order to realize the global goal.
- **NOTE:**
 - the composition is not tailored towards satisfying completely the client requested behavior, but concerns with the global behavior of the system in which some client desired executions may happen not to be fulfilled

Traverso's group



References on Traverso's group

Papers on Planning as Model Checking

- [Giunchiglia&Traverso ECP99] F. Giunchiglia, P. Traverso: Planning as Model Checking. ECP 1999: 1-20
- [Pistore&Traverso IJCAI01] M. Pistore, P. Traverso: Planning as Model Checking for Extended Goals in Non-deterministic Domains. IJCAI 2001: 479-486
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- [Bertoli et al ICAPS03] P. Bertoli, A. Cimatti, M. Pistore, P. Traverso: A Framework for Planning with Extended Goals under Partial Observability. ICAPS 2003: 215-225

Papers on Service Composition

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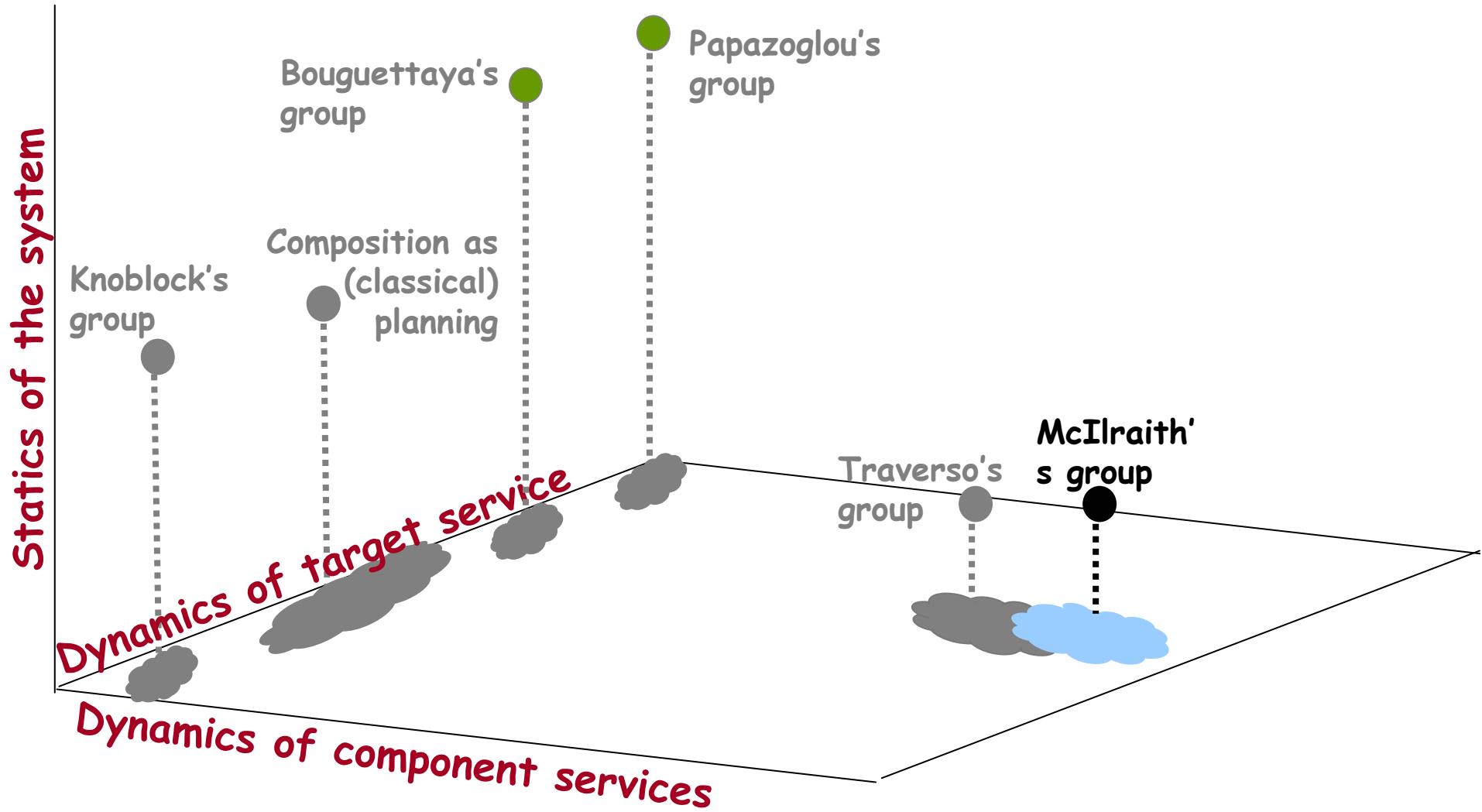
McIlraith's group

- both available and composite service:
behavioral description seen as procedures
invokable by clients
 - Golog procedure, atomically executed, i.e., seen by its client as an atomic Situation Calculus action, presenting an I/O interface
 - each service stored in an OWL-S ontology

McIlraith's group

- client request:
 - skeleton of a Golog procedure expressing also client constraints and preferences
- **service composition problem:**
 - **Input:** (i) OWL-S ontology of services as atomic actions, and (ii) client request
 - **Output:** Golog procedure obtained by **automatically** instantiating the client request with services contained in the ontology, by also taking client preferences and constraints into account
- NOTE: the client has not influence over the control flow of the composite service

McIlraith's group



References on McIlraith's group

Background

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- [McCarthy&Hayes MI69] J. L. McCarthy and P. C. Hayes: Some Philosophical Problems from the Standpoint of Artificial Intelligence. *Machine Intelligence* 4, 1969
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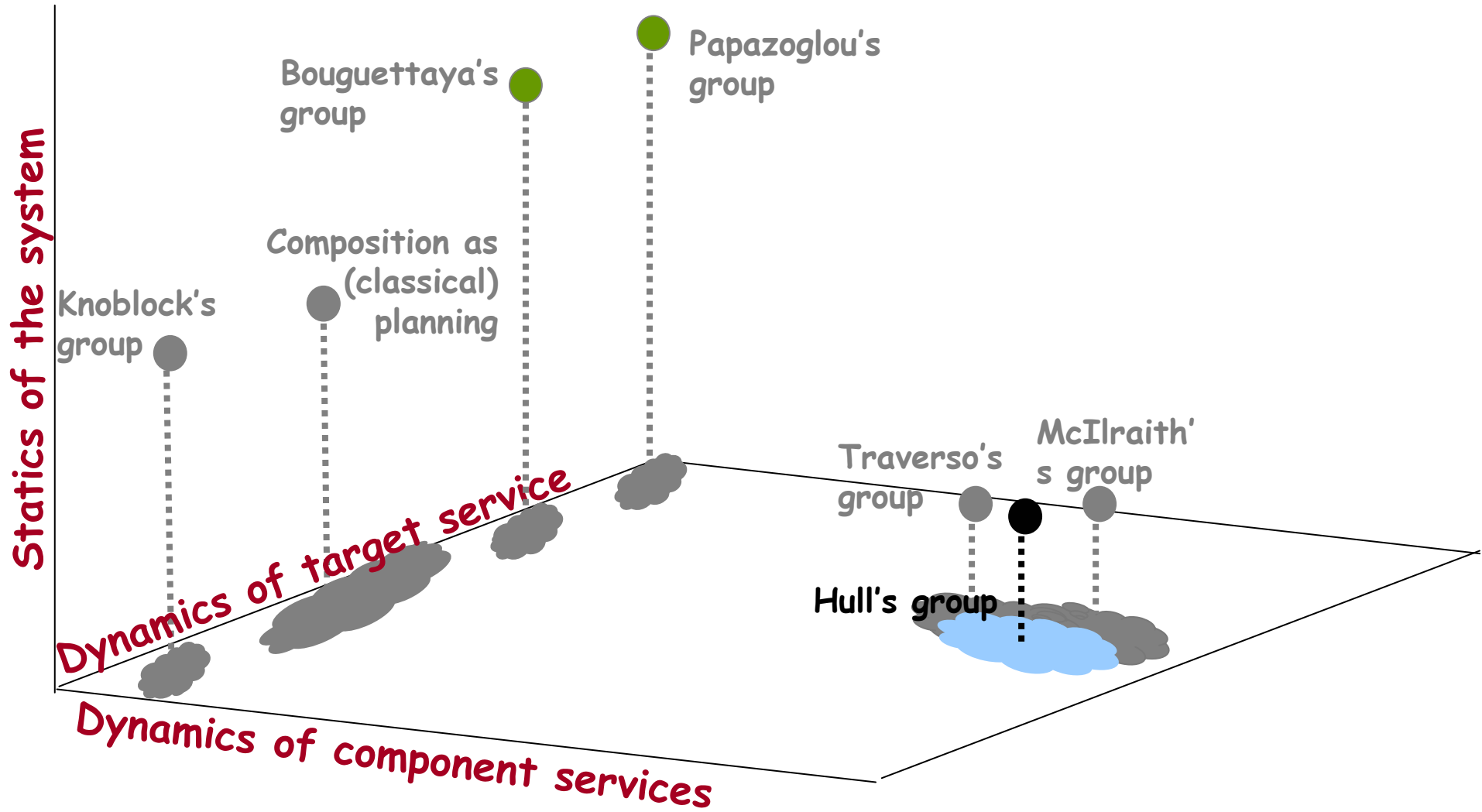
Hull's group

- both available and composite service (peer):
behavioral description
 - Mealy machine, that exchanges messages with other peers according to a predefined communication topology (channels among peers)
 - peers equipped with (bounded) queue to store messages received but not yet processed
 - Conversation: sequence of messages exchanged by peers
 - At each step, a peer can either (i) send a message, or (ii) receive a message, or (iii) consume a message from the queue, or (iv) perform an empty move, by just changing state

Hull's group

- **Choreography mapping problem:**
 - **Input:** (i) a desired global behavior (i.e., set of desired conversations) as a Linear Temporal Logic formula, and (ii) an infrastructure (a set of channels, a set of peer names and a set of messages)
 - **Output:** Mealy machines (**automatically obtained**) for all the peers such that their conversations are compliant with the LTL specification
- **NOTE:** not yet a "jam session style" choreography

Hull's group



References on Hull's group

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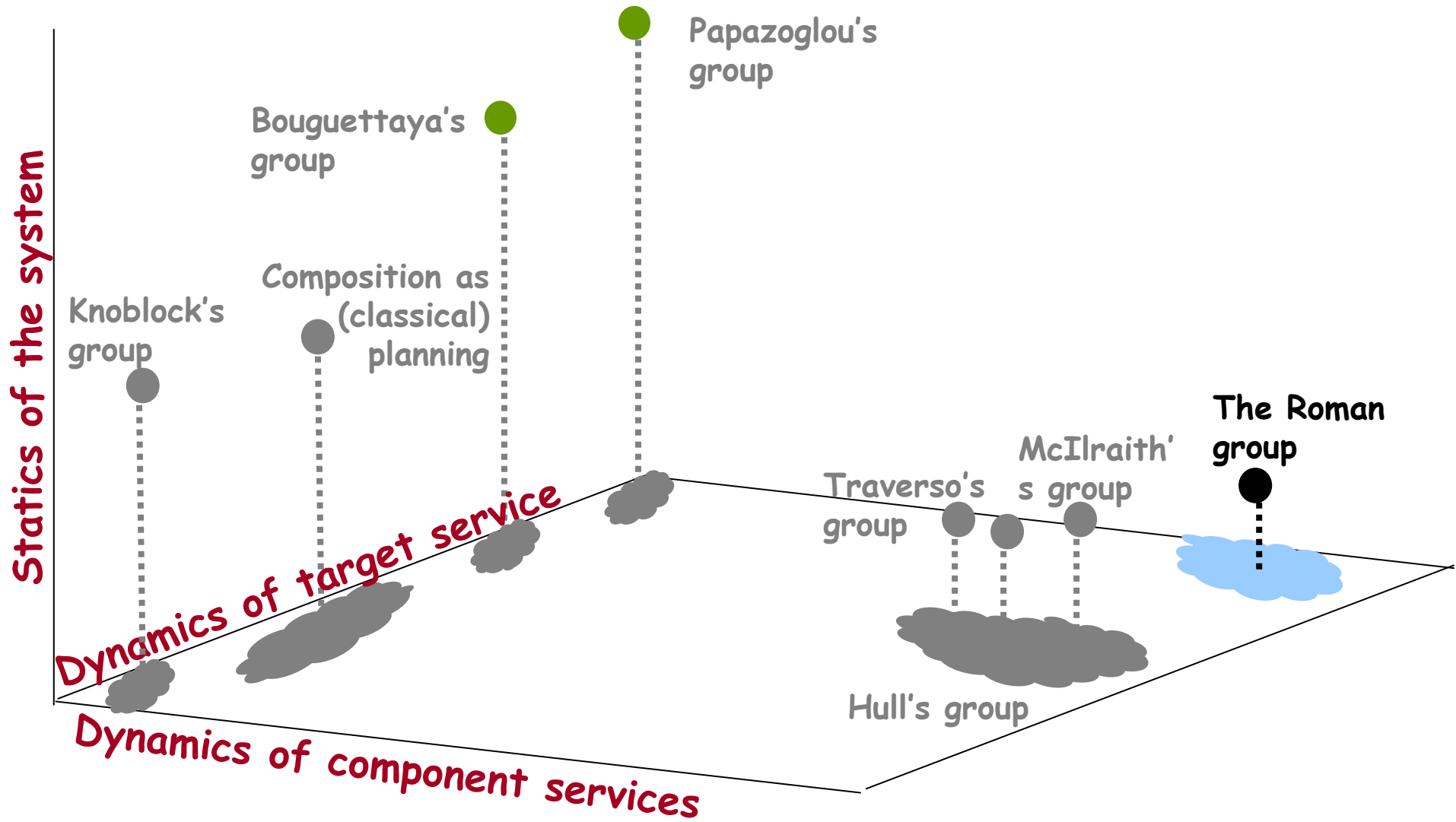
The Roman group

- available service: **behavioral description**
 - service as an interactive program: at each step it presents the client with a set of actions among which to choose the next one to be executed
 - client choice depends on outcome of previously executed actions, but the rationale behind this choice depends entirely on the client
 - behavior modeled by a finite state transition system, each transition being labeled by a deterministic (atomic) action, seen as the abstraction of the effective input/output messages and operations offered by the service

The Roman group

- client request (target service):
 - set of executions organized in a (finite state) *transition system* of the activities he is interested in doing
- **service composition problem:**
 - **Input:** (i) finite state transition system of available services, and (ii) finite state transition system of target service
 - **Output:** (automatically obtained) composite service that realizes the client request, such that each action of the target service is delegated to at least one available service, in accordance with the behavior of such service.
- NOTE: the client "strongly" influence the composite service control flow

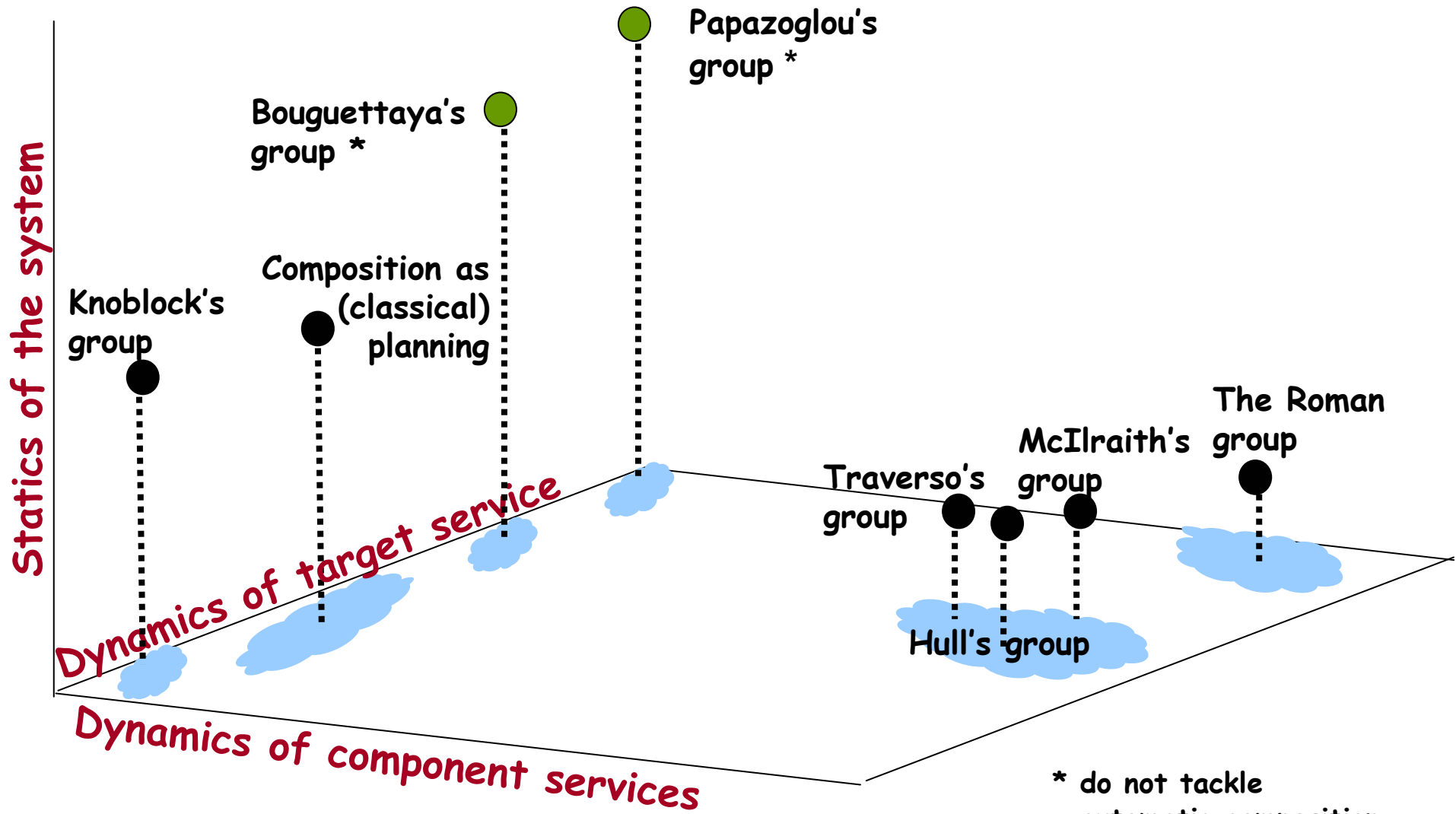
The Roman group



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The whole picture



Other Relevant Works

- Approaches proposing interesting conceptual models for services, not targeted towards composition:
 - Vianu 's group
 - Benatallah & Casati's group

Vianu's group

A. Deutsch, L. Sui, and V. Vianu: Specification and Verification of Data-driven Web Services, In Proceedings of the 23rd ACM SIGACT SIGMOD SIGART Symposium on Principles of Database Systems (PODS 2004), ACM, 2004, pp. 71-82

- available service: data query + behavioral descr.
 - service as a data-driven entity characterized by a database and a tree of web pages
 - At each step, set of input choices presented to client: some generated as queries over the database; specific client data treated as constants. The client chooses one of such inputs, and in response, the service produces as output updates over the service database and/or performs some actions, and makes a transition from a web page to another
- automatic verification of service properties:
 - both over runs (linear setting) and over sets of runs (branching setting)
 - they characterize the complexity of verifying such properties for various classes of services

Benatallah & Casati's group

B. Benatallah, F. Casati, and F. Toumani:

Web services conversation modeling: The Cornerstone for E-Business Automation.

IEEE Internet Computing, 8 (2004), no. 1, pp.46 - 54

- available service: **behavioral description**
 - behavior of a service as finite state transition system in terms of message exchanged with the clients (conversations)
 - transitions labeled by messages, and states labeled with the status of the conversation (e.g., effect of the message exchange leading to it, if clearly defined)
- they study how to automatically generate the skeleton of a BPEL4WS spec. starting from the transition system modeling the service behavior
- they also study properties of service behavior in order for two services to correctly interact

(Only) Orchestration

- Two main kinds of orchestration [Hull et al PODS03]:
 - (i) the mediated approach, based on a hub-and-spoke topology, in which one service is given the role of process mediator/delegator, and all the interactions pass through such a service, and
 - (ii) the peer-to-peer approach, in which there is no centralized control

Mediated Orchestration Engines

- *e-Flow [Casati & Shan, IS01]:*
 - Platform for specifying, enacting and monitoring composite service
 - Composite *E-Service* (CES) is a service process engine offered as (meta-) service that performs coordination of services, with some process adaption/evolution mechanisms
 - A provider can offer a value added service as coordination of different services: it registers the new service to the CES and let the CES enact its execution
- *AZTEC [Christophides etal TES01]:*
 - Framework for orchestration of session-oriented, long running telecommunication services is studied. It is based on active flowcharts thus coping with asynchronous events that can happen during active telecom sessions

Mediated Orchestration Engines

- WISE [*Lazcano et al CSSE2000*]:
 - Orchestration engine that coordinates the execution of distributed applications (virtual processes), and a set of brokers enables the interaction with already existing systems that are to be used as building blocks.
 - Process meta-model based on Petri Nets, with the possibility to add Event-Condition-Action (ECA) rules
- MENTOR-lite [*Shegalov et al VLDBJ01*]:
 - Workow management system based on a XML mediator for coordinating services which are distributed among different organizations and deployed on heterogeneous platforms
 - Process meta-model is based on a specific statechart dialect

Peer-to-Peer Orchestration Engines

- *Self-Serv [Benatallah et al IEEE03]:*
 - Platform for composing services and executing new composed services in a decentralized way, through peer-to-peer interactions
 - Composite service modeled as an activity diagram
 - Its enactment carried out through the coordination of different state coordinators (one for each service involved in the specification and one for the composite service itself)
- *PARIDE Orchestrator [Mecella et al VLDB-TES02]:*
 - A composition schema, modeled as a specific Coloured Petri Net, is orchestrated by a set of organizations, which moves it (as a "token") along the execution
 - Separation between the responsibility of the orchestration and the providing of services (suitable in specific scenarios)
 - Services can be substituted with other compatibles

References

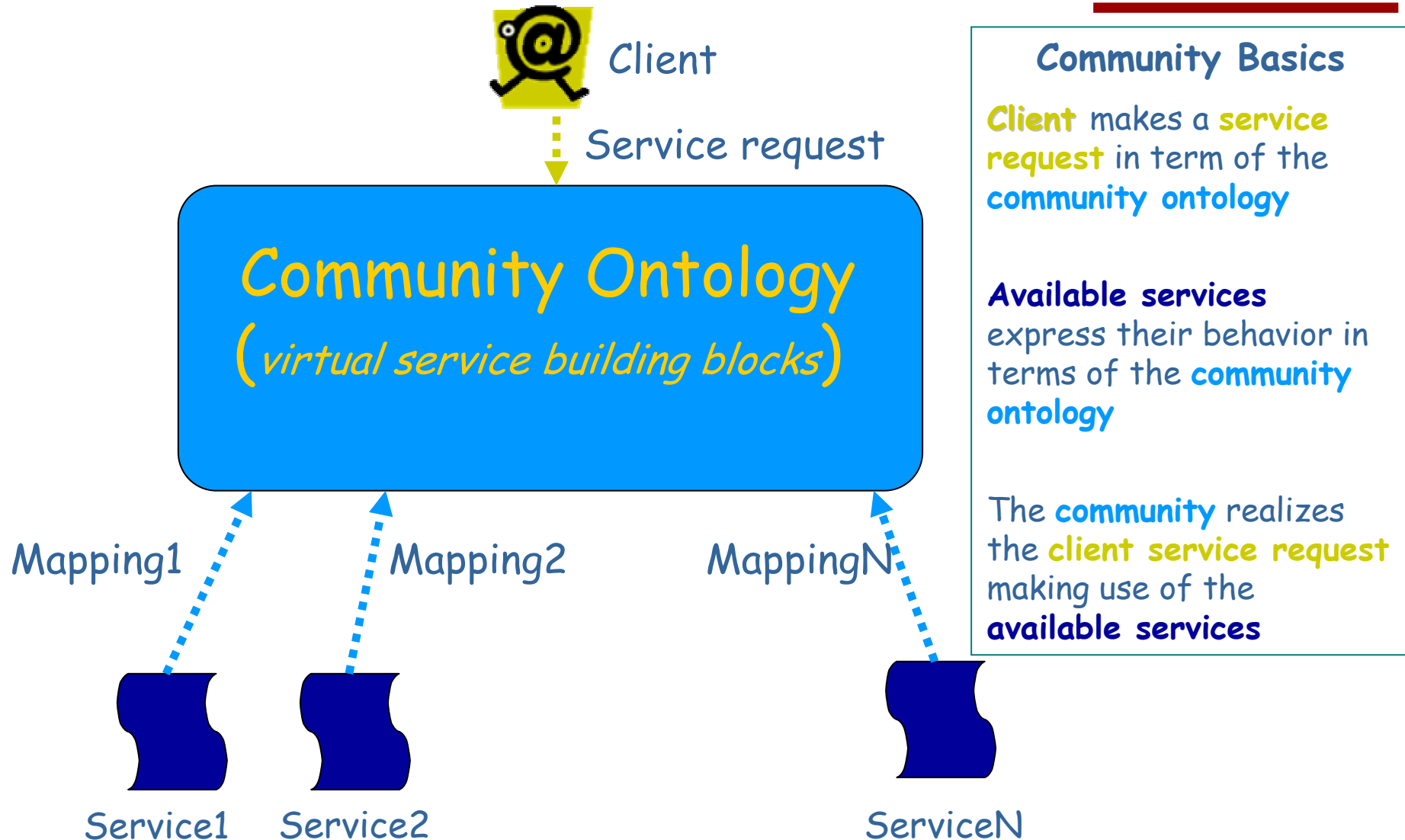
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Automatic Composition: A Basic Research Perspective

Basic Research

- Envision of a sort of
"Service Semantic Integration System"
- Semantic integration via composition synthesis
- Several directions (as we have seen):
 - Information Oriented Services
 - Services as Atomic Actions
 - Services as Processes

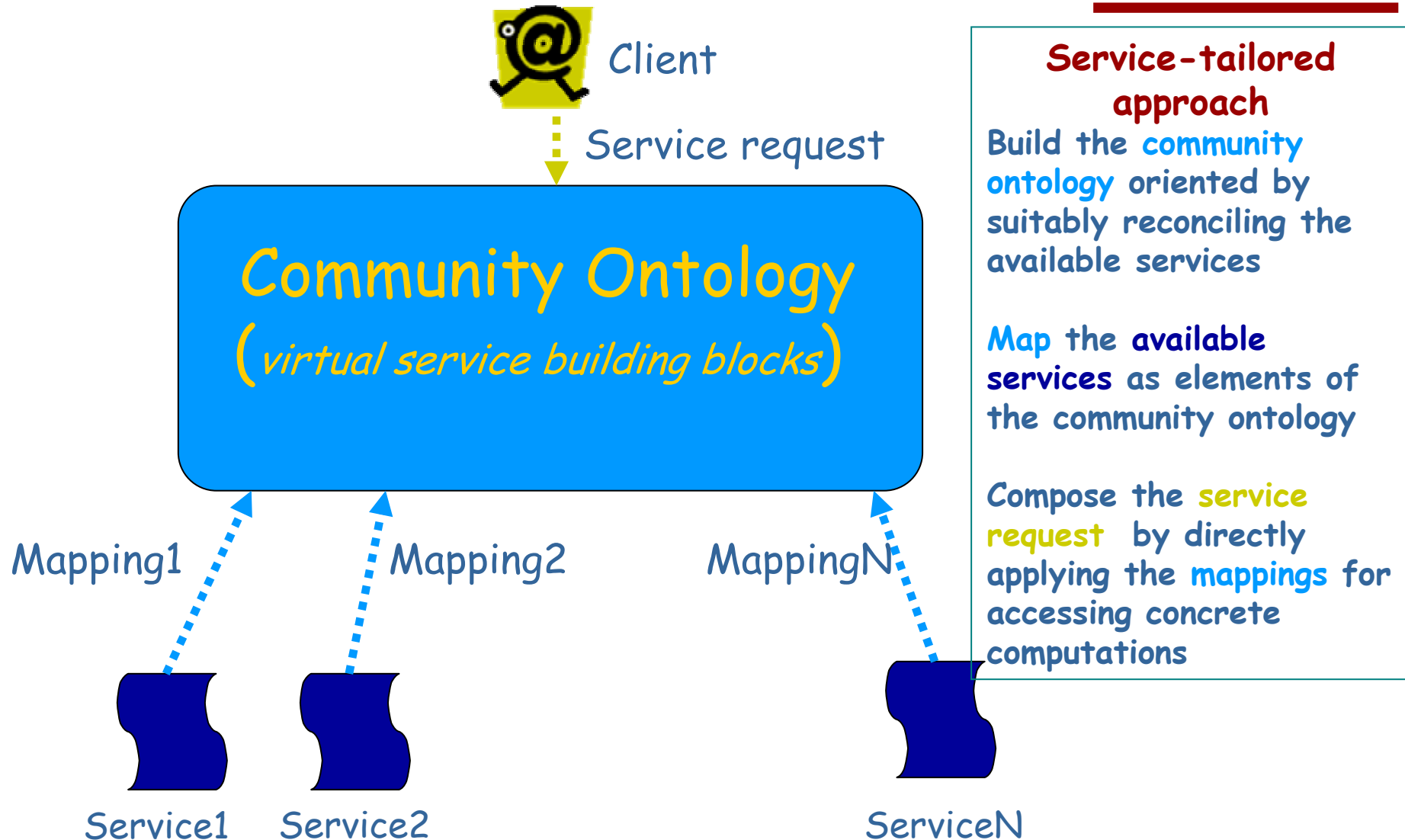
Semantic Service Integration



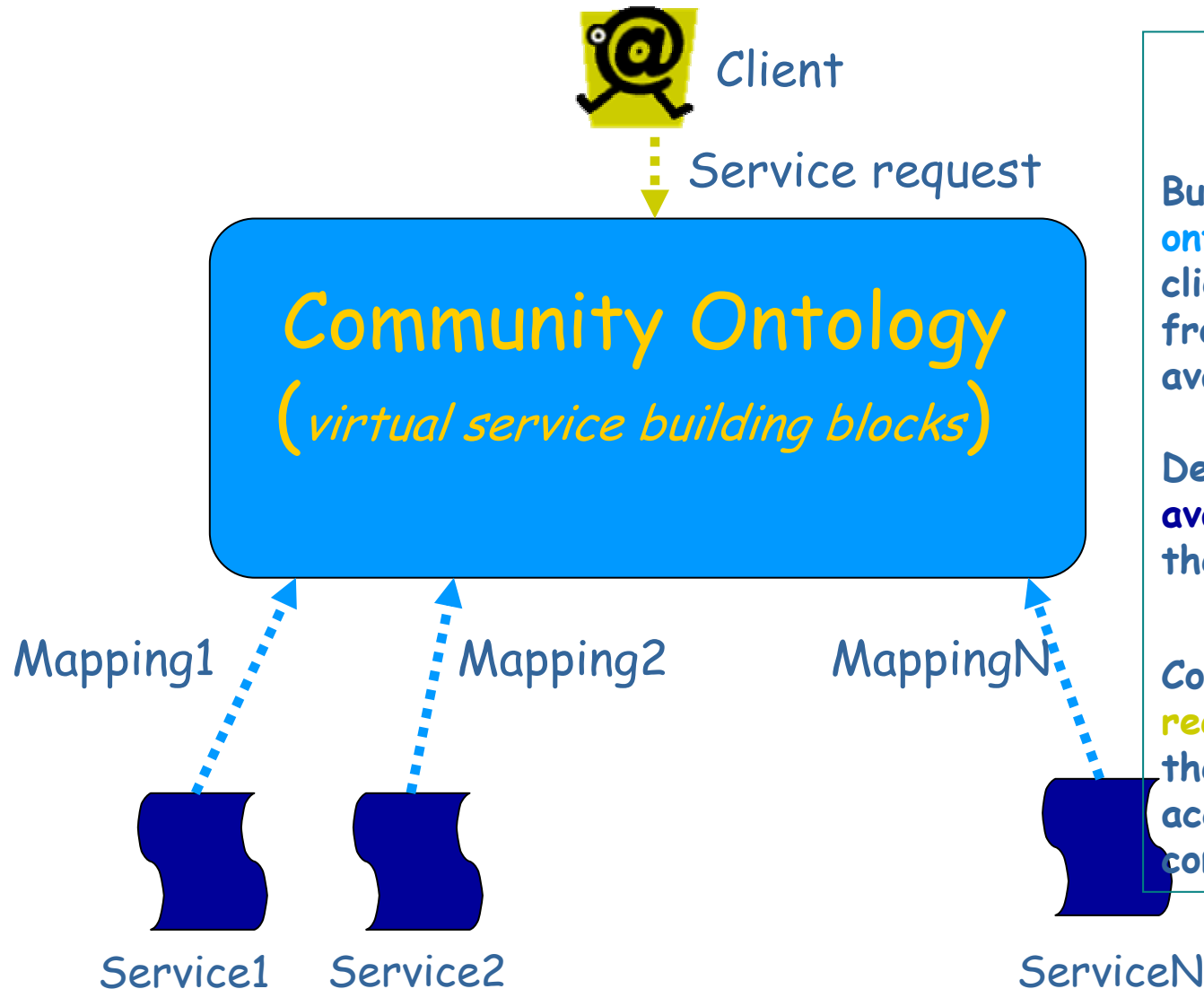
Service Integration Systems

- In building such system we can take two general approach:
 - Service-tailored
 - Client-tailored

Service-Tailored Approach



Client-Tailored Approach



Client-tailored approach

Build the **community ontology** oriented to the client, independently from the services available

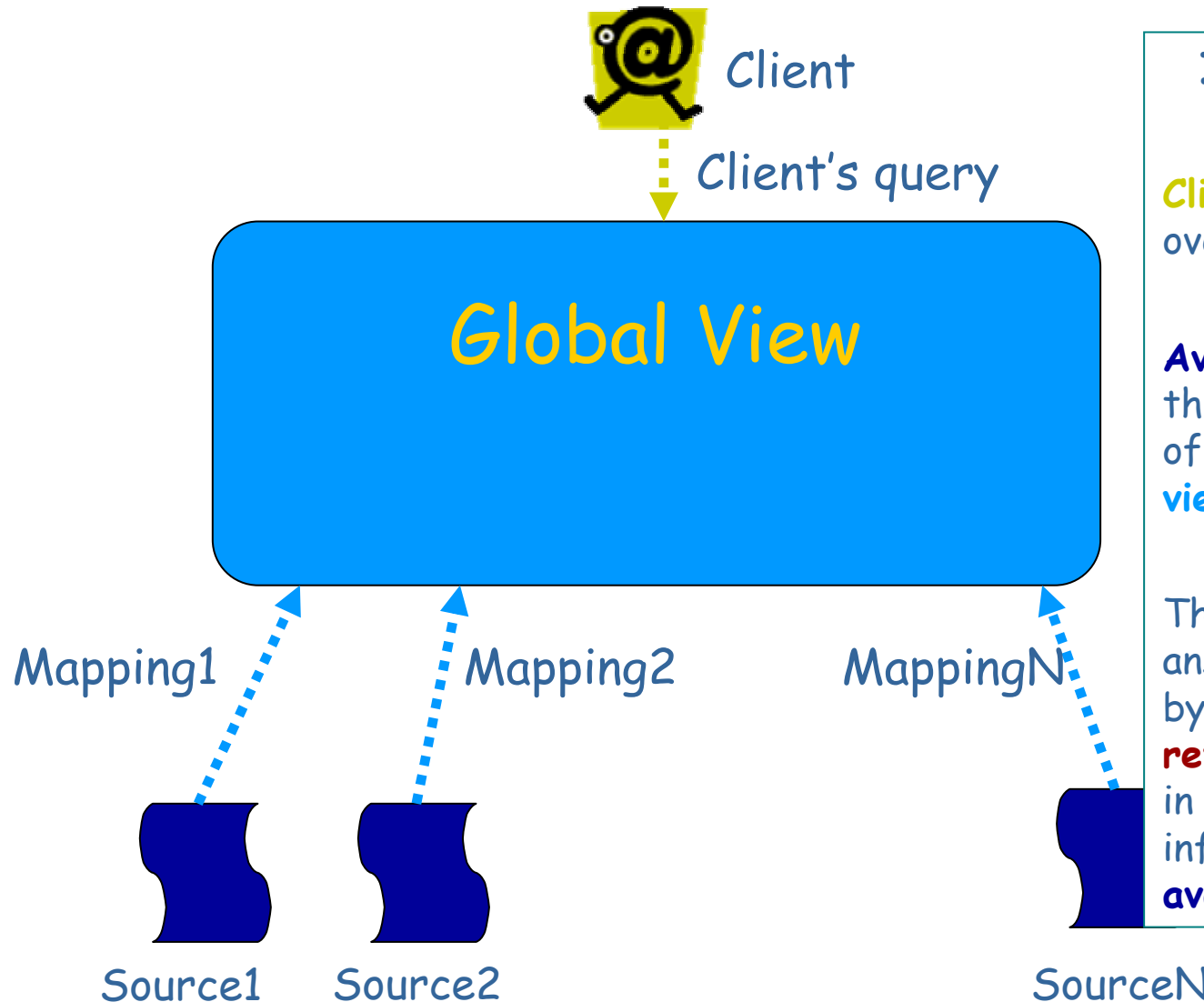
Describe (**map**) the **available services** using the community ontology

Compose the **service request** by reversing these **mappings** for accessing concrete computations

Data Integration

- The Service-tailored vs Client-tailored distinction mimics the **GAV** (Global As View) vs **LAV** (Local As View) approach in **data integration** ...

Data Integration System



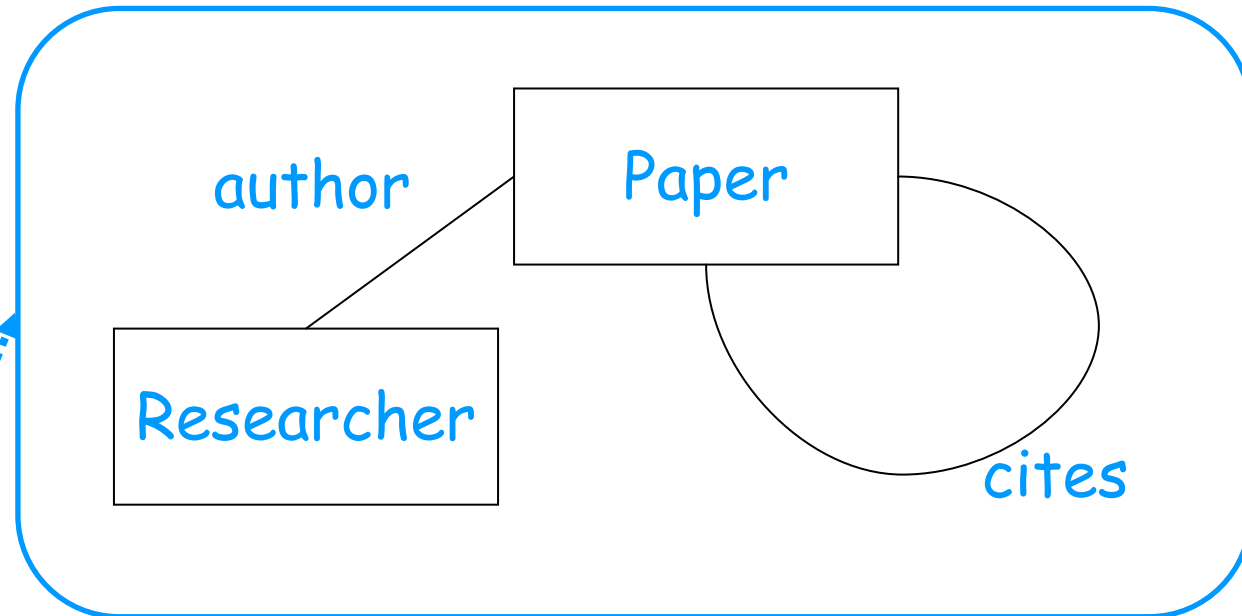
Integration System Basics

Client's request: query over the global view

Available sources express their information in terms of a query over the global view

The integration system answers the client's query by **reformulating/rewriting** it in terms of the information in the **available sources**

Example



$$\text{Selfcitation}(x) \rightsquigarrow \exists z, y. \text{cite}(x,y) \wedge \text{author}(z,x) \wedge \text{author}(z,y)$$

Selfcitation

...

Selfcitation: contains papers that cite (other) papers by the same authors

GAV and LAV Mappings in Data Integration

- In **data integration**, we can distinguish two approaches in defining the mapping:
 - **GAV** (Global As View): terms of the Global View are mapped to queries over the sources
 - **LAV** (Local As View): sources are described by mapping them to a query over the Global View (cf. previous example)

GAV vs LAV

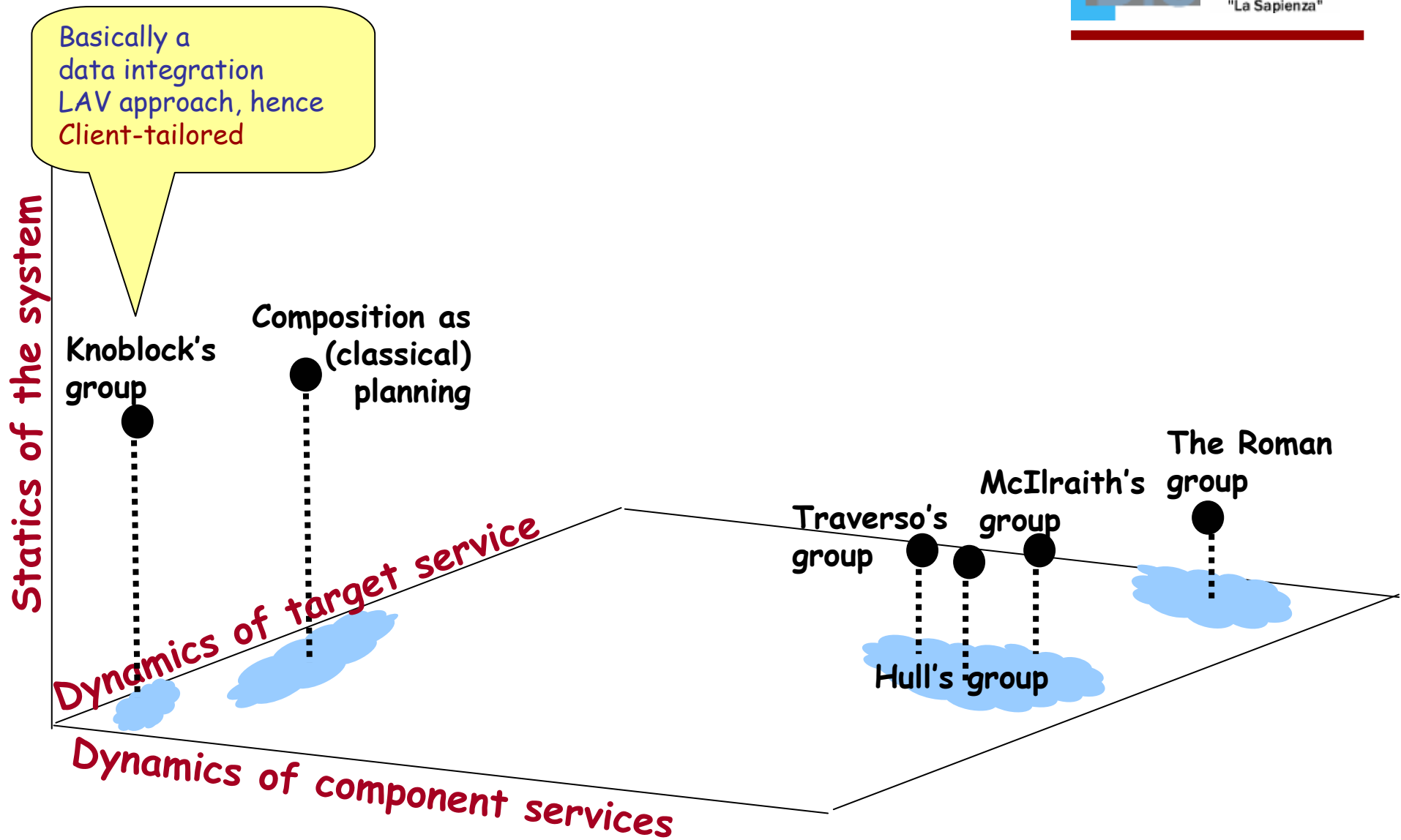
- **GAV:**
 - Adopted in early Data Integration Systems
 - Typical setting
 - Sources are relational DBs
 - Global View is a relational schema
 - Mapping associate relations in the global view with a relational query over the sources
 - **Query Answering** is performed by
 - "unfolding" (substituting) each relation in the client's query with the corresponding query over the sources (the mapping),
c.f., computing the composition
 - the evaluating the resulting query
c.f., executing the composition
 - If constrains are present in the Global View, QA becomes more involved

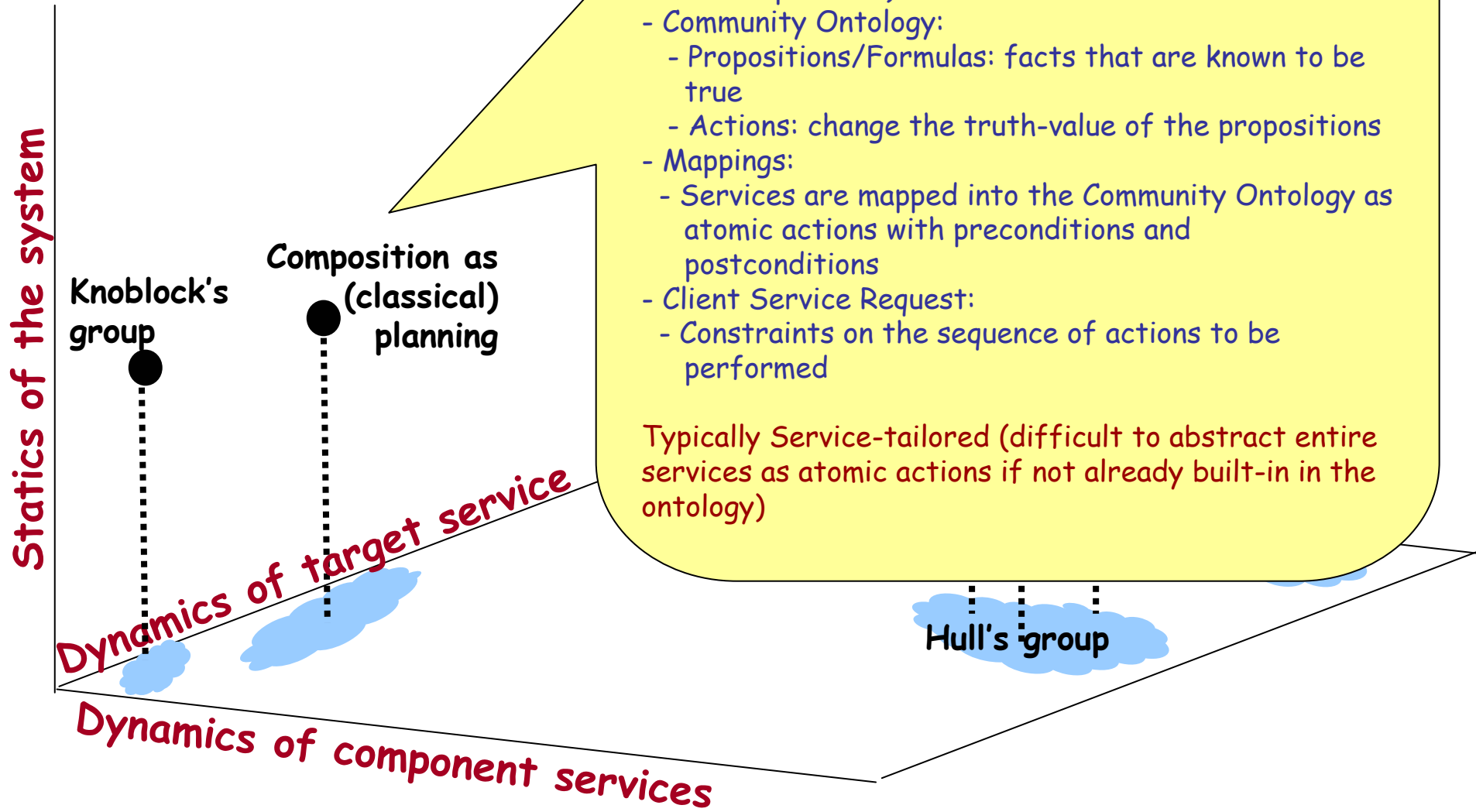
GAV vs LAV

- LAV:
 - Recent research on data integration favors the LAV approach over the GAV approach
 - **Better support of dynamic changes in the system:** sources (services) can be added and deleted without restructuring the global view (community ontology), and hence without impacting the clients
 - **Query Answering** is a challenge because it needs to deal with incomplete information
 - QA is conceptually performed by
 - first, "**rewriting**" the client query to an "equivalent" query over the sources,
c.f., computing the composition
 - then, evaluating the resulting query
c.f., executing the composition
 - Often rewriting is not obvious and/or may require query languages that are different from the one used by the client and the mappings

Impact on Service Composition

- Work in data integration as a **direct impact on information-based service composition systems**
 - Techniques developed there can be often used off-the-shelf or with minor adaptation for information-based services
- More generally data integration research has deeply looked at systems that share many conceptual notions with service composition systems:
 - **Insights** in data integration systems can be applied to service composition systems
 - Examples:
 - The distinction between **GAV** and **LAV**
 - The distinction between **query evaluation** and **query rewriting** (**execution time vs. composition time**)
- However Data Integration has **not** looked at the **procedural aspects** typical of services (except for binding patterns)





- Services seen as (possibly infinite) transition systems
- Common ontology is a Situation Calculus Theory and service names
- Mapping:
 - each service name in the common ontology is mapped to a service seen as a procedure in Golog/Congolog SitCalc based high level programming language these languages describe (possibly infinite transition system)
- Client Service Request
 - Golog/Congolog program having service name as atomic actions with the understanding that it specifies acceptable sequenced of actions for the client (as in planning) and not a transition system that the client want to realize (see later)

Essentially a Service-tailored approach

Statics of the system

Knoblock's group

Dynamics of target service

Dynamics of component services

Traverso's group

McIlraith's group

The Roman group

Hull's group

Statics of the system

Knoblock's group

Composition (classic planning)

Dynamics of target service

Dynamics of component services

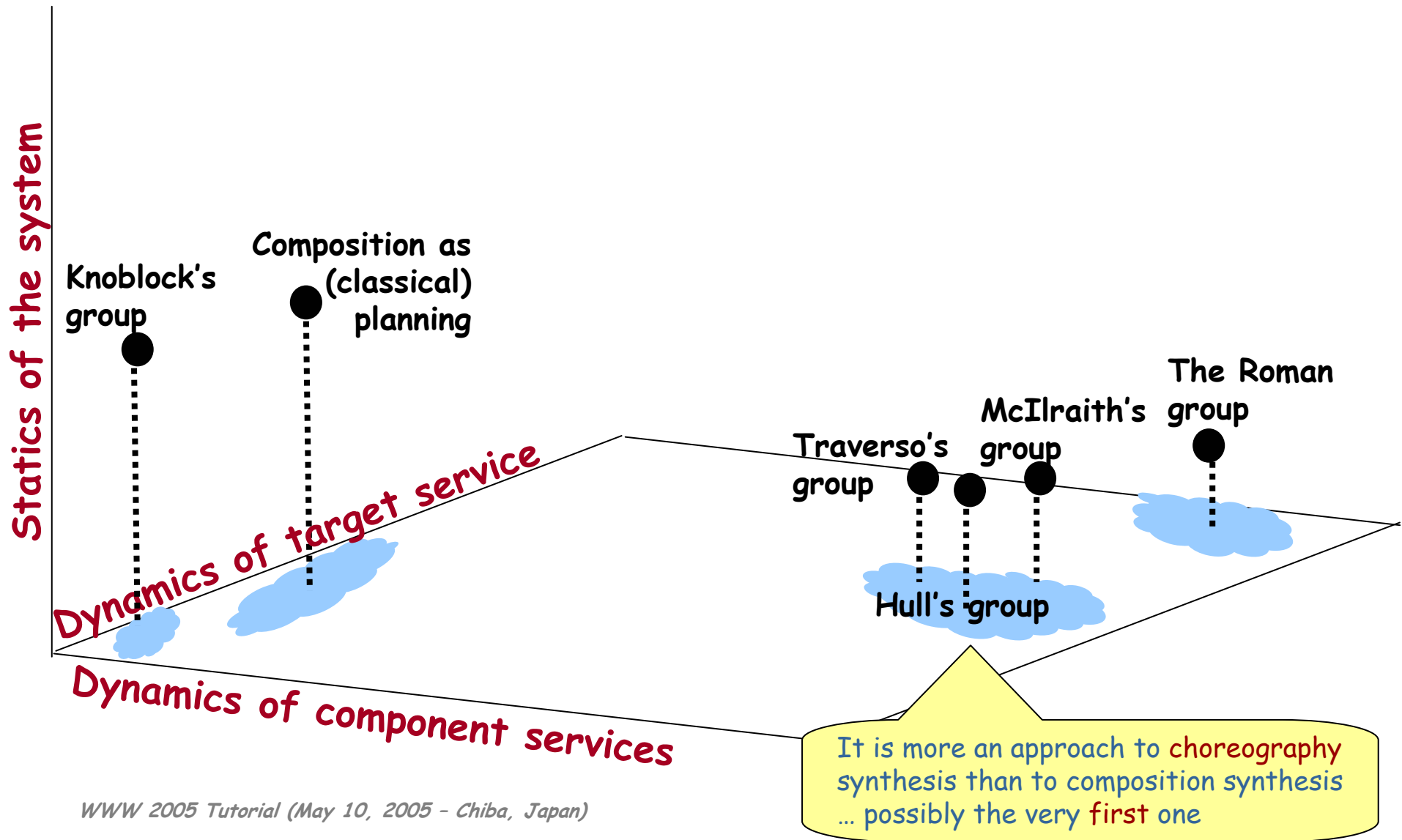
Traverso's group

McIlraith's group

Hull's group

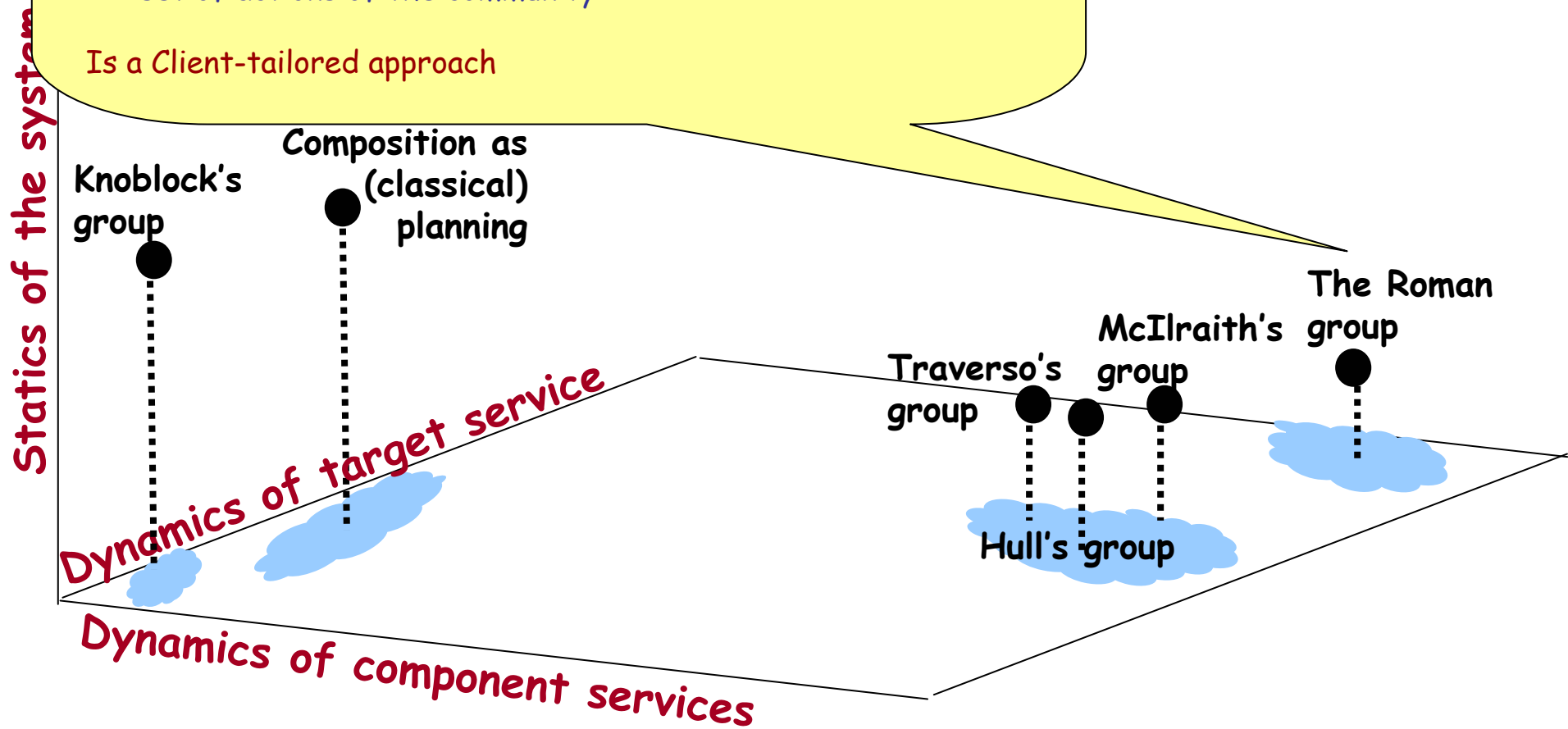
- Services seen as (finite) transition systems
- Common ontology:
 - atomic actions and propositions, as in Planning
- Mapping:
 - A service is mapped to the community ontology as a transition system using the alphabet of the community and defining how transitions affect the propositions
- Client Service Request:
 - try to find a sequence of actions to achieve Goal1 (main computation), with guarantees that upon failure Goal2 is reached (exception handling)

Can be seen as a Client-tailored approach



- Services seen as (finite) transition systems
- Common ontology: Alphabet of atomic actions
- Mapping:
 - A service is mapped to the community ontology as a transition system using the alphabet of the community
- Client Service Request:
 - Desired service behavior, i.e., a (finite) TS using the common set of actions of the community

Is a Client-tailored approach



References

- **Read and exploit data integration literature!**

- Survey on data integration**

- [Halevy VLDBJ01] A. Y. Halevy: Answering queries using views: A survey. VLDB J. 10(4): 270-294 (2001)

- [Lenzerini PODS02] M. Lenzerini: Data Integration: A Theoretical Perspective. PODS 2002: 233-246

- [Ullman ICDT97] J. D. Ullman: Information Integration Using Logical Views. ICDT 1997: 19-40

- Seminal papers**

- [Levy etal PODS05] A. Y. Levy, A. O. Mendelzon, Y. Sagiv, D. Srivastava: Answering Queries Using Views. PODS 1995: 95-104

- [Abiteboul etal PODS98] S. Abiteboul, O. M. Duschka: Complexity of Answering Queries Using Materialized Views. PODS 1998: 254-263

- [Duschka etal PODS97] O. M. Duschka, M. R. Genesereth: Answering Recursive Queries Using Views. PODS 1997: 109-116

- [Calvanese etal JCSS02] D. Calvanese, G. De Giacomo, M. Lenzerini, M. Y. Vardi: Rewriting of Regular Expressions and Regular Path Queries. J. Comput. Syst. Sci. 64(3): 443-465 (2002)

- [Rajaraman etal PODS95] A. Rajaraman, Y. Sagiv, J. D. Ullman: Answering Queries Using Templates with Binding Patterns. PODS 1995: 105-112

- **See how other service-researchers have used it!**

- [Ghandeharizadeh etal ICWS03] S. Ghandeharizadeh, C. A. Knoblock, C. Papadopoulos, C. Shahabi, E. Alwagait, J. L. Ambite, M. Cai, C. Chen, P. Pol, R. R. Schmidt, S. Song, S. Thakkar, R. Zhou: Proteus: A System for Dynamically Composing and Intelligently Executing Web Services. ICWS 2003: 17-21

- [Thakkar etal P4WGS] S. Thakkar, J. L. Ambite, C. A. Knoblock: A Data Integration Approach to Automatically Composing and Optimizing Web Services. P4WGS -ICAPS WS 2004: 86-93

Transition Systems (in more details)

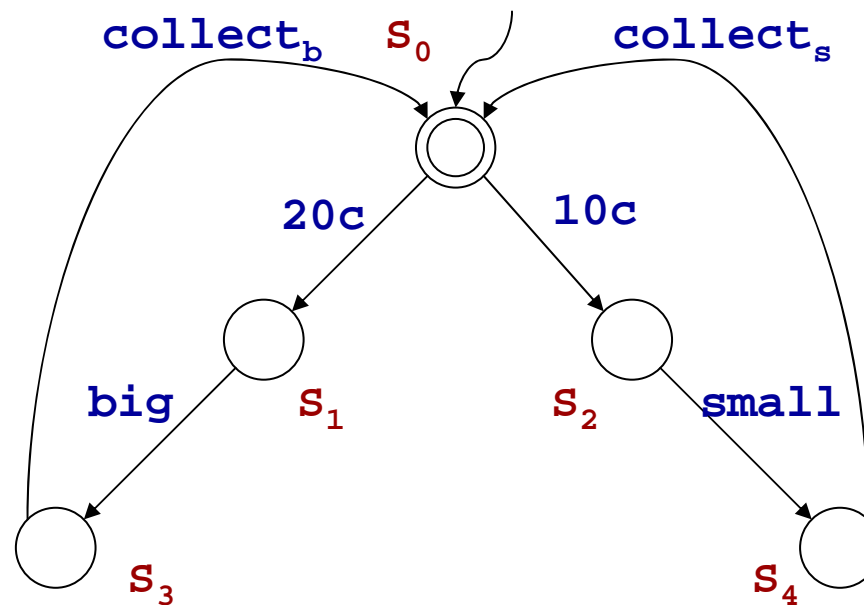
Transition Systems

- A transition system TS is a tuple $T = \langle A, S, S^0, \delta, F \rangle$ where:
 - A is the set of actions
 - S is the set of states
 - $S^0 \subseteq S$ is the set of initial states
 - $\delta \subseteq S \times A \times S$ is the transition relation
 - $F \subseteq S$ is the set of final states

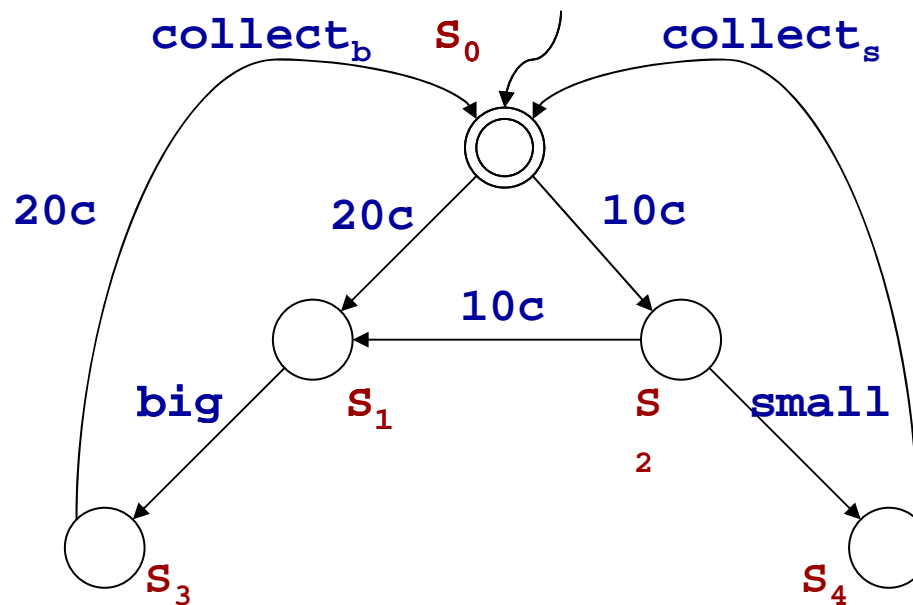
(c.f. Kripke Structure)

- Variants:
 - No initial states
 - Single initial state
 - Deterministic actions
 - States labeled by propositions other than Final/ \neg Final

Example (Vending Machine)

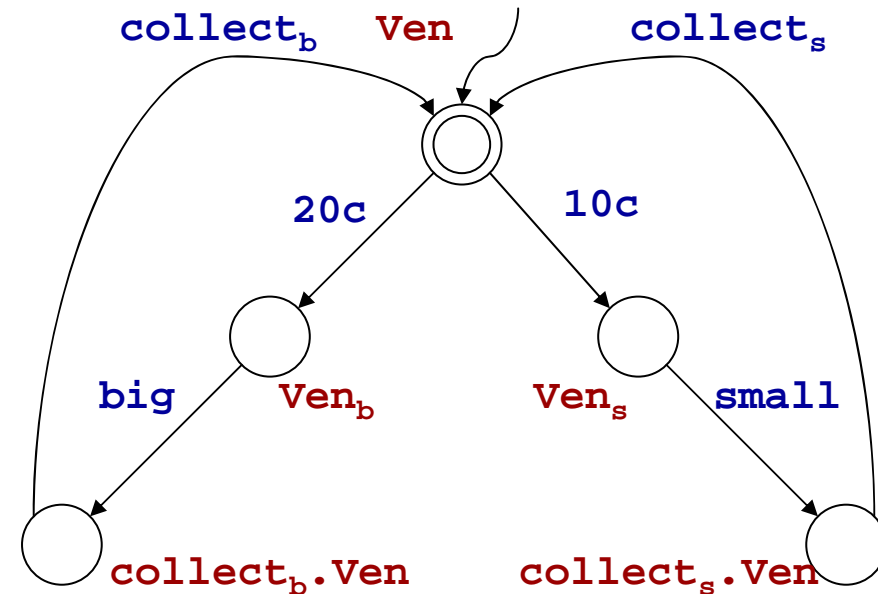


Example (Another Vending Machine)



Process Algebras are Formalisms for Describing TS

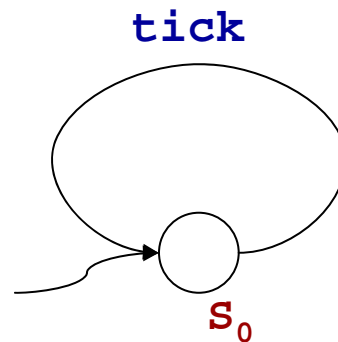
- Trans (a la CCS)
 - $Ven = 20c.Ven_b + 10c.Ven_s$
 - $Ven_b = big.collect_b.Ven$
 - $Ven_s = small.collect_s.Ven$
- Final
 - $\checkmark Ven$



- *TS may have infinite states - e.g., this happens when generated by process algebras involving iterated concurrency*
- *However we have good formal tools to deal only with finite states TS*

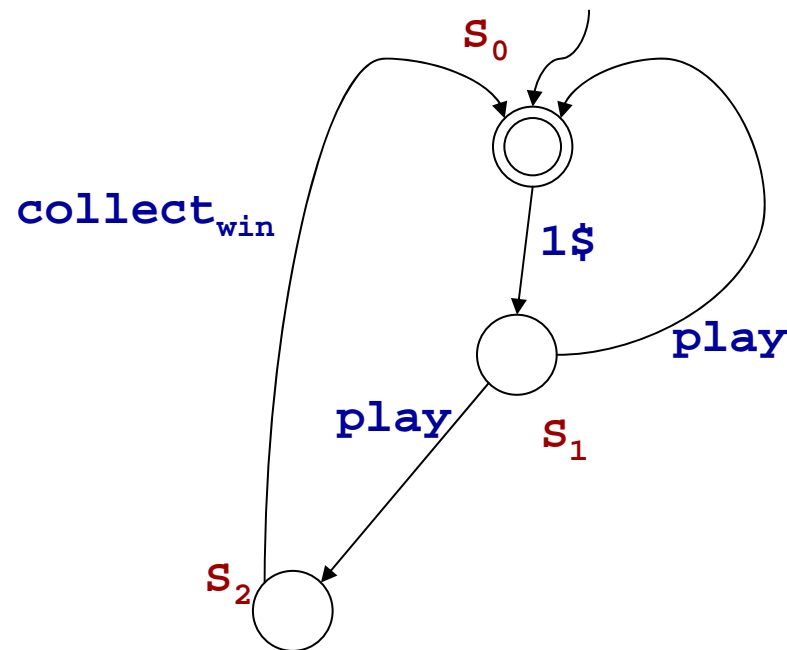
Example (Clock)

TS may describe (legal) nonterminating processes

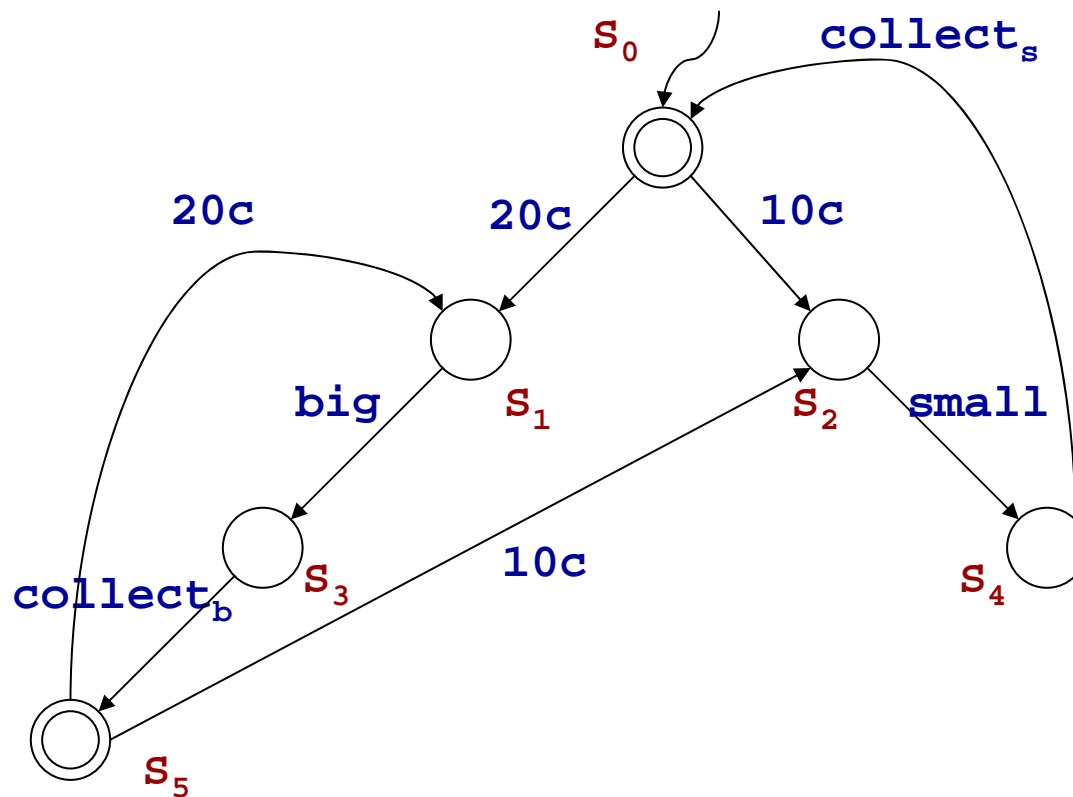


Example (Slot Machine)

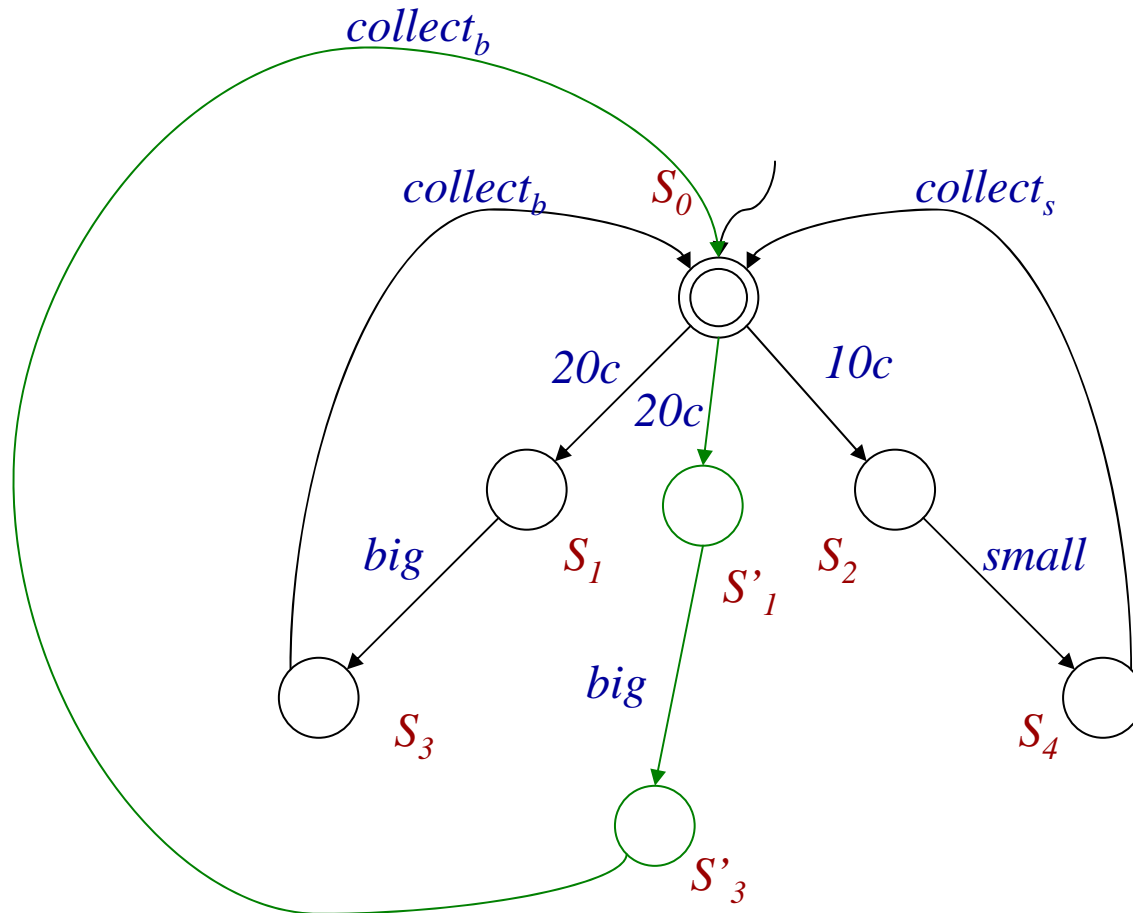
Nondereminisic transitions express
choice that is not under the control of clients



Example (Vending Machine - Variant 1)



Example (Vending Machine - Variant 2)



Bisimulation

- A binary relation R is a **bisimulation** iff:

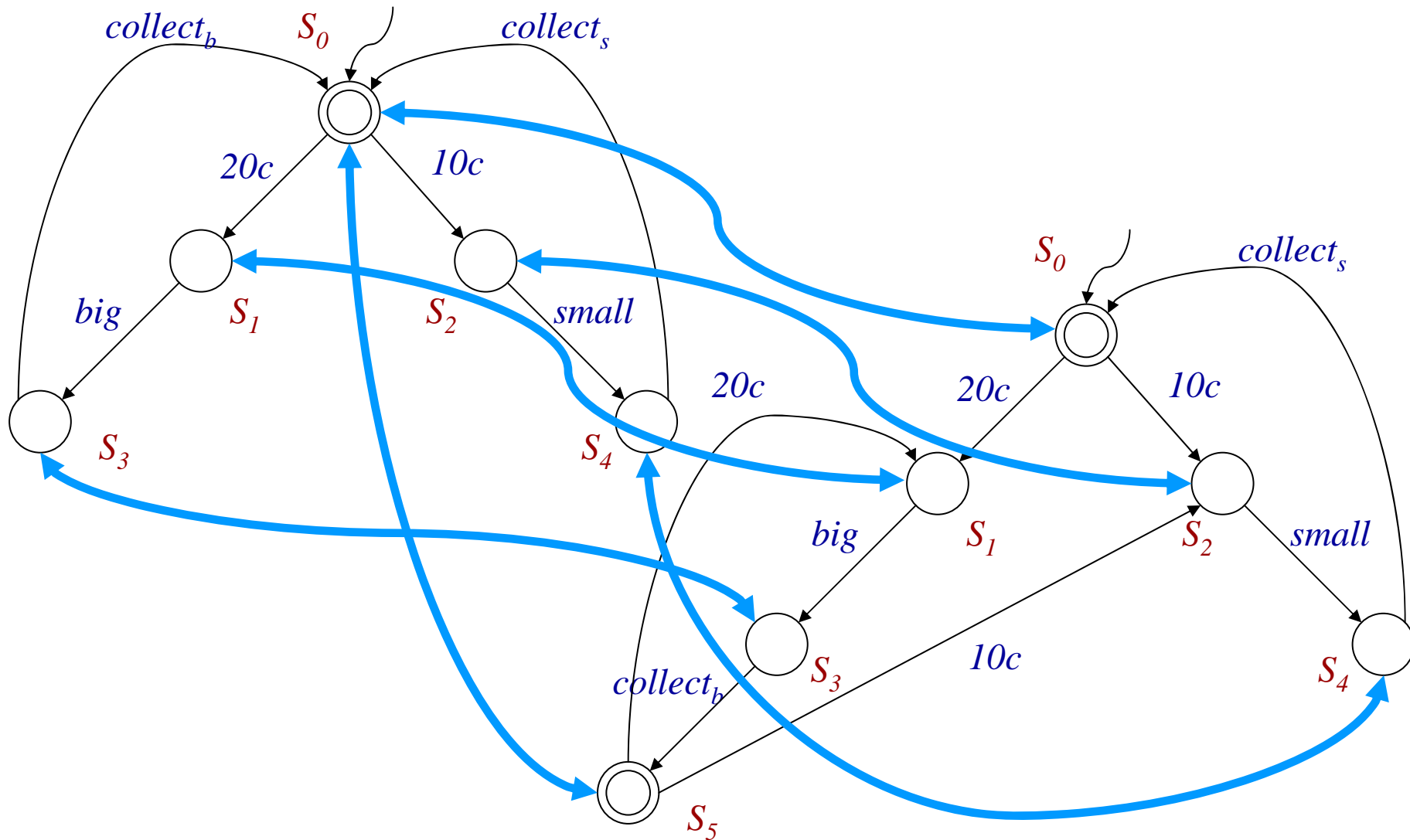
$(s,t) \in R$ implies that

- s is *final* iff t is *final*
- for all actions a
 - if $s \rightarrow_a s'$ then $\exists t' . t \rightarrow_a t'$ and $(s',t') \in R$
 - if $t \rightarrow_a t'$ then $\exists s' . s \rightarrow_a s'$ and $(s',t') \in R$

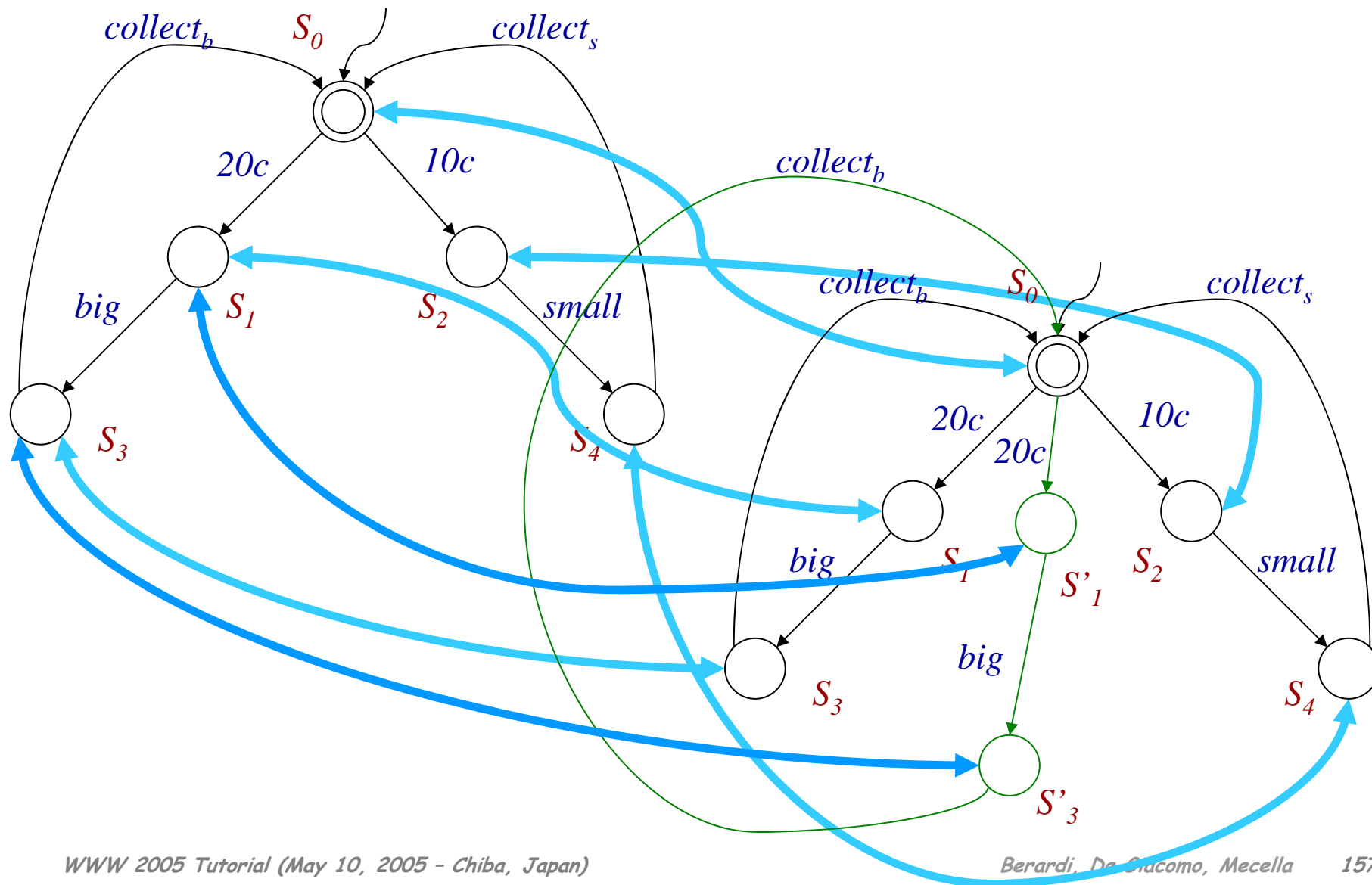
Note it is a co-inductive definition!

- A state s_0 of transition system S is **equivalent** to a state t_0 of transition system T iff there **exists** a bisimulation between the initial states s_0 and t_0 .

Example of Bisimulation

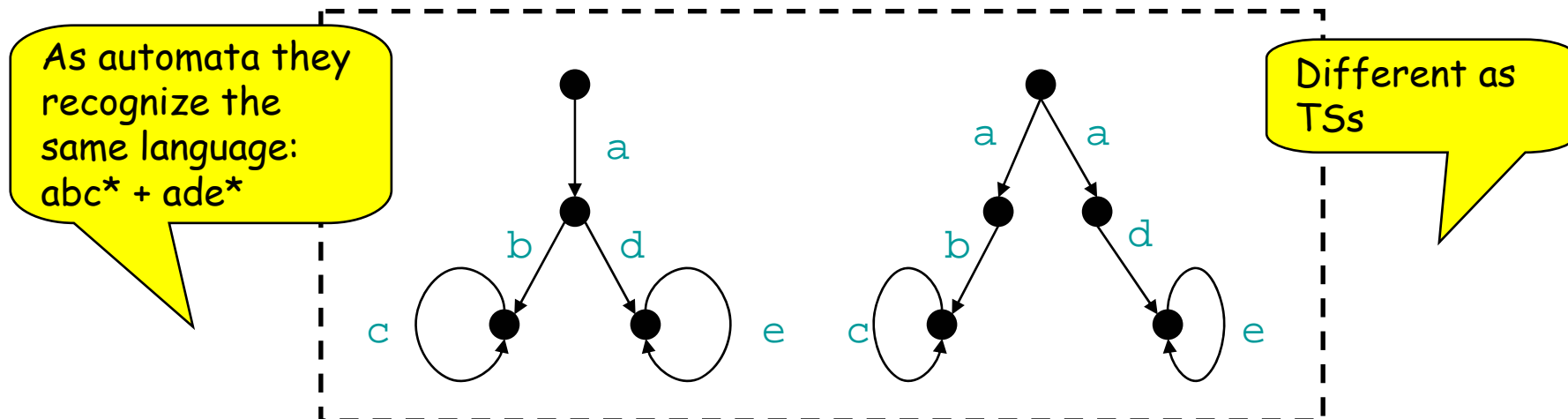


Example of Bisimulation



Automata vs. Transition Systems

- Automata
 - define sets of runs (or traces or strings): (finite) length sequences of actions
- TSs
 - ... but I can be interested also in the alternatives "encountered" during runs, as they represent client's "choice points"



Logics of Programs

- Are modal logics that allow to describe properties of transition systems
- Examples:
 - HennessyMilner Logic
 - Propositional Dynamic Logics
 - Modal (Propositional) Mu-calculus
- Perfectly suited for describing transition systems: they can tell apart transition systems modulo bisimulation

HennesyMilner Logic

- $\Phi := P$ | *(atomic propositions)*
 $\neg \Phi$ | $\Phi_1 \wedge \Phi_2$ | $\Phi_1 \vee \Phi_2$ | *(closed under boolean operators)*
 $[a]\Phi$ | $\langle a \rangle \Phi$ *(modal operators)*
- Propositions are used to denote final states
- $\langle a \rangle \Phi$ means there *exists* an a -transition that leads to a *state where Φ holds*; i.e., expresses the capability of executing action a bringing about Φ
- $[a]\Phi$ means that *all* a -transitions lead to states where Φ holds; i.e., express that executing action a brings about Φ

Logics of Programs: Examples

- Usefull abbreviation:
 - $\langle \text{any} \rangle \Phi$ stands for $\langle a_1 \rangle \Phi \vee \dots \vee \langle a_n \rangle \Phi$
 - $[\text{any}] \Phi$ stands for $[a_1] \Phi \wedge \dots \wedge [a_n] \Phi$
 - $\langle \text{any} - a_1 \rangle \Phi$ stands for $\langle a_2 \rangle \Phi \vee \dots \vee \langle a_v \rangle \Phi$
 - $[\text{any} - a_1] \Phi$ stands for $[a_2] \Phi \wedge \dots \wedge [a_v] \Phi$
- Examples:
 - $\langle a \rangle \text{true}$ *cabability of performing action a*
 - $[a] \text{false}$ *inability of performing action a*
 - $\neg \text{Final} \langle \text{any} \rangle \text{true} \wedge [\text{any} - a] \text{false}$
*necessity/inevitability of performing action a
i.e., action a is the only action possible*
 - $\neg \text{Final} \wedge [\text{any}] \text{false}$ *deadlock!*

Propositional Dynamic Logic

- $\Phi := P$ | *(atomic propositions)*
 $\neg \Phi$ | $\Phi_1 \wedge \Phi_2$ | $\Phi_1 \vee \Phi_2$ | *(closed under boolean operators)*
 $[r]\Phi$ | $\langle r \rangle \Phi$ | *(modal operators)*
- $r := a$ | $r_1 + r_2$ | $r_1; r_2$ | r^* | $P?$ | *(complex actions as regular expressions)*
- Essentially add the capability of expressing partial correctness assertions via formulas of the form
 - $\Phi_1 \rightarrow [r]\Phi_2$ | *under the conditions Φ_1 , all possible executions of r that terminate reach a state of the TS where Φ holds*
- Also add the ability of asserting that a property holds in all nodes of the transition system
 - $[(a_1 + \dots + a_n)^*]\Phi$ | *in every reachable state of the TS Φ holds*
- Useful abbreviations:
 - a stands for $(a_1 + \dots + a_n)$ | *- observe that $+$ can be expressed in HM Logic*
 - u stands for any^* | *- this is the so called master/universal modality*

Modal Mu-Calculus

- $\Phi := P$ | *(atomic propositions)*
 $\neg \Phi$ | $\Phi_1 \wedge \Phi_2$ | $\Phi_1 \vee \Phi_2$ | *(closed under boolean operators)*
 $[r]\Phi$ | $\langle r \rangle \Phi$ | *(modal operators)*
 $\mu X. \Phi(X)$ | $\nu X. \Phi(X)$ | *(fixpoint operators)*
- It is the most expressive logic of the family of logics of programs.
- It subsumes
 - PDL (modalities involving complex actions are translated into formulas involving fixpoints)
 - LTL (linear time temporal logic),
 - CTS, CTS* (branching time temporal logics)
- Examples:
- $[any^*]\Phi$ can be expressed as $\nu X. \Phi \wedge [any]X$
- $\mu X. \Phi \vee [any]X$ | *along all runs eventually Φ*
- $\mu X. \Phi \vee \langle any \rangle X$ | *along some run eventually Φ*
- $\nu X. [a](\mu Y. \langle any \rangle true \wedge [any-b]Y) \wedge X$ | *every run that contains a contains later b*

Model Checking

- Model checking is polynomial in the size of the TS for
 - HennessyMilner Logic
 - PDL
 - Mu-Calculus
- Also model checking is wrt the formula
 - Polynomial for HennessyMiner Logic
 - Polynomial for PDL
 - Polynomial for Mu-Calculus with bounded alternation of fixpoints and $NP \cap coNP$ in general

Model Checking

- Given a TS T , one of its states s , and a formula Φ verify whether the formula holds in s . Formally:

$$T, s \models \Phi$$

- Examples (TS is our vending machine):

- $S_0 \models \text{Final}$

- $S_0 \models \langle 10c \rangle \text{true}$

capability of performing action 10c

- $S_2 \models [\text{big}] \text{false}$

inability of performing action big

- $S_0 \models [10c][\text{big}] \text{false}$

after 10c cannot execute big

- $S_i \models \mu X. \text{Final} \vee [\text{any}] X$

eventually a final state is reached

- $S_0 \models \nu Z. (\mu X. \text{Final} \vee [\text{any}] X) \wedge [\text{any}] Z$ *or equivalently*

- $S_0 \models [\text{any}^*](\mu X. \text{Final} \vee [\text{any}] X)$

from everywhere eventually final

Planning as Model Checking

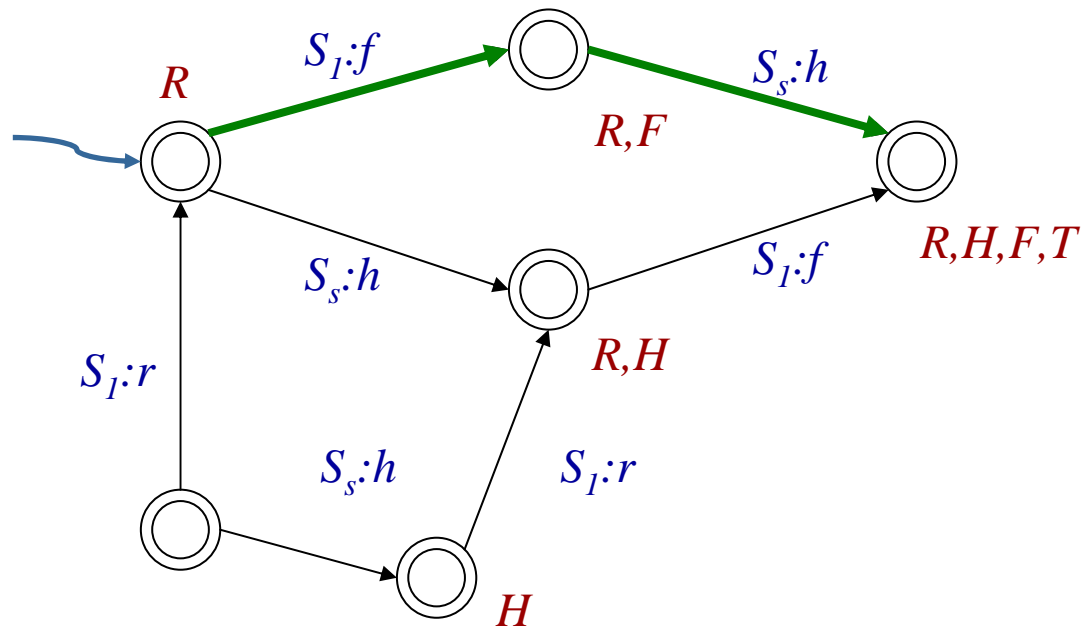
- **Build the TS of the domain:**
 - Consider the set of states formed all possible truth value of the propositions (this works only for propositional setting).
 - Use Pre's and Post of actions for determining the transitions

Note: the TS is exponential in the size of the description.
- **Write the goal in a logic of program**
 - typically a single least fixpoint formula of Mu-Calculus
- **Planning:**
 - model check the formula on the TS starting from the given initial state.
 - use the path (paths) used in the above model checking for returning the plan.
- *This basic technique works only when we have complete information (or at least total observability on state):*
 - *Sequential plans if initial state known and actions are deterministic*
 - *Conditional plans if many possible initial states and/or actions are nondeterministic*

Example

- Operators (Services + Mappings)
 - $\text{Registered} \wedge \neg \text{FlightBooked} \rightarrow [S_1:\text{bookFlight}] \text{FlightBooked}$
 - $\neg \text{Registered} \rightarrow [S_1:\text{register}] \text{Registered}$
 - $\neg \text{HotelBooked} \rightarrow [S_2:\text{bookHotel}] \text{HotelBooked}$
- Additional constraints (Community Ontology):
 - $\text{TravelSettledUp} \equiv \text{FlightBooked} \wedge \text{HotelBooked} \wedge \text{EventBooked}$
- Goals (Client Service Requests):
 - Starting from state
 $\text{Registered} \wedge \neg \text{FlightBooked} \wedge \neg \text{HotelBooked} \wedge \neg \text{EventBooked}$
check $\langle \text{any}^* \rangle \text{TravelSettledUp}$
 - Starting from all states such that
 $\neg \text{FlightBooked} \wedge \neg \text{HotelBooked} \wedge \neg \text{EventBooked}$
check $\langle \text{any}^* \rangle \text{TravelSettledUp}$

Example

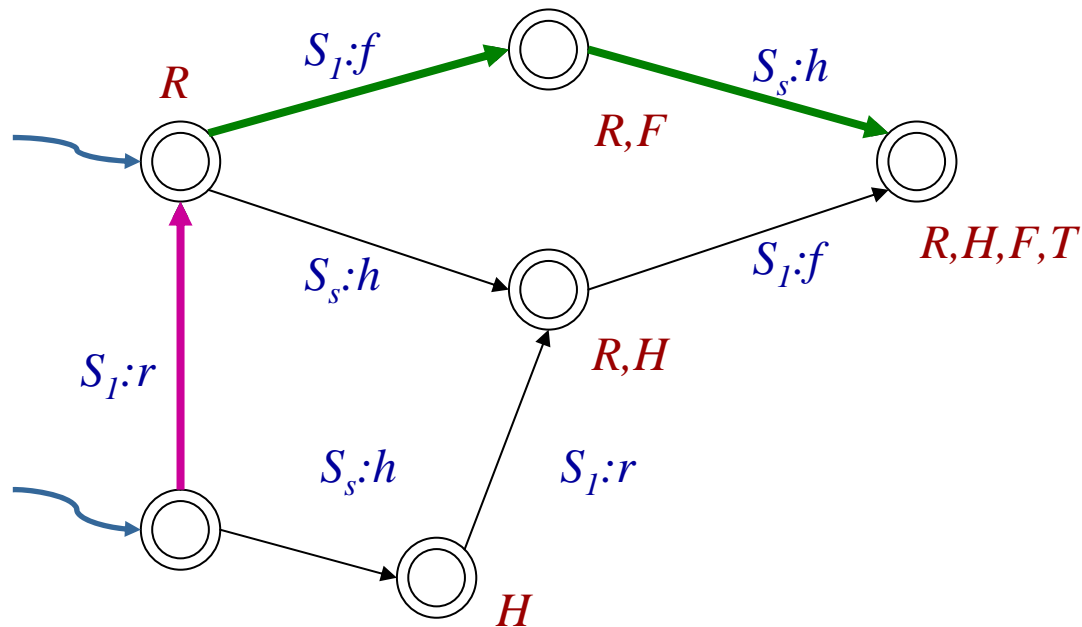


Plan:

S_1 :bookFlight;
 S_2 :bookHotel

Starting from state
Registered $\wedge \neg$ FlightBooked $\wedge \neg$ HotelBooked $\wedge \neg$ EventBooked
check
 $\langle \text{any}^* \rangle$ TravelSettledUp

Example



Plan:

```

if( $\neg$ Registered) {
  S1:register;
}
S1:bookFlight;
S2:bookHotel
    
```

Starting from states where
 \neg FlightBooked \wedge \neg HotelBooked \wedge \neg EventBooked
 check
 \langle any* \rangle TravelSettledUp

Satisfiability

- Observe that a formula Φ may be used to select among all TS T those such that for a given state s we have that $T, s \models \Phi$
- **SATISFIABILITY**: Given a formula Φ verify whether there exists a TS T and a state s such that. Formally:

check whether exists T, s such that $T, s \models \Phi$

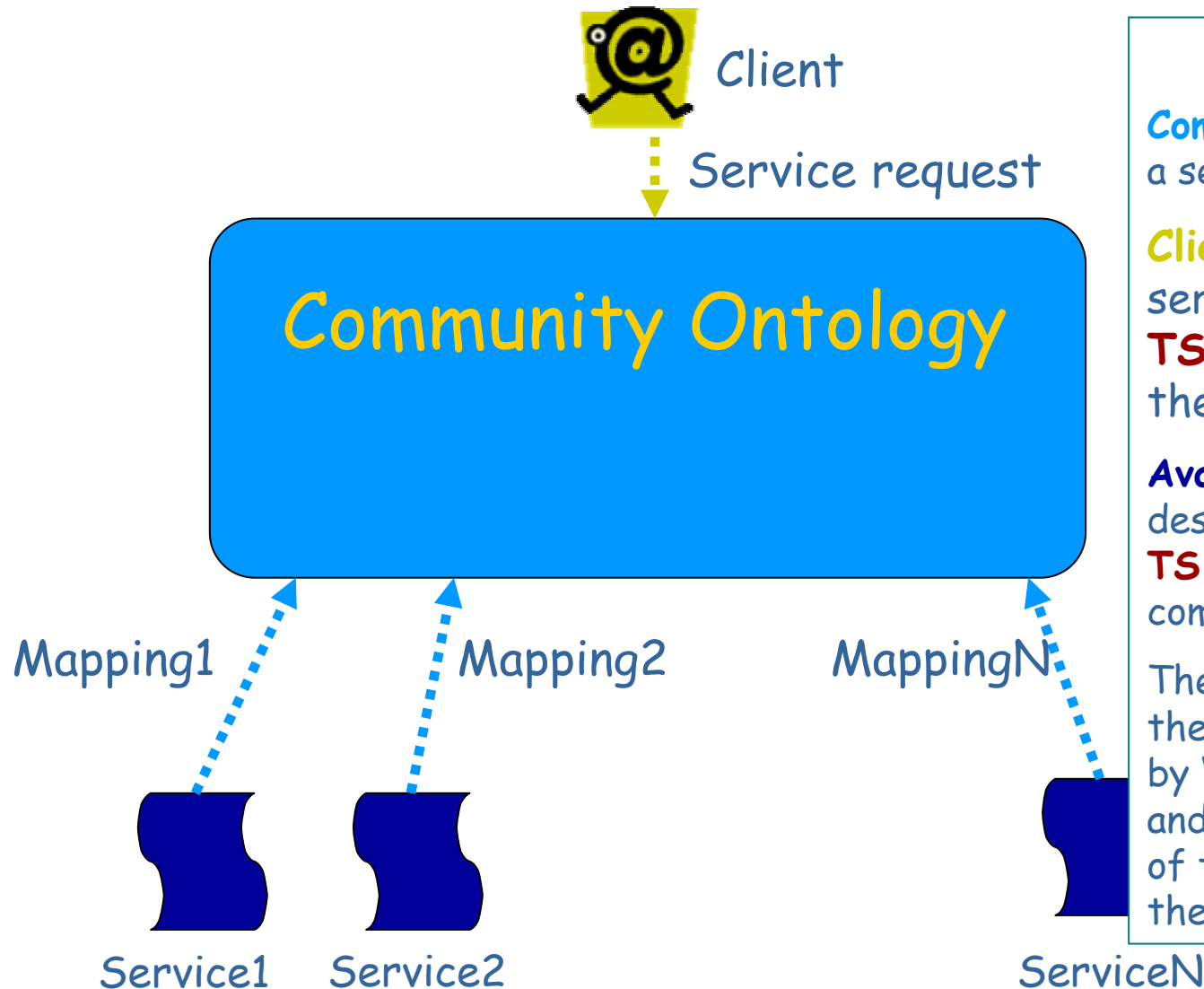
- Satisfiability is:
 - PSPACE for HennessyMilner Logic
 - EXPTIME for PDL
 - EXPTIME for Mu-Calculus

References

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- [Bradfield&Stirling HPA01] J. Bradfield, C. Stirling: Modal logics and mu-calculi. Handbook of Process Algebra, 293-332, Elsevier, 2001.
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- [Vardi etal CAV94] M. Vardi, O. Kupferman and P. Wolper: An Automata-Theoretic Approach to Branching-Time Model Checking (full version of CAV'94 paper).

Composition: the Roman Approach

The Roman Approach



Client-tailored!

Community ontology: just a set of **actions**

Client formulates the service it requires as a **TS** using the **actions** of the common ontology

Available services: described in terms of a **TS** using **actions** of the community ontology

The **community** realizes the **client's target service** by "reversing" the mapping and hence using **fragments** of the computation of the **available services**

Community of Services

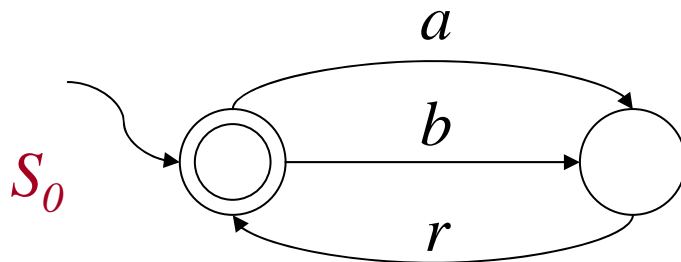
- A **community** of Services is
 - a **set** of services ...
 - ... that share implicitly a *common understanding* on a **common set of actions** (common ontology limited to the alphabet of actions)...
 - ... and export their **behavior** using (finite) **TS** over this **common set of actions**
- A **client** specifies needs as a service behavior, i.e, a (finite) **TS** using the **common set of actions** of the community

(Target & Available) Service TS

- We model *services* as finite TS $T = (\Sigma, S, s^0, \delta, F)$ with
 - **single initial state** (s^0)
 - **deterministic transitions** (i.e., δ is a partial function from $S \times \Sigma$ to S)

Note: In this way the client entirely controls/chooses the transition to execute

Example:



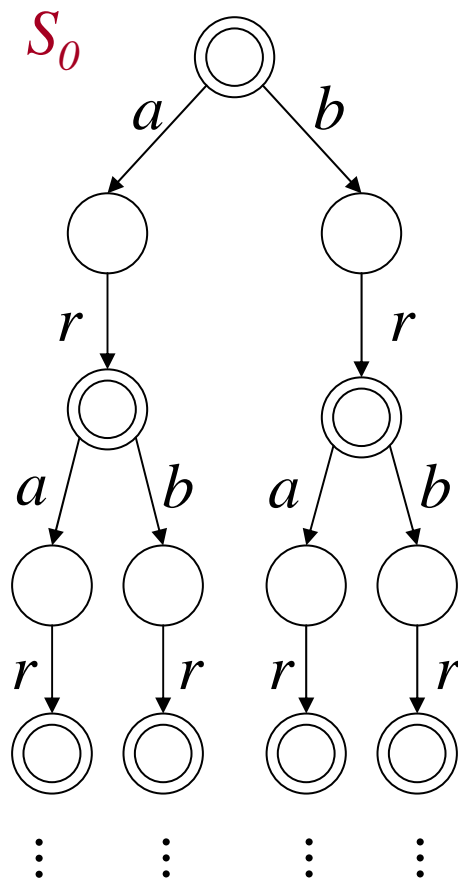
a: "search by author (and select)"

b: "search by title (and select)"

r: "listen (the selected song)"

Service Execution Tree

By "unfolding" a (finite) TS one gets an (infinite) **execution tree**
-- yet another (infinite) TS which bisimilar to the original one)



- **Nodes:** *history (sequence) of actions executed so far*
- **Root:** *no action yet performed*
- **Successor node $x \cdot a$ of x :** *action a can be executed after the sequence of action x*
- **Final nodes:** *the service can terminate*

Formalizing Service Composition

Composition:

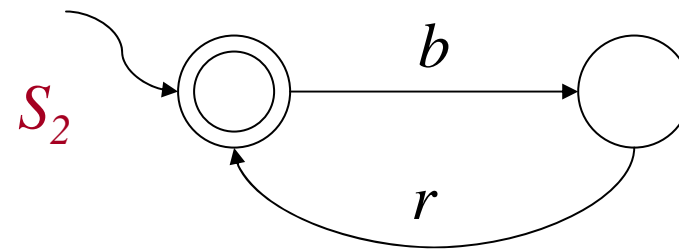
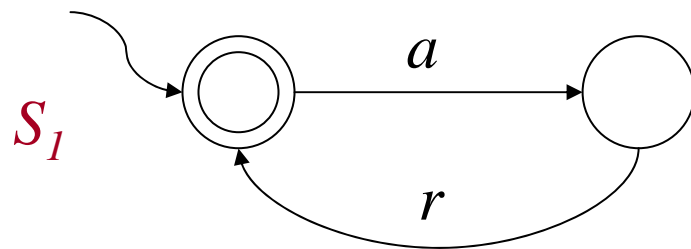
- coordinating program ...
- ... that realizes the target service ...
- ... by suitably coordinating available services

⇒ Composition can be formalized as:

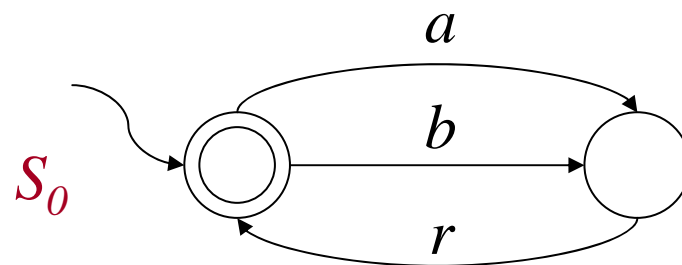
- a labeling of the execution tree of the target service such that ...
- ... each action in the execution tree is labeled by the community service that executes it ...
- ... and each possible sequence of actions on the target service execution tree corresponds to possible sequences of actions on the community service execution trees, suitably interleaved

Example of Composition (1)

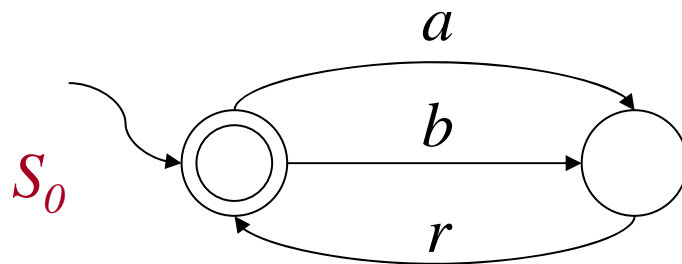
- Community services



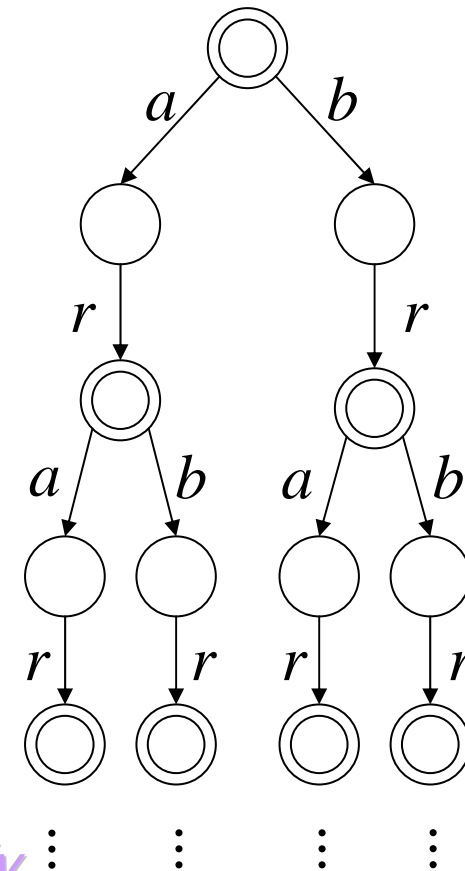
- Target service



Example of Composition (2)



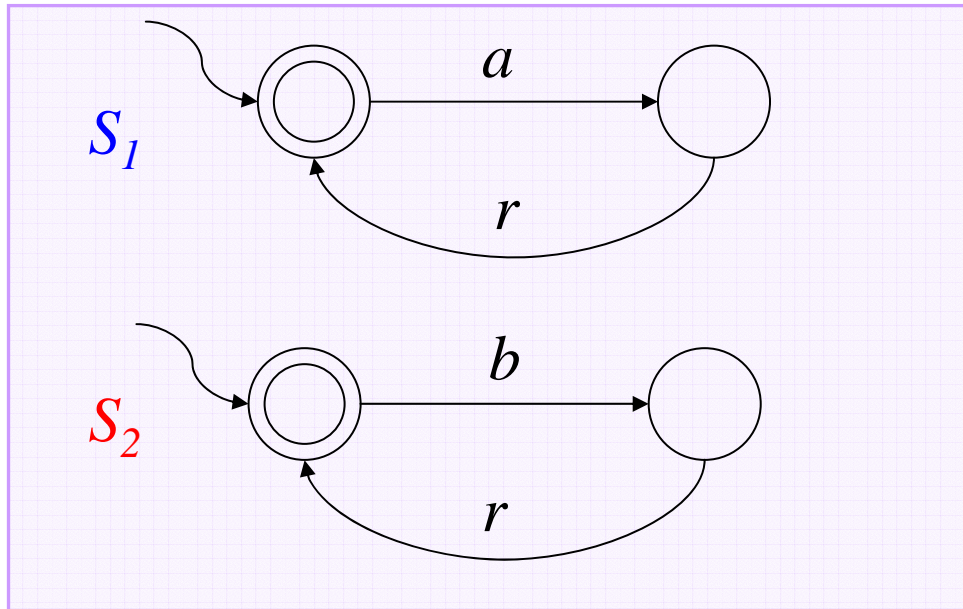
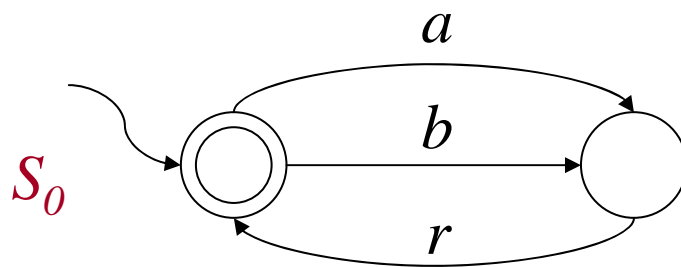
Execution tree of S_0



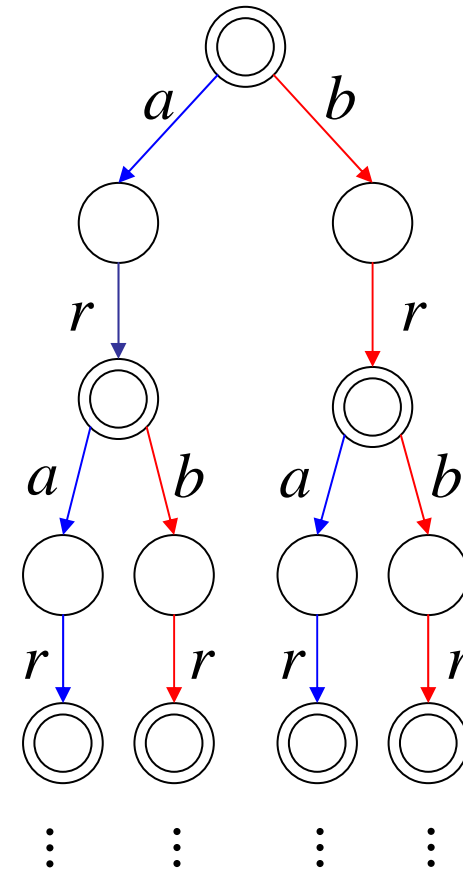
Note: we cannot label the target service TS directly ...

... we need to label the execution tree

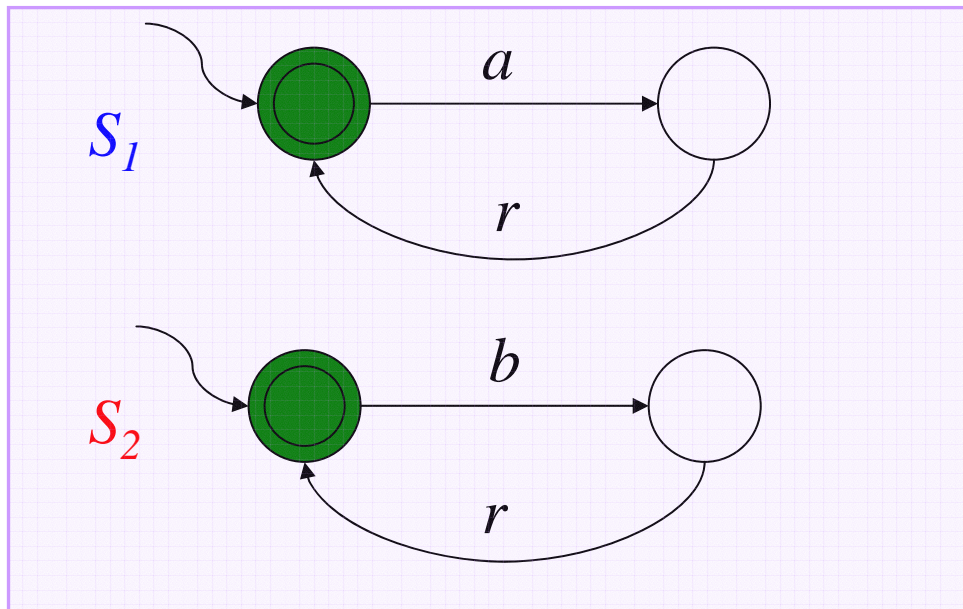
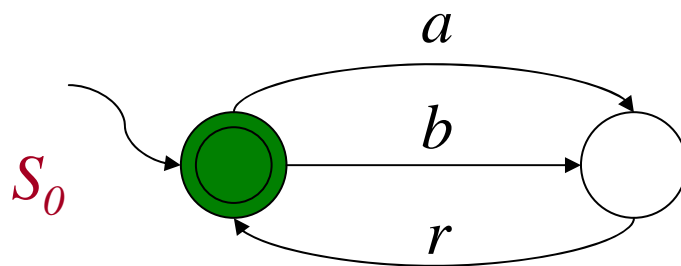
Example of Composition (3)



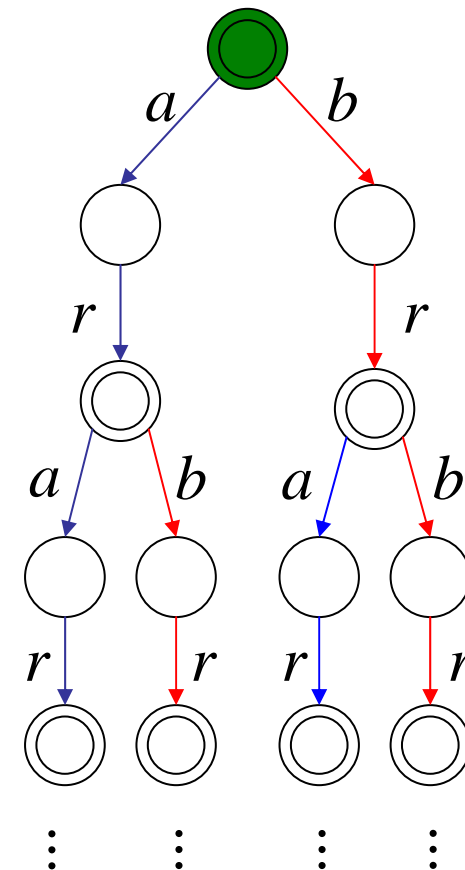
$$S_0 = \text{orch}(S_1 \parallel S_2)$$



Example of Composition (4)

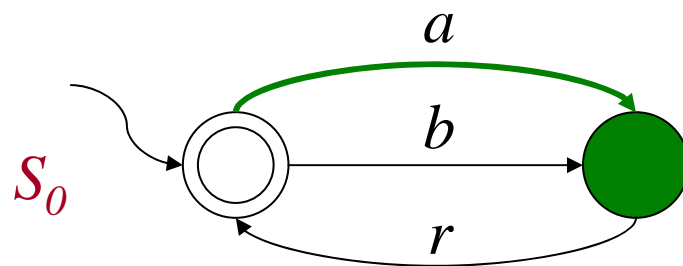


$$S_0 = \text{orch}(S_1 \parallel S_2)$$

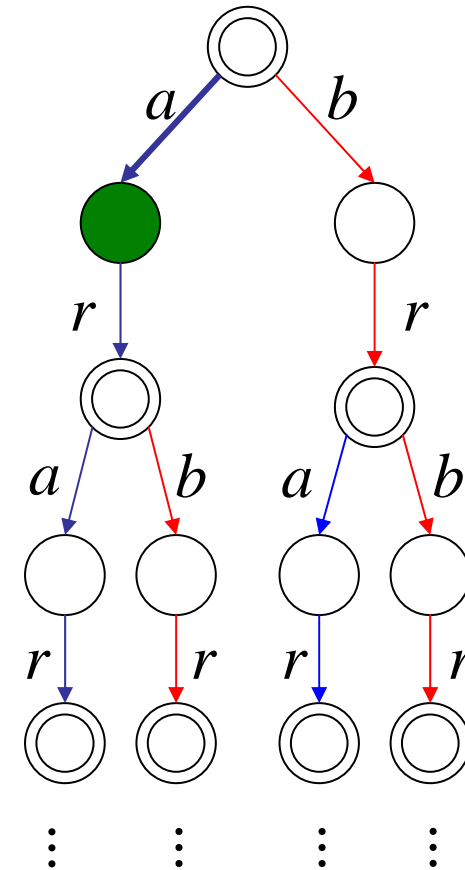
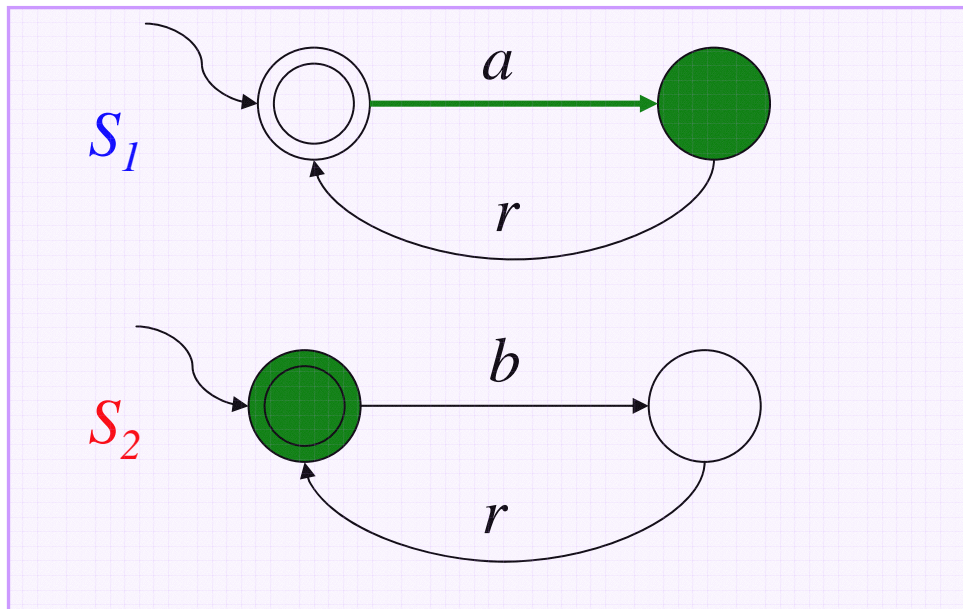


All services start from their starting state

Example of Composition (5)

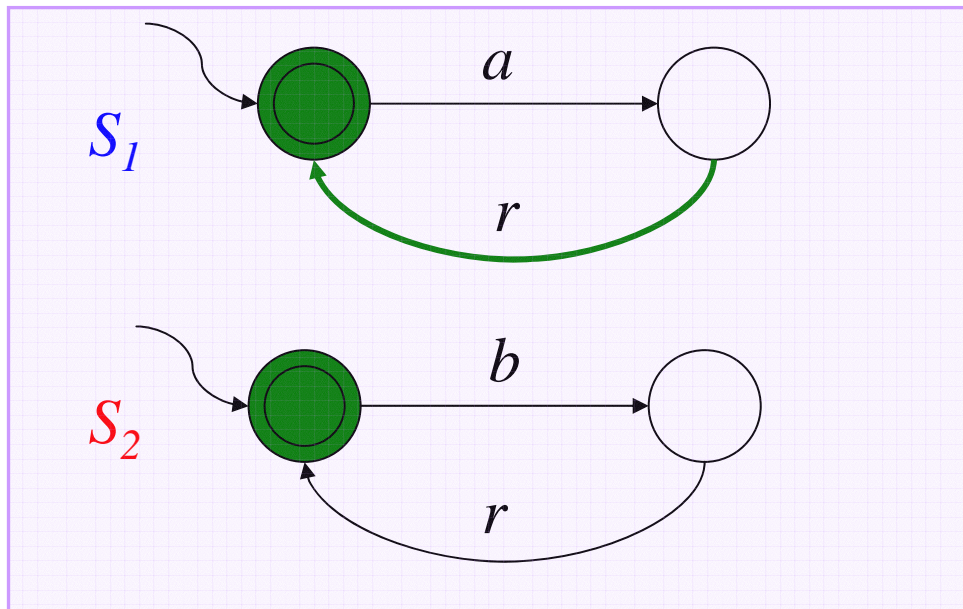
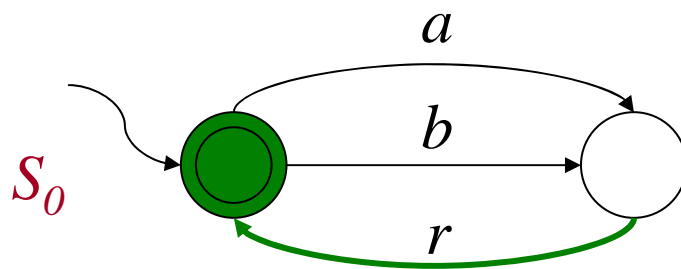


$$S_0 = \text{orch}(S_1 \parallel S_2)$$

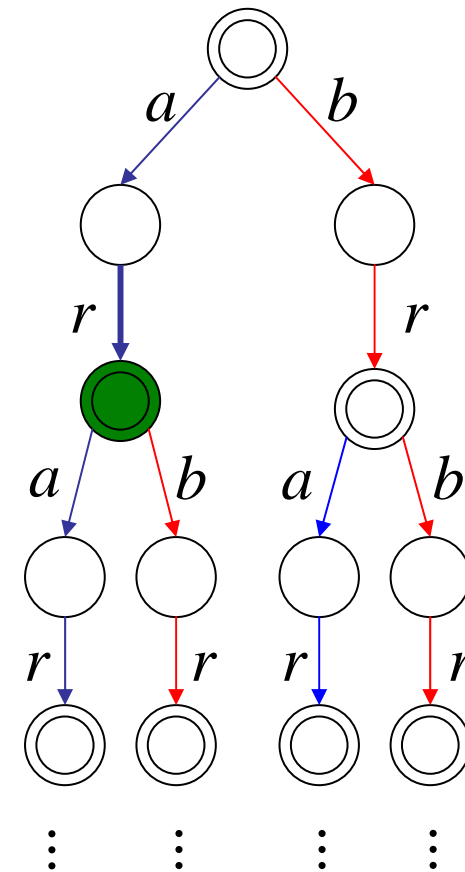


Each action of the target service is executed by at least one of the component services

Example of composition (6)

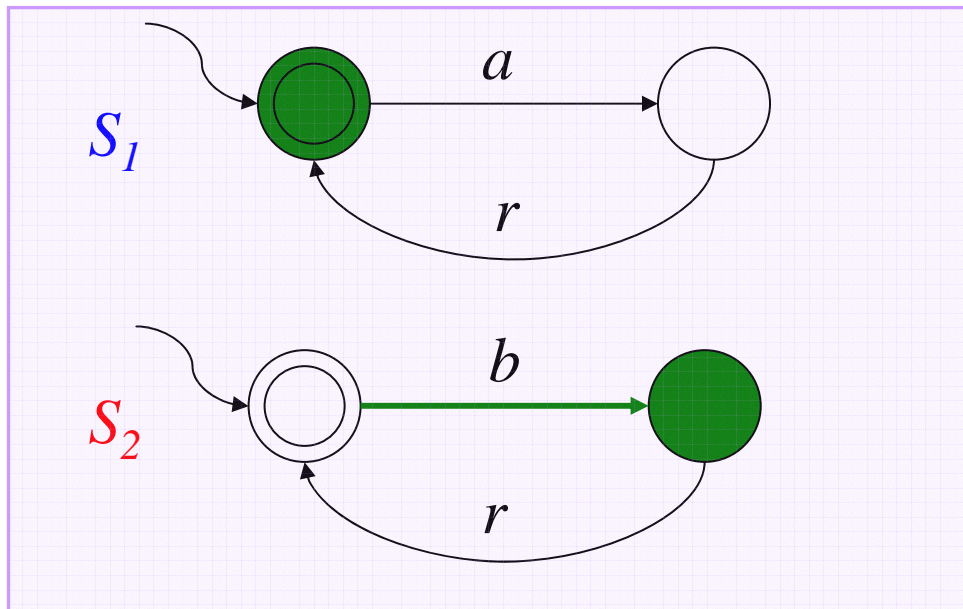
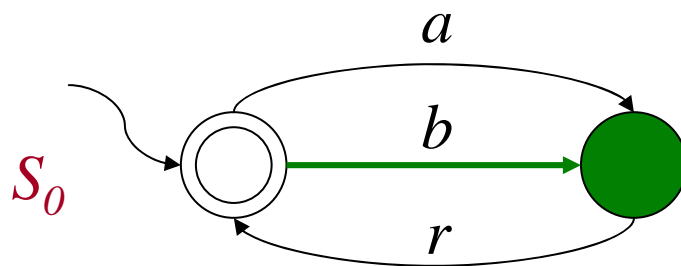


$$S_0 = \text{orch}(S_1 \parallel S_2)$$

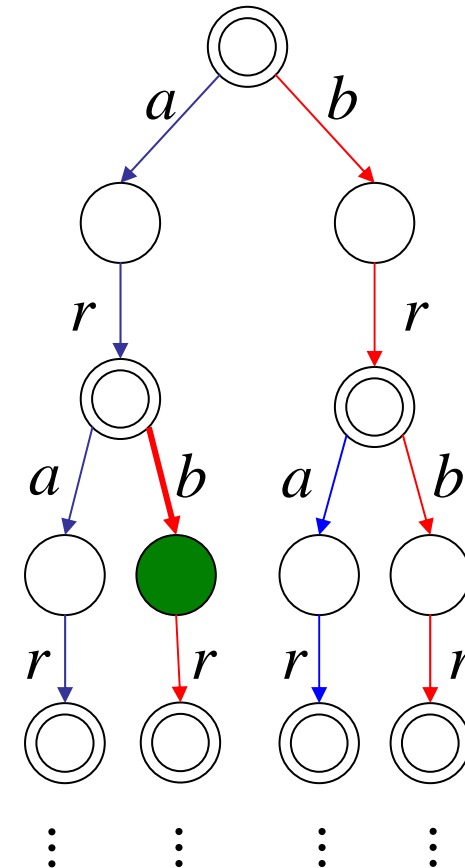


When the target service can be left, then all component services must be in a final state

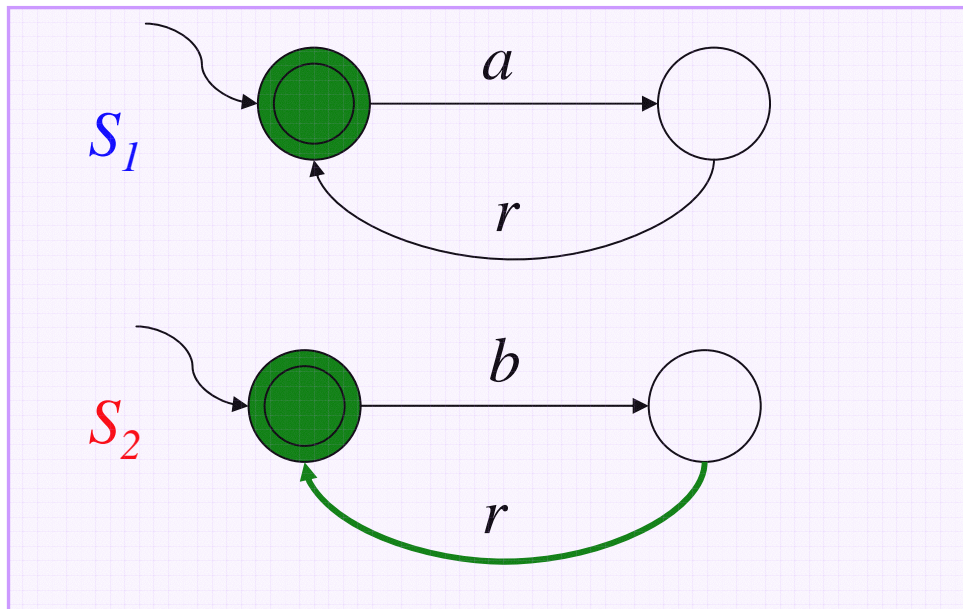
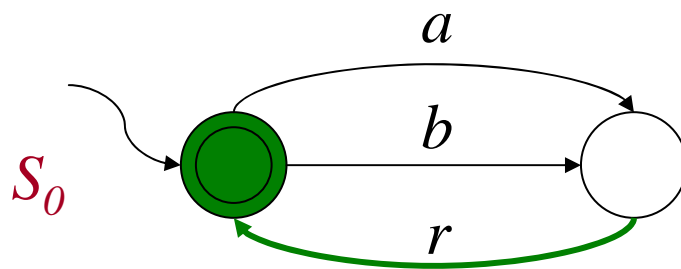
Example of composition (7)



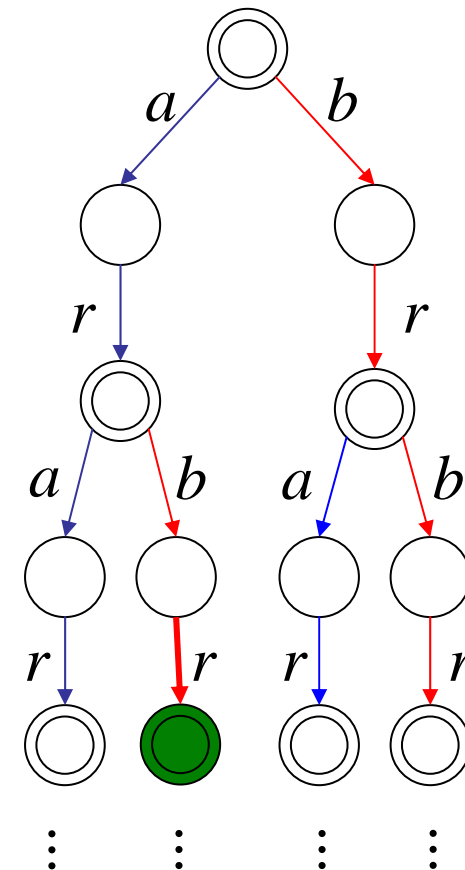
$$S_0 = \text{orch}(S_1 \parallel S_2)$$



Example of composition (8)

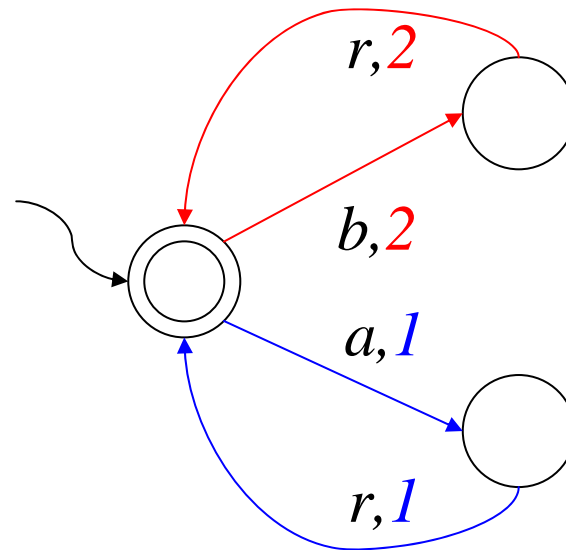


$$S_0 = \text{orch}(S_1 \parallel S_2)$$



Observation

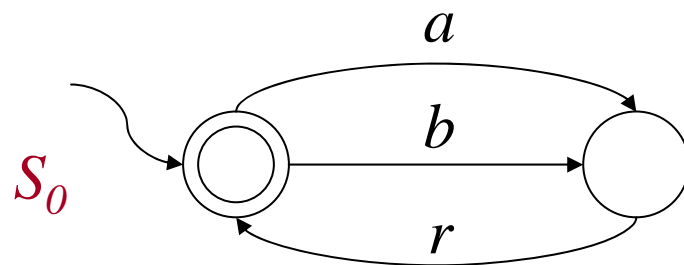
- This labeled execution tree has a finite representation as a finite TS ...
- ...with transitions labeled by an **action** and the **service** performing the action



Is this always the case when we deal with services expressible as finite TS? See later...

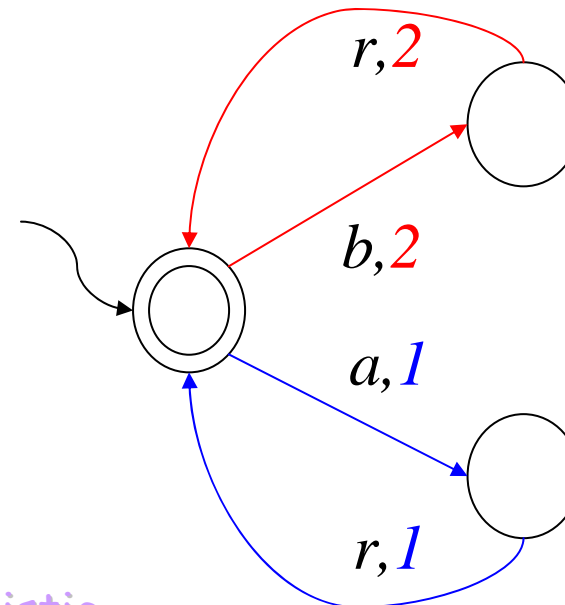
TS for Services and TS for Composition

Finite TS for services



- Deterministic
- Transitions labeled by actions
- Output on state to signal when final

Finite TS for composition



- Deterministic
- Transitions labeled by actions and services
- Output on transition to signal which service

Questions

Assume services of community and target service are finite TSs

- Can we always check composition existence?
- If a composition exists there exists one which is a finite TS?
- If yes, how can a finite TS composition be computed?

To answer we exploit PDL SAT

Answers

Reduce service composition synthesis to satisfiability in (deterministic) PDL

- Can we always check composition existence?
Yes, SAT in PDL is decidable in EXPTIME
- If a composition exists there exists one which is a finite TS?
Yes, by the small model property of PDL
- How can a finite TS composition be computed?
From a (small) model of the corresponding PDL formula

Structure of the PDL Encoding

$$\Phi = \text{Init} \wedge [u](\Phi_0 \wedge \bigwedge_{i=1, \dots, n} \Phi_i \wedge \Phi_{\text{aux}})$$

Initial states of all
services

PDL encoding of
target service

PDL encoding of i -
th component
service

PDL additional
domain-
independent
conditions

PDL encoding is polynomial in the size of the service TSSs

PDL Encoding

- Target service $S_0 = (\Sigma, S_0, s^0_0, \delta_0, F_0)$ in PDL we define Φ_0 as the conjunction of:
 - $s \rightarrow \neg s'$ for all pairs of distinct states in S_0
service states are pair-wise disjoint
 - $s \rightarrow \langle a \rangle T \wedge [a]s'$ for each $s' = \delta_0(s, a)$
target service can do an a-transition going to state s'
 - $s \rightarrow [a] \perp$ for each $\delta_0(s, a)$ undef.
target service cannot do an a-transition
 - $F_0 \equiv \bigvee_{s \in F_0} s$
denotes target service final states
- ...

PDL Encoding (cont. d)

- Community services $S_i = (\Sigma, S_i, s^0_i, \delta_i, F_i)$ in PDL we define Φ_i as the conjunction of:
 - $s \rightarrow \neg s'$ for all pairs of distinct states in S_i
Service states are pair-wise disjoint
 - $s \rightarrow [a](\text{moved}_i \wedge s' \vee \neg \text{moved}_i \wedge s)$ for each $s' = \delta_i(s, a)$
if service moved then new state, otherwise old state
 - $s \rightarrow [a](\neg \text{moved}_i \wedge s)$ for each $\delta_i(s, a)$ undef.
if service cannot do a, and a is performed then it did not move
 - $F_i \equiv \bigvee_{s \in F_i} s$
denotes community service final states
- ...

PDL Encoding (cont. d)

- Additional assertions Φ_{aux}
 - $\langle a \rangle T \rightarrow [a] \bigvee_{i=1, \dots, n} moved_i$ for each action a
at least one of the community services must move at each step
 - $F_0 \rightarrow \bigwedge_{i=1, \dots, n} F_i$
when target service is final all comm. services are final
 - $Init \equiv s_0^0 \wedge_{i=1, \dots, n} s_i^0$
Initially all services are in their initial state

PDL encoding: $\Phi = Init \wedge [u](\Phi_0 \wedge_{i=1, \dots, n} \Phi_i \wedge \Phi_{aux})$

Results

Thm: Composition exists iff PDL formula Φ SAT

From composition labeling of the target service one can build a tree model of the PDL formula and viceversa

Information on the labeling is encoded in predicates moved;

\Rightarrow Composition existence of services expressible as finite TS is decidable in EXPTIME

Results on TS Composition

Thm: If composition exists then finite TS composition exists.

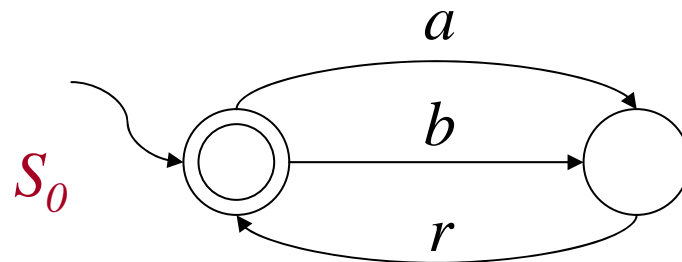
*From a small model of the PDL formula Φ ,
one can build a finite TS machine*

*Information on the output function of the machine is encoded in
predicates moved;*

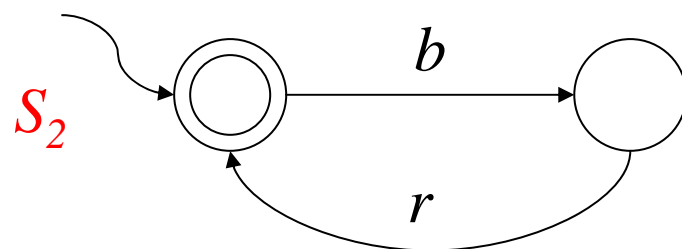
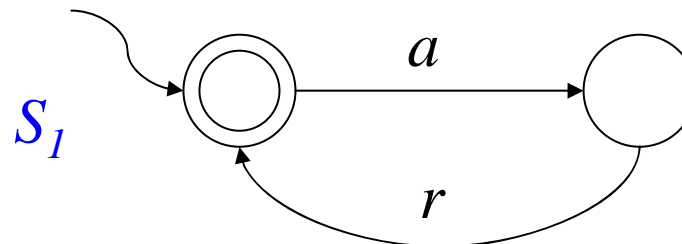
⇒ finite TS composition existence of services
expressible as finite TS is decidable in EXPTIME

Example (1)

Target service



Community services



DPDL

...
...
...

$$s_0^0 \wedge s_1^0 \wedge s_2^0$$

$$\langle a \rangle T \rightarrow [a] (\text{moved}_1 \vee \text{moved}_2)$$

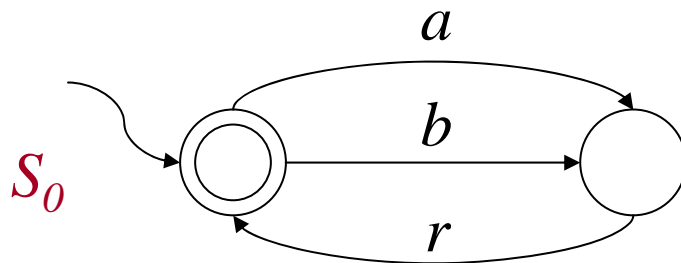
$$\langle b \rangle T \rightarrow [b] (\text{moved}_1 \vee \text{moved}_2)$$

$$\langle r \rangle T \rightarrow [r] (\text{moved}_1 \vee \text{moved}_2)$$

$$F_0 \rightarrow F_1 \wedge F_2$$

Example (2)

Target service



$$s_0^0 \rightarrow \neg s_0^1$$

$$s_0^0 \rightarrow \langle a \rangle \top \wedge [a] s_0^1$$

$$s_0^0 \rightarrow \langle b \rangle \top \wedge [b] s_0^1$$

$$s_0^1 \rightarrow \langle r \rangle \top \wedge [r] s_0^0$$

$$s_0^0 \rightarrow [r] \perp \wedge [r] s_0^0$$

$$s_0^1 \rightarrow [a] \perp$$

$$s_0^1 \rightarrow [b] \perp$$

$$F_0 \equiv s_0^0$$

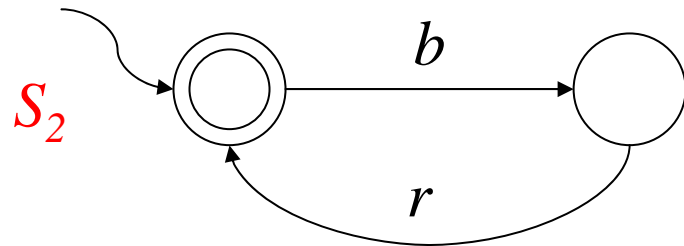
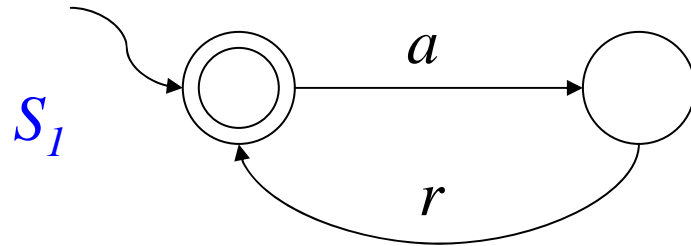
...

...

...

Example (3)

Community services



...

$$s_1^0 \rightarrow \neg s_1^1$$

$$s_1^0 \rightarrow [a] (\text{moved}_1 \wedge s_1^1 \vee \neg \text{moved}_1 \wedge s_1^0)$$

$$s_1^0 \rightarrow [r] \neg \text{moved}_1 \wedge s_1^0$$

$$s_1^1 \rightarrow [b] \neg \text{moved}_1 \wedge s_1^1$$

$$s_1^1 \rightarrow [a] \neg \text{moved}_1 \wedge s_1^1$$

$$s_1^1 \rightarrow [b] \neg \text{moved}_1 \wedge s_1^1$$

$$s_1^1 \rightarrow [r] (\text{moved}_1 \wedge s_1^0 \vee \neg \text{moved}_1 \wedge s_1^0)$$

$$F_1 \equiv s_1^0$$

$$s_2^0 \rightarrow \neg s_2^1$$

$$s_2^0 \rightarrow [b] (\text{moved}_2 \wedge s_2^1 \vee \neg \text{moved}_2 \wedge s_2^0)$$

$$s_2^0 \rightarrow [r] \neg \text{moved}_2 \wedge s_2^0$$

$$s_2^0 \rightarrow [a] \neg \text{moved}_2 \wedge s_2^0$$

$$s_2^1 \rightarrow [b] \neg \text{moved}_2 \wedge s_2^1$$

$$s_2^1 \rightarrow [a] \neg \text{moved}_2 \wedge s_2^1$$

$$s_2^1 \rightarrow [r] (\text{moved}_2 \wedge s_2^0 \vee \neg \text{moved}_2 \wedge s_2^0)$$

$$F_2 \equiv s_2^0$$

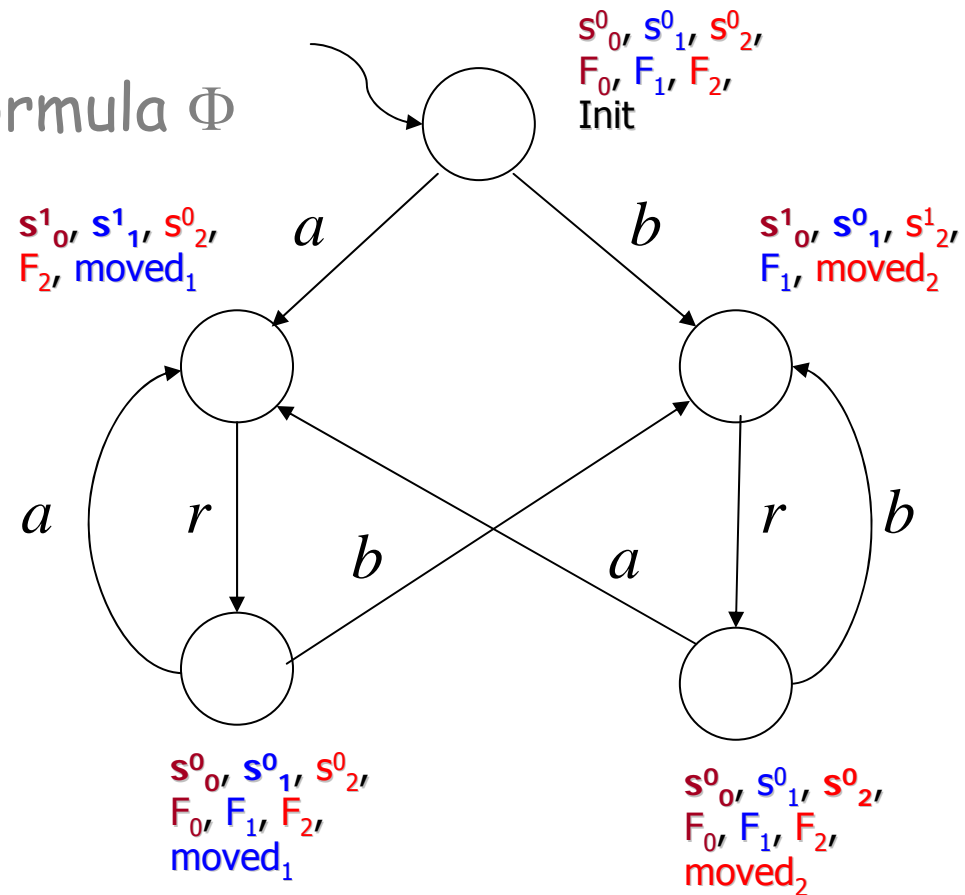
...

Example (4)

Check: run SAT on PDL formula Φ

Example

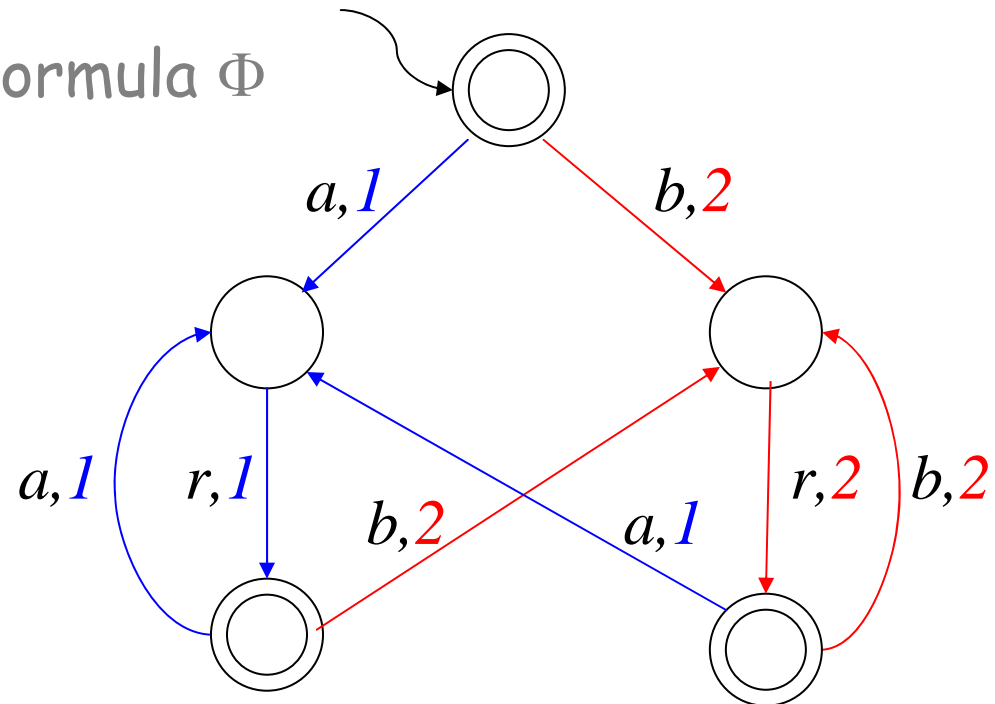
Check: run SAT on PDL formula Φ
Yes \Rightarrow (small) model



Example

Check: run SAT on PDL formula Φ
Yes \Rightarrow (small) model

\Rightarrow extract finite TS



Example

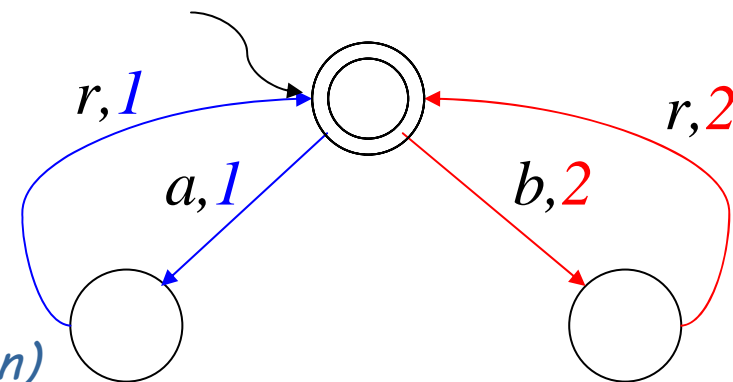
Check: run SAT on PDL formula Φ

Yes \Rightarrow (small) model

\Rightarrow extract finite TS

\Rightarrow minimize finite TS

(similar to Mealy machine minimization)



Results on Synthesizing Composition

- Using PDL reasoning algorithms based on model construction (cf. tableaux), build a (small) model
Exponential in the size of the PDL encoding/services finite TS
Note: SitCalc, etc. can compactly represent finite TS, PDL encoding can preserve compactness of representation
- From this model extract a corresponding finite TS
Polynomial in the size of the model
- Minimize such a finite TS using standard techniques (opt.)
Polynomial in the size of the TS
Note: finite TS extracted from the model is not minimal because encodes output in properties of individuals/states

Tools for Synthesizing Composition

- In fact we use only a fragment of PDL in particular we use fixpoint (transitive closure) only to get the universal modality ...
- ... thanks to a tight correspondence between PDLs and Description Logics (DLs), we can use current highly optimized DL reasoning systems to do synthesis ...
- ... when the ability of returning models will be added ...
- ... meanwhile we have developed a prototype tool on this idea (see ESC - E-Service Composer:
<http://sourceforge.net/projects/paride>)

Extensions (1)

- **Loose specification of target service**
 - target service "under-specified"
 - the client delegates the composer to resolve certain choices

Note: angelic nondeterminism

- **Interaction between services without client involvement**
 - A component service may initiate an interaction with another component service to get to a certain state
 - Client specifies when during the computation this is allowed and to what extent

Note: again angelic nondeterminism

See ICSOC04

Extensions (2)

- Incomplete specification of services of the community
 - Component services export their behavior as nondeterministic TS (also related to **data acquisition**) ...

Note: diabolic nondeterminism
 - ...the transitions are not completely under the control of the client nor of the orchestrator ...
 - ... composition has to work in spite of choices made by component services
 - Two possible assumptions
 1. Orchestrator **can observe** state reached by component service
 2. Orchestrator **cannot fully observe** state reached by component service

For 1, variants of the technique shown here still apply
- work in progress

For 2, most likely techniques based on automata on infinite trees are needed – see Vardi's work on process synthesis

References

Roman Group

- *See above*

Process Synthesis

[Vardi&Kupferman ICTL97] M. Vardi, O. Kupferman: Synthesis with Incomplete Information (full version of ICTL'97).

[Vardi CAV95] M. Vardi, An Automata-Theoretic Approach to Fair Realizability and Synthesis. CAV 1995.

[Vardi&Kupferman MFCS2000] M. Vardi, O. Kupferman: Mu-calculus Synthesis. MFCS 2000

[Kupferman & Vardi LCS01] Orna Kupferman, Moshe Y. Vardi: Synthesizing Distributed Systems. Logic in Computer Science, 2001.

Description Logics and relationship with Logic of Programs

[BCMNS2003] F. Baader, D. Calvanese, D. L. McGuinness, D. Nardi, P. F. Patel-Schneider: The Description Logic Handbook: Theory, Implementation, and Applications Cambridge University Press 2003

[Calvanese et al HAR01] D. Calvanese, G. De Giacomo, M. Lenzerini, D. Nardi: Reasoning in Expressive Description Logics. Handbook of Automated Reasoning 2001: 1581-1634

Recent evolution of the Roman Approach: COLOMBO Project

(joint work with Rick Hull)

- Integrates ideas from
 - Hull's Conversation Model: Messages
 - OWL-S: "Semantics" & Data
 - Roman Model: Composition by "Synthesis"into a single approach.

COLOMBO Project (1)

- A model that combines
 - Impact on "real world": OWL-S atomic process
 - Incorporate explicit database manipulations
 - Message passing: WSDL and other standards
 - Process model inside web service: FSM-based, as in Roman and Conversation models
- Composition synthesis results, similar in spirit to the Roman results
 - For our first results, willing to impose many restrictions
 - Hopefully, can generalize the results in subsequent research

COLOMBO Project (2)

- Real world modeled by keyed relations
- Atomic Processes modeled after OWL-S
 - Atomic Process can read/write selected world relations
- Web Service: Guarded automaton
 - Local store (with scalars)
 - Transitions have conditions based on local store
 - Transitions have actions:
 - Atomic Process
 - Send message
 - Receive message
 - Ports (reminiscent of WSDL)
- System: family of web services, with linkage
 - Instantaneous description, $(id, I) \vdash (id', I')$
 - Execution tree
- Focus on
 - Client request is the realization of a given target service
 - Web services drawn from pre-existing set (UDDI directory)
 - Client-tailored approach

Conclusions

Summary

- Review of relevant technologies
- Distinction between orchestration and choreography
- Relevance of transition systems for abstracting over technologies
- State of the art in service composition
- Automatic composition: a basic research view
- Transition systems and formal systems for verification and synthesis
- In-depth analysis of a particular approach

What to Bring Home

- Composition is not Choreography
 - Composition: we are starting to understand*
 - Choreography: still needs to be developed*
- Relevance of Transition Systems
 - Don't confuse with language-theoretic automata*
- Relevance of Data Integration
 - If you are involved with information-based services, study data integration literature*
 - If you are not involved, look at it anyway, e.g., GAV and LAV*
- Relevance of Planning
 - If you can afford to have clients not driving the control flow, planning has a lot to say*
 - If not, planning doesn't directly apply, but has a lot to say anyway (it is a rich area)*
- Relevance of Process Verification and Synthesis
 - Full potential still largely unexplored*

Having clients driving the control flow of the synthesized process is a new kind of need that is completely specific of a service composition