

Your platform: Erratic Robot

Imagine to control a mobile wheeled robot (e.g. an Erratic robot) within an indoor environment.

The type of actions that the robot can perform concerns the navigation within the environment.

The robot can execute the following actions:

- ***Moving***
 - Go near the commode of the lounge
 - Enter the laundry room
 - Move to the right of the dresser
- ***Bringing***
 - Bring the towel to the bathroom
- ***Finding***
 - Find the printer
 - Search for the address book
- ***Releasing***
 - Put the knife on the table of the kitchen
 - Drop the bottle in the garage
- ***Taking***
 - Take the remote controller
 - Take the newspaper in the dining room
- ***Inspecting***
 - Check if the kitchen is clean
 - Check if the door of the dining room is open

