Optimization Methods for Machine Learning Decomposition methods for RBF networks

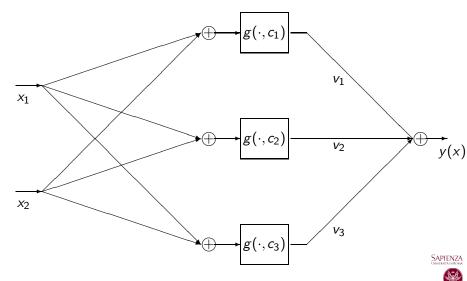
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Via Ariosto 25





Supervised selection of the centers

Step 1. (Minimization with respect to weights v)

Compute v^{k+1} solving LLSQ



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Set

$$\widehat{c}^{k+1} = \begin{cases} c^k & \text{if } \|\nabla_c E(c^k, v^{k+1})\| \leq \xi_2^k \end{cases}$$

 ξ_2^k decreasing tolerance $\xi_2^{k+1} \leq \theta \xi_2^k$



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with η^k by an Armijo lineseach

$$E(v^{k+1}, c^k + \eta^k d^k) \le E(v^{k+1}, c^k) - \gamma \eta^k \| \nabla_c E(v^{k+1}, c^k) \|^2$$



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with η^{k} by an Armijo lineseach $E_{ref} = E(v^{k+1}, c^{k} + \eta^{k}d^{k})$ allow more freedom Set c^{k+1} : $E(c^{k+1}, v^{k+1}) \leq E_{ref}$



PIENZA

Convergence of Two-block decompositions in RBF

Theorem (Buzzi, Grippo, Sciandrone 2000, [1])

Let $\{(v^k, c^k)\}$ be an infinite sequence generated the Two-blocks Algorithm. Then:

i)
$$\{(v^k, c^k)\}$$
 has limit points;

- ii) the sequence $\{E(v^k, c^k)\}$ converges to a limit;
- iii) every limit point of $\{(v^k, c^k)\}$ is a stationary point of E.



More than two-blocks decomposition in RBF

Even the approximate minimization with respect to the centers can be very expensive when N is large.



More than two-blocks decomposition in RBF

Even the approximate minimization with respect to the centers can be very expensive when N is large. The variables (v, c) are partitioned into the N + 1 blocks, corresponding to the weights vand the N center positions $c_1, c_2 \dots, c_N$.

Step 2. (Minimization with respect to centers)

For j = 1, ..., N.

$$c_{j}^{k+1} = c_{j}^{k} - \eta_{j}^{k} \nabla_{c_{j}} E(v^{k+1}, c_{1}^{k+1}, \dots, c_{j-1}^{k+1}, \frac{c_{j}}{c_{j}}, c_{j+1}^{k}, \dots, c_{N}^{k})$$

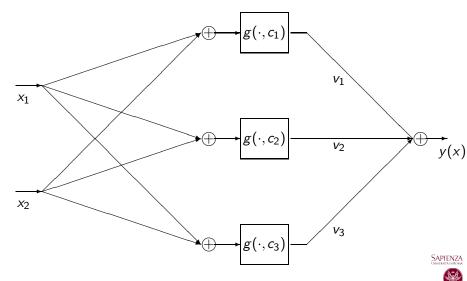
with
$$\eta_i^k$$
 satisfying

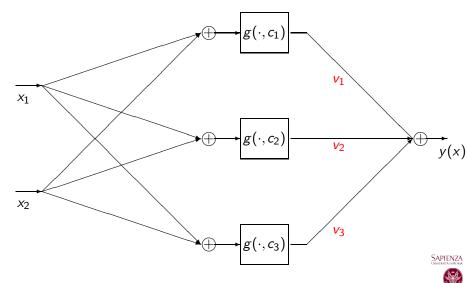
$$E(v^{k+1}, c^{k+1}) \le E(v^{k+1}, c^k) - \gamma \eta_j^k \|\nabla_{c_j} E(v^{k+1}, c^k)\|^2$$

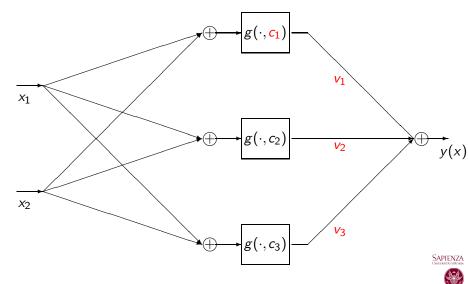
Set
$$\xi_i^{k+1} \leq \theta \xi_i^k$$

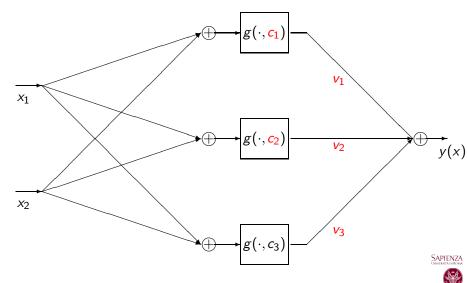
Decomposition methods for FFN

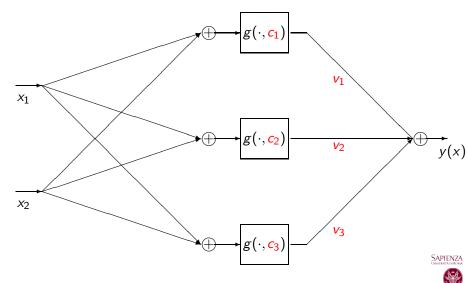


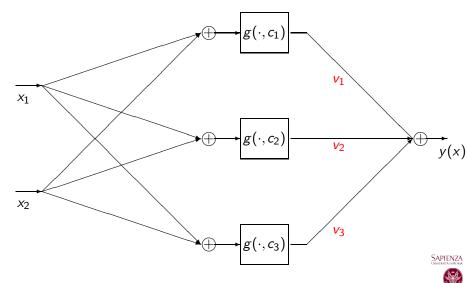












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PROs

- Problem can be decomposed into much smaller subproblems
- Gradient type iteration
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Computational price

(Cost of line-search)



References



C Buzzi, L Grippo, and Marco Sciandrone.

Convergent decomposition techniques for training rbf neural networks. *Neural Computation*, 13(8):1891–1920, 2001.

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