

Ottimizzazione Combinatoria 2

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*Un esempio basato sulle slide della seguente lezione del
Corso **Network Optimization MITOpenCourseware***

<http://ocw.mit.edu/courses/sloan-school-of-management/15-082j-network-optimization-fall-2010/>

15.082J and 6.855J and ESD.78J

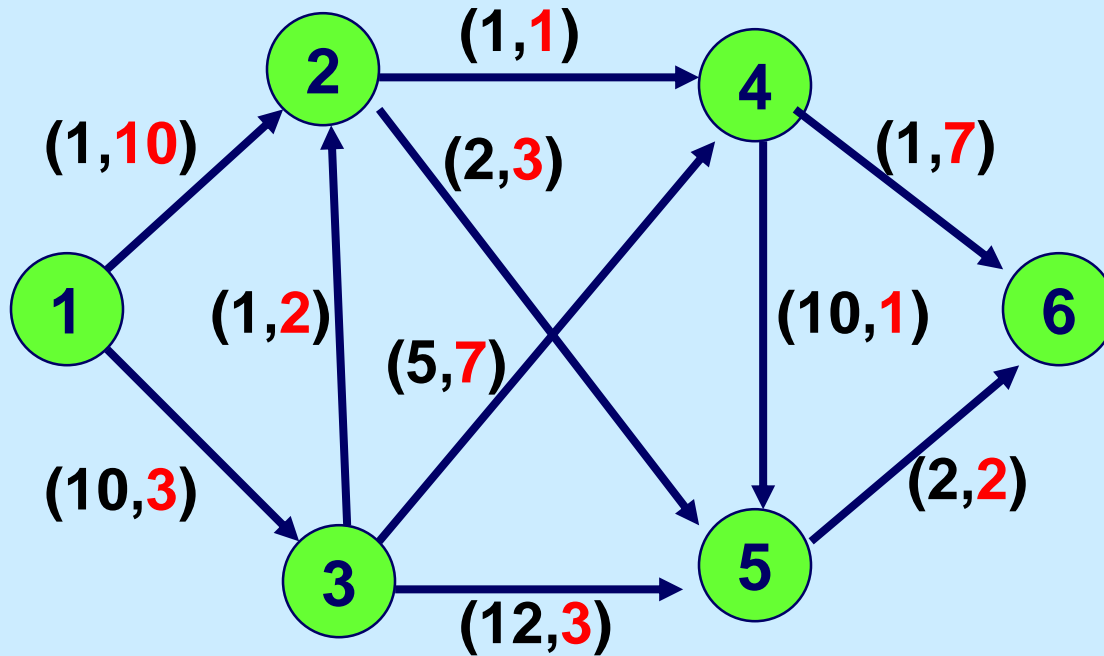
Lagrangian Relaxation 2

- Applications
- Algorithms
- Theory

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The Constrained Shortest Path Problem



Find the ***path of minimum cost*** (**black**) from node **1** to node **6** with a ***transit time*** (**red**) at most 14.

Constrained Shortest Paths: Path Formulation

Given: a network $G = (N,A)$

w_{ij} cost for arc (i,j)

$w(P)$ cost of path P

t_{ij} traversal time for arc (i,j)

T upper bound on transit times.

$t(P)$ traversal time for path P

\mathbf{P} set of paths from node 1 to node n
(nodi 1 e 6 nell'esempio)

$$\begin{array}{ll} \text{Min} & w(P) \\ \text{s.t.} & t(P) \leq T \\ & P \in \mathbf{P} \end{array}$$

Constrained Problem

$$\begin{array}{ll} L(\mu) = \text{Min} & w(P) + u (t(P) - T) \\ \text{s.t.} & P \in \mathbf{P} \end{array}$$

Lagrangian

The Lagrangian Multiplier Problem

Step 0. Formulate the Lagrangian Problem.

$$\begin{aligned} L(u) = \text{Min} \quad & w(P) + u t(P) - uT \\ \text{s.t.} \quad & P \in \mathbf{P} \end{aligned}$$

Step 1. Rewrite as a maximization problem

$$\begin{aligned} L(u) = v^* = \text{Max } v \\ \text{s.t.} \quad v \leq w(P) + u t(P) - uT \\ \text{for all } P \in \mathbf{P} \end{aligned}$$

Step 2. Write the Lagrangian multiplier problem

$$\begin{aligned} L^* = \max \{L(u): u \geq 0\} = \\ = \text{Max } v \\ \text{s.t.} \quad v \leq w(P) + u t(P) - uT \\ \text{for all } P \in \mathbf{P} \\ u \geq 0 \end{aligned}$$

$$\text{Max } \{ v: v \leq w(P) + u t(P) - uT \quad \forall P \in \mathbf{P}, u \geq 0 \}$$

$$-uT + \text{Min } \{ w(P) + u t(P) : P \in \mathbf{P} \} \rightarrow P^* = \text{Path}(u)$$

Rappresentiamo un cammino P con il suo **vettore di incidenza** x ($x_{ij} = 1 \leftrightarrow ij \in P$) e sia Q_{st} il **poliedro dei cammini minimi** tra i nodi s e t (nell'esempio 1 e 6).

Il problema corrispondente ad un **fissato** u si scrive:

$$-uT + \min \left\{ \sum_{ij \in A} w_{ij} x_{ij} + u \sum_{ij \in A} t_{ij} x_{ij} : x \in Q_{st} \cap \{0, 1\}^{|A|} \right\}$$

Ovvero:

$$L(u) = -uT + \min \left\{ \sum_{ij \in A} (w_{ij} + u t_{ij}) x_{ij} : x \in Q_{st} \cap \{0, 1\}^{|A|} \right\}$$

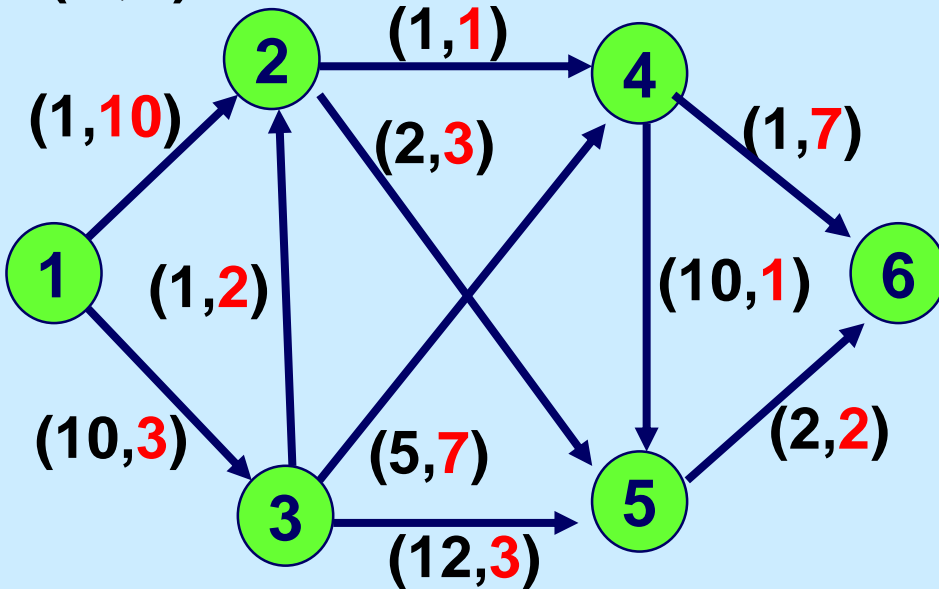
Per u fissato il problema lagrangiano è un problema di cammino minimo con pesi $(w_{ij} + u t_{ij})$

$$\text{Max } \{ v: v \leq w(P) + u t(P) - uT \quad \forall P \in \mathbf{P}, u \geq 0 \}$$

$$-uT + \text{Min } \{ w(P) + u t(P) : P \in \mathbf{P} \} \rightarrow P^* = \text{Path}(u)$$

Per u fissato \rightarrow Cammino minimo con pesi $(w_{ij} + ut_{ij})$

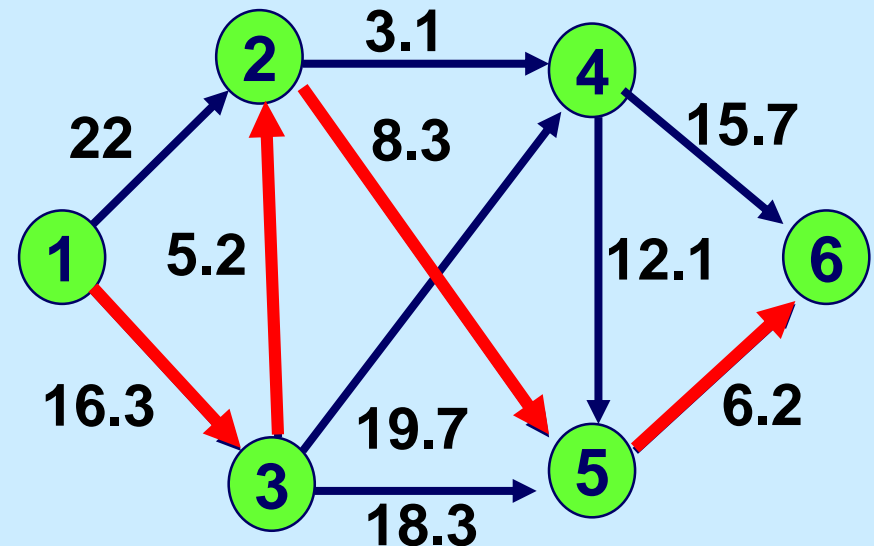
(w, t)



$$u = 0 \rightarrow w_{ij}$$

$$u = M \gg 0 \rightarrow w_{ij} + M t_{ij} \approx M t_{ij}$$

$$u = 2.1$$



Per ogni u una diversa istanza del cammino minimo

Discretizzazione del problema lagrangiano

$$Q \cap \{0,1\}^n = \{x^1, x^2, \dots, x^p\} \quad \Rightarrow \quad x^k \in Q_{st} \cap \{0,1\}^{|A|}$$

x^k Vettore di incidenza di un cammino s-t (1-n)

$$L(u) = \min_{k=1, \dots, p} \{w^T x^k + u^T (b - Ax^k)\} = \min_{k=1, \dots, p} \{L^k(u)\}$$

$$L^k(u) = w^T x^k + u^T (b - Ax^k) \quad \Rightarrow \quad w(P) + u (t(P) - T)$$

Iperpiano in R^{m+1}

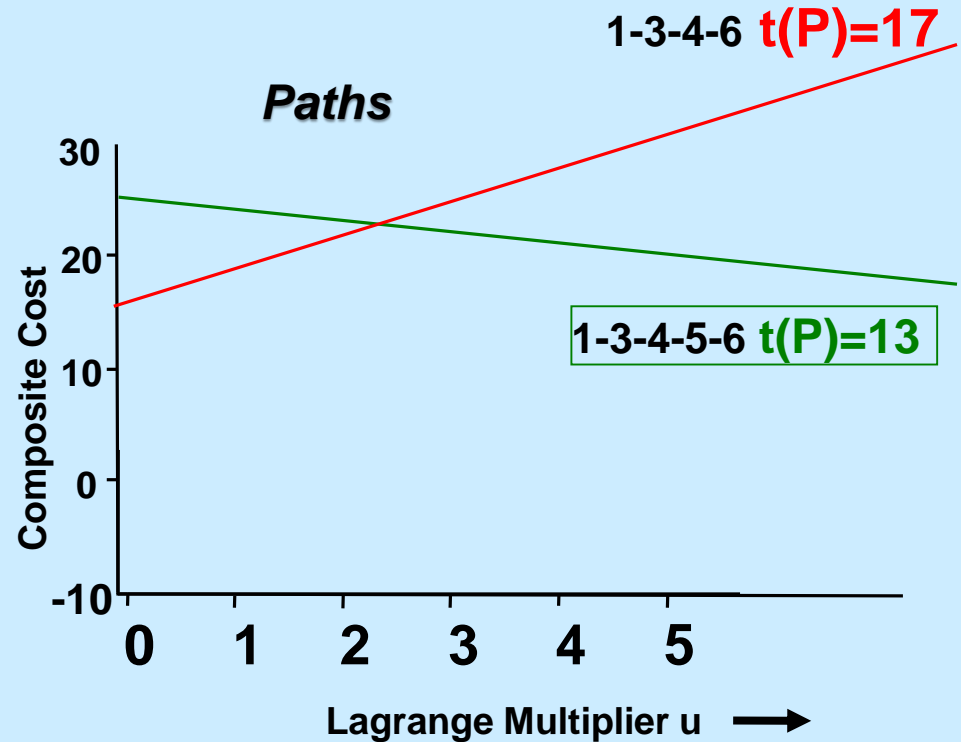
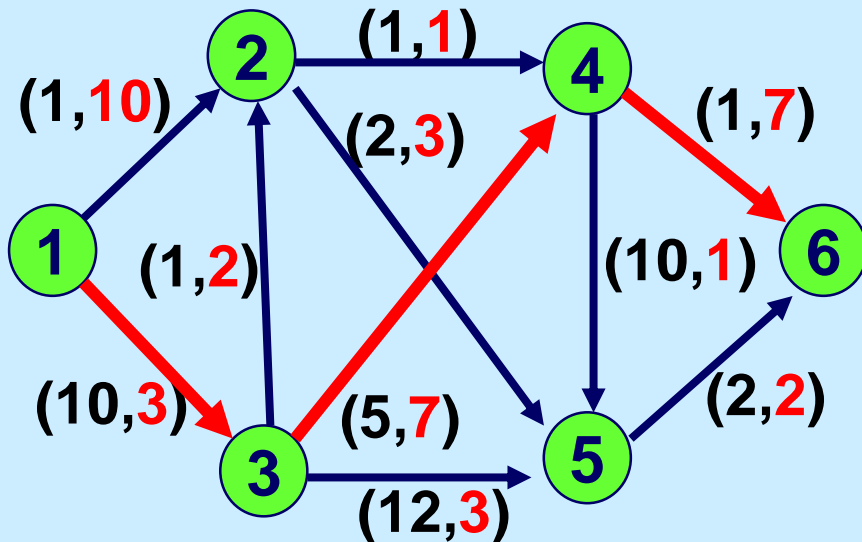
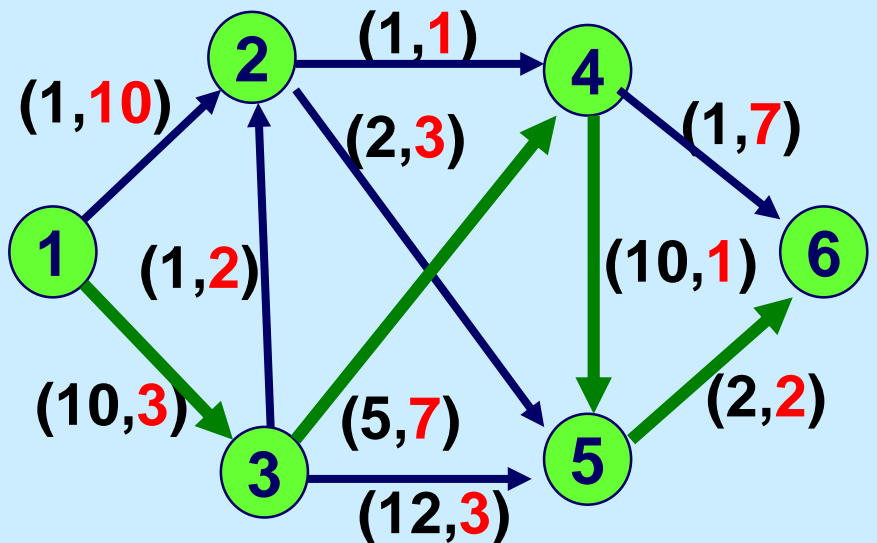
$$L^k(u) = \sum_{ij \in A} w_{ij} x_{ij}^k + u \left(\sum_{ij \in A} t_{ij} x_{ij}^k - T \right)$$

Positivo se il vincolo è violato

Ogni soluzione x^k (cammino) definisce un iperpiano (retta)

Discretizzazione del problema lagrangiano

Ogni soluzione (cammino) definisce un iperpiano (retta)



$$w(P) + u (t(P) - T)$$

$$27 + u (13 - 14) \text{ [pendenza neg]}$$

$$16 + u (17 - 14) \text{ [pendenza pos]}$$

$$\text{Max } \{ v: v \leq w(P) + u t(P) - uT \quad \forall P \in \mathbf{P}, \\ \text{and } u \geq 0 \}$$

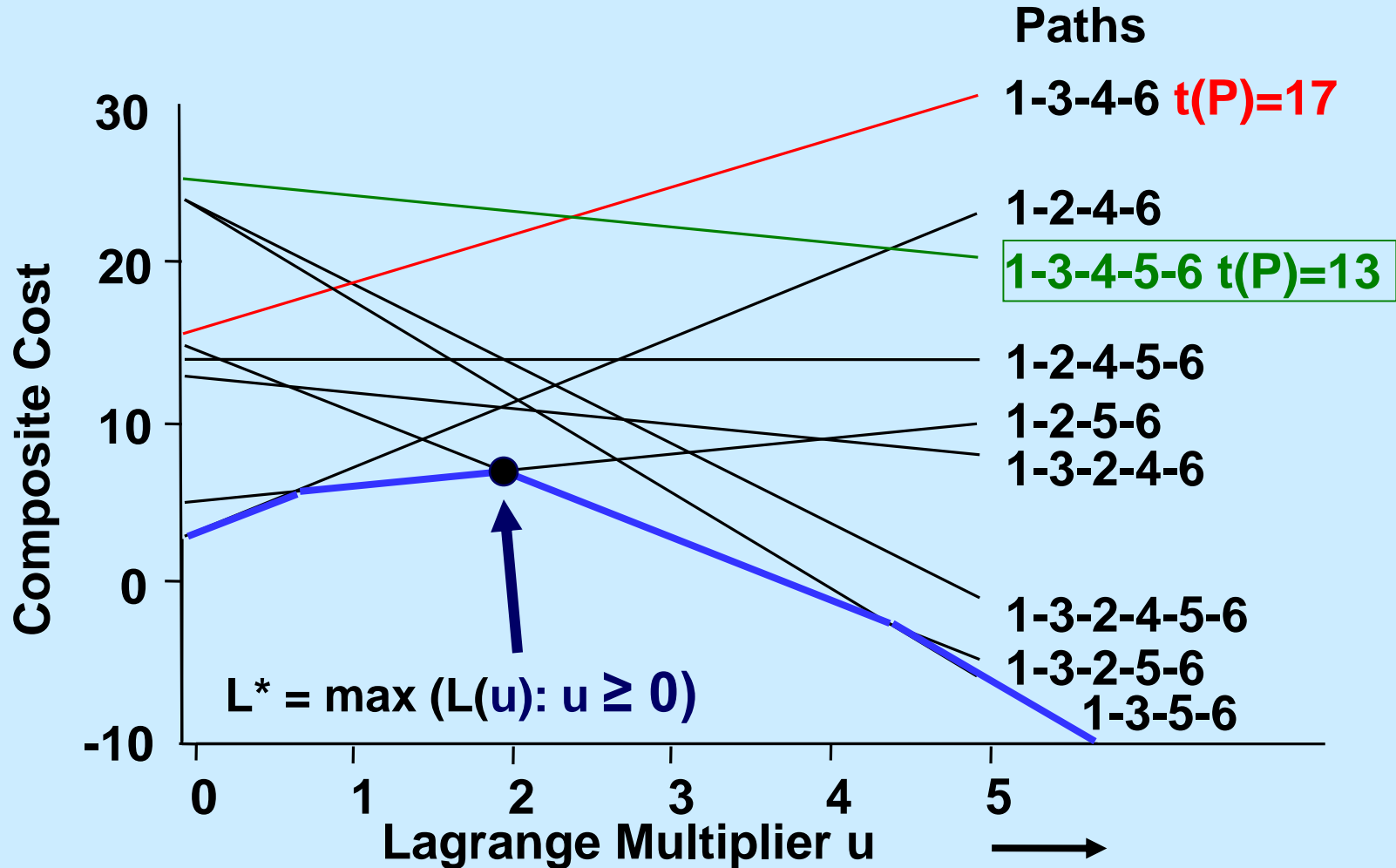


Figure 16.3 The Lagrangian function for $T = 14$.

The Restricted Lagrangian

P : the set of paths from node 1 to node n

B \subseteq **P** : a subset of paths

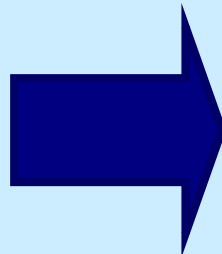
$$\begin{aligned} L^* = v^* = \max v \\ \text{s.t. } v \leq w(P) + u (t(P) - T) \\ \text{for all } P \in \mathbf{P} \\ u \geq 0 \end{aligned}$$

Lagrangian Multiplier Problem

$$\begin{aligned} L_B^* = \max v \\ \text{s.t. } v \leq w(P) + u t(P) - u T \\ \text{for all } P \in \mathbf{B} \\ u \geq 0 \end{aligned}$$

Restricted Lagrangian
Multiplier Problem

$$L(u) \leq L^* \leq L_B^*$$



$$\text{If } L(u) = L_B^* \text{ then } L(u) = L^*.$$

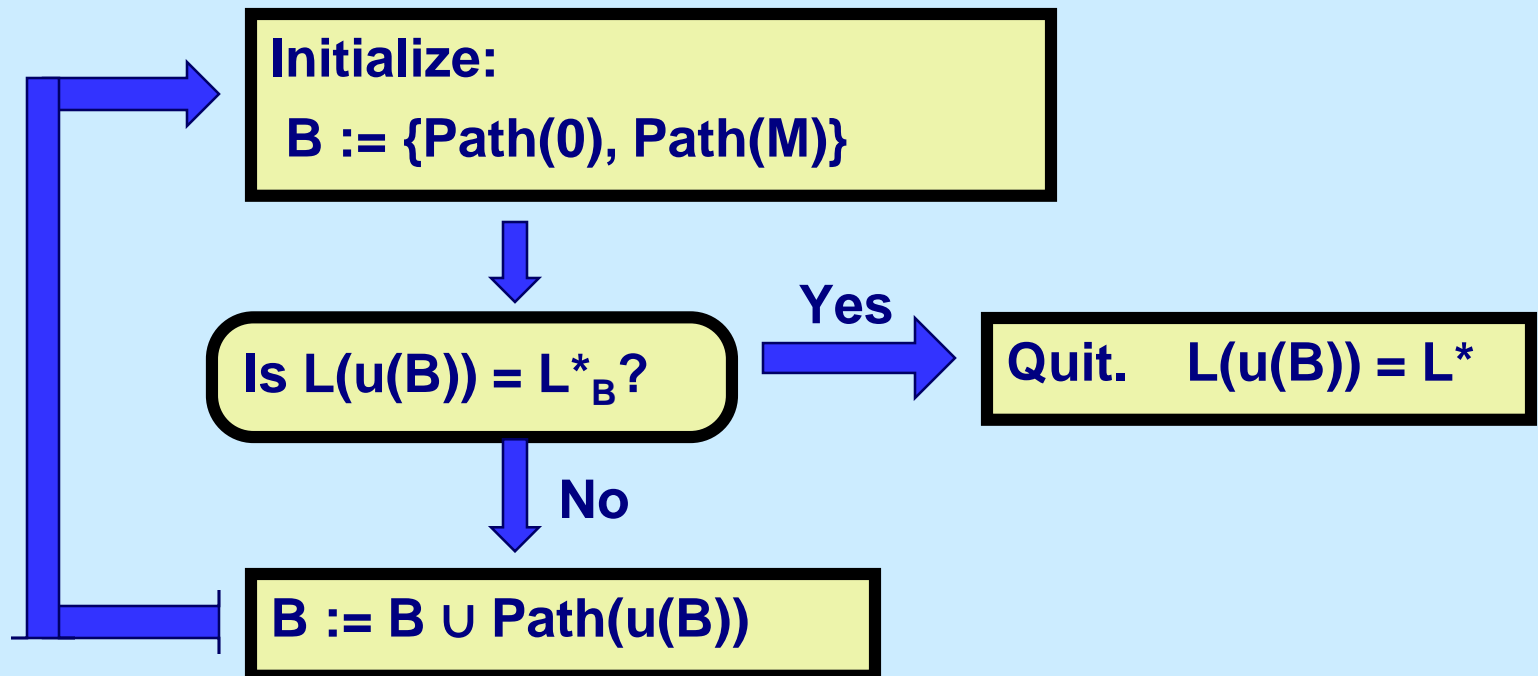
Optimality Conditions

Constraint Generation for Finding L^*

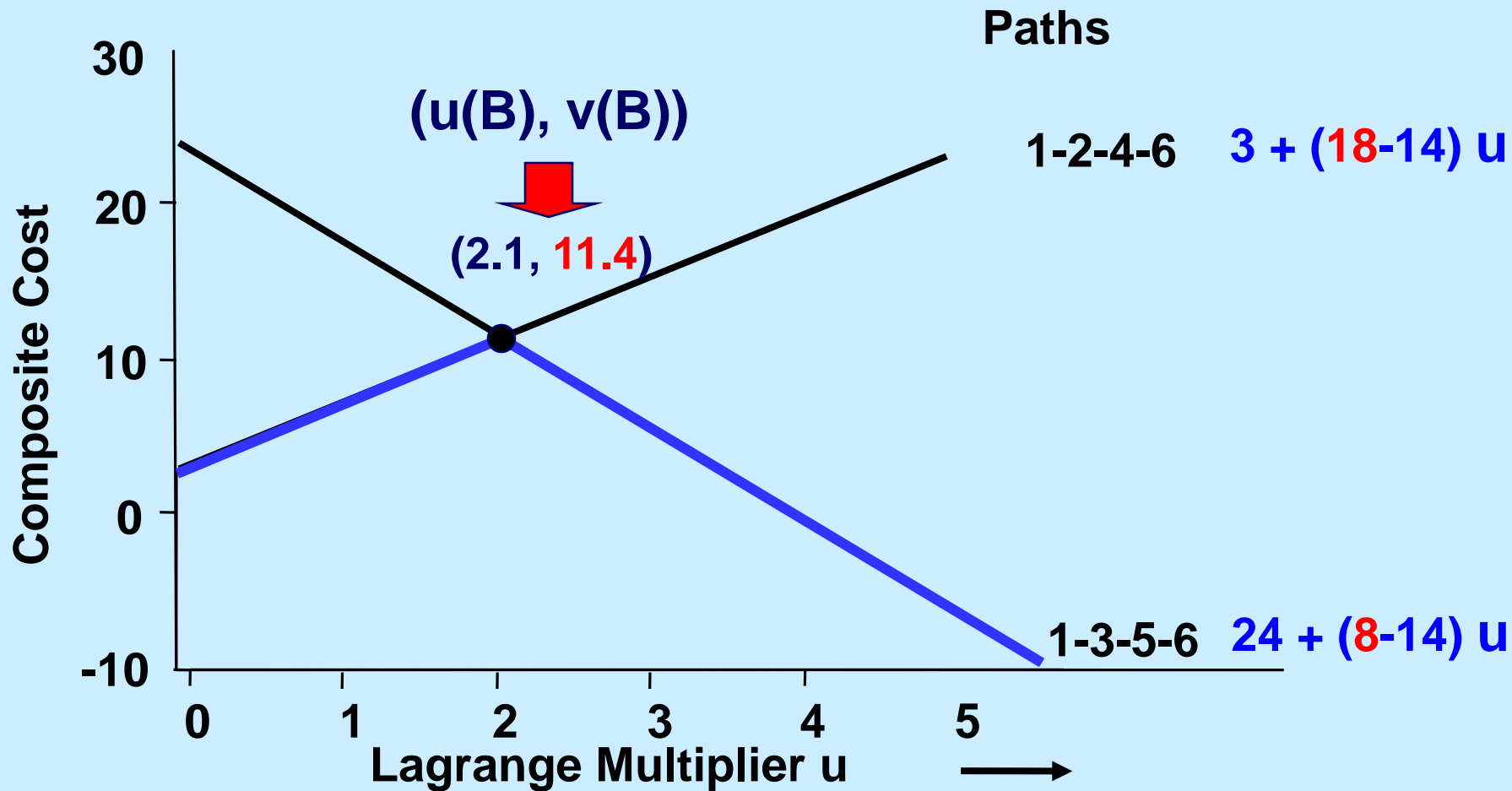
Let $\text{Path}(u)$ be the path (*iperpiano*) that optimizes $L(u)$.

Let $u(B)$ be the value of u that optimizes $L_B(u)$.

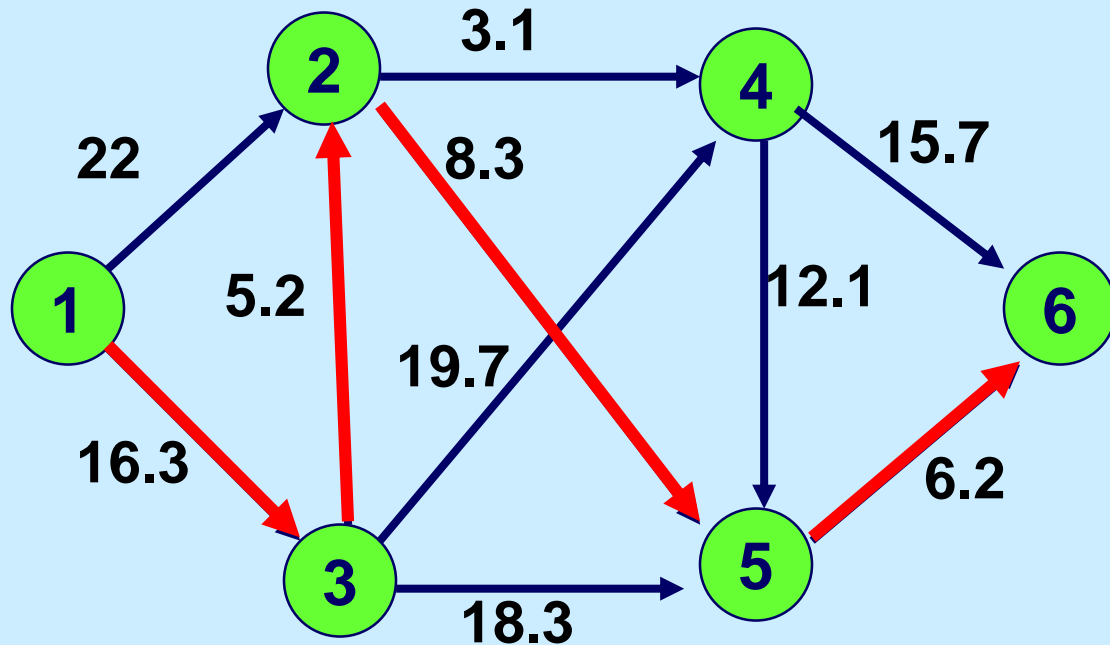
M is some large number



We start with the paths 1-2-4-6, and 1-3-5-6 which are optimal for $L(0)$ and $L(\infty)$.



Set $u(B) = 2.1$ and solve the CSP problem $(L(u(B)))$



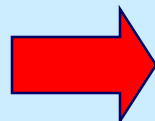
$$L(u(B)) = -u(B)T + w(P^*) + u(B)t(P^*) = -2.1 * 14 + 36 = -29.4 + 36 = 6.6$$

Ovvero:

$$L(u(B)) = 15 + 10 u(B) - 14 u(B)$$

$$15 + 21 - 29.4 = 6.6$$

$6.6 < 11.4$



Aggiungi il path P^* e riottimizza

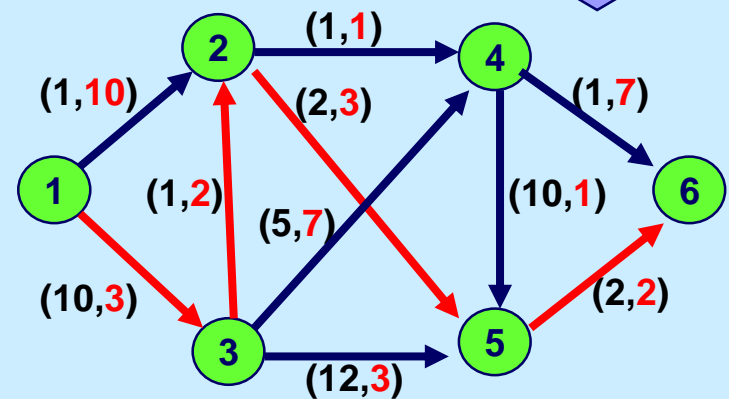
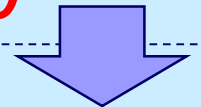
The optimum path

P^* is 1-3-2-5-6

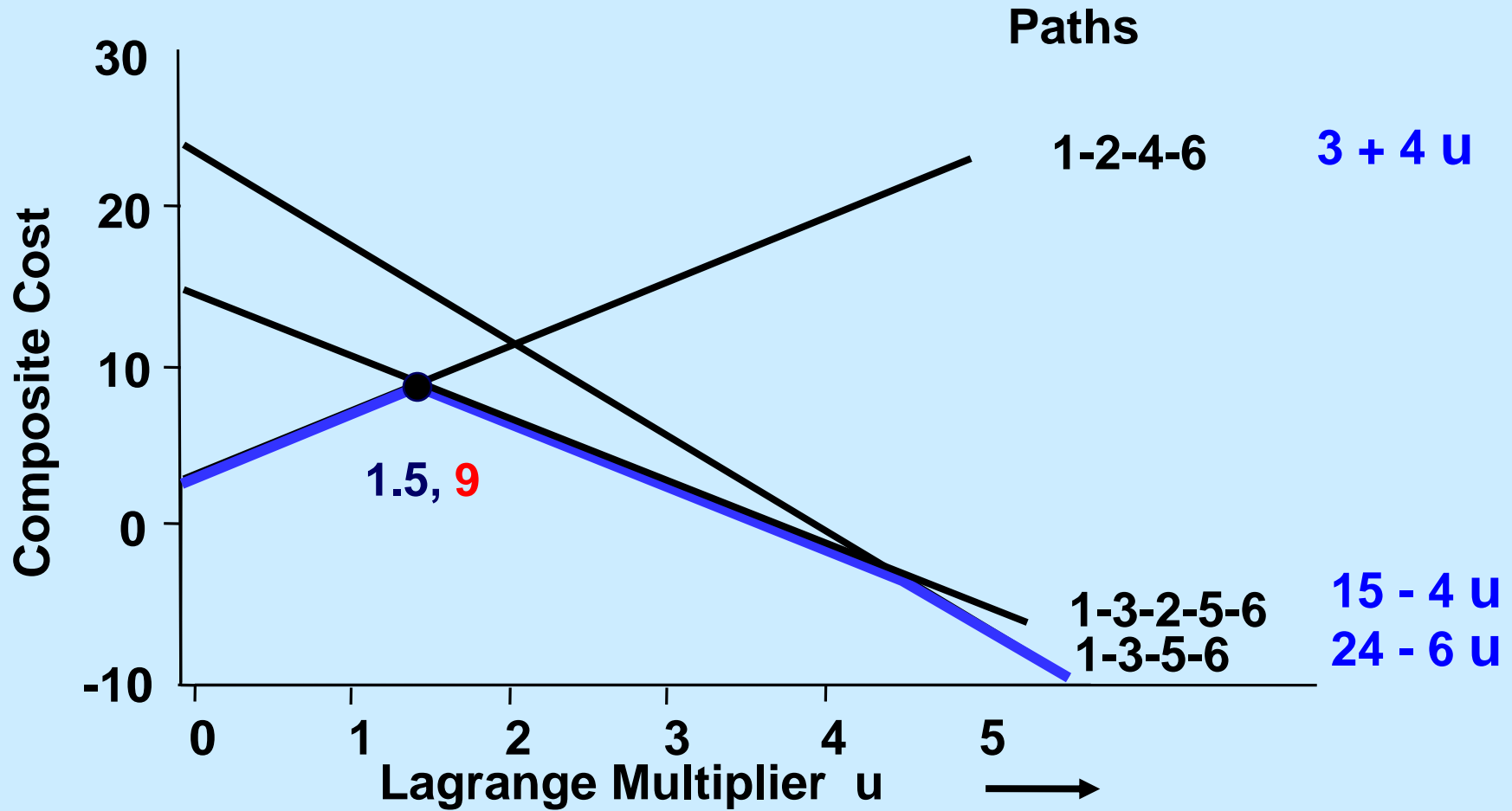
Costo modificato = 36

Costo = 15

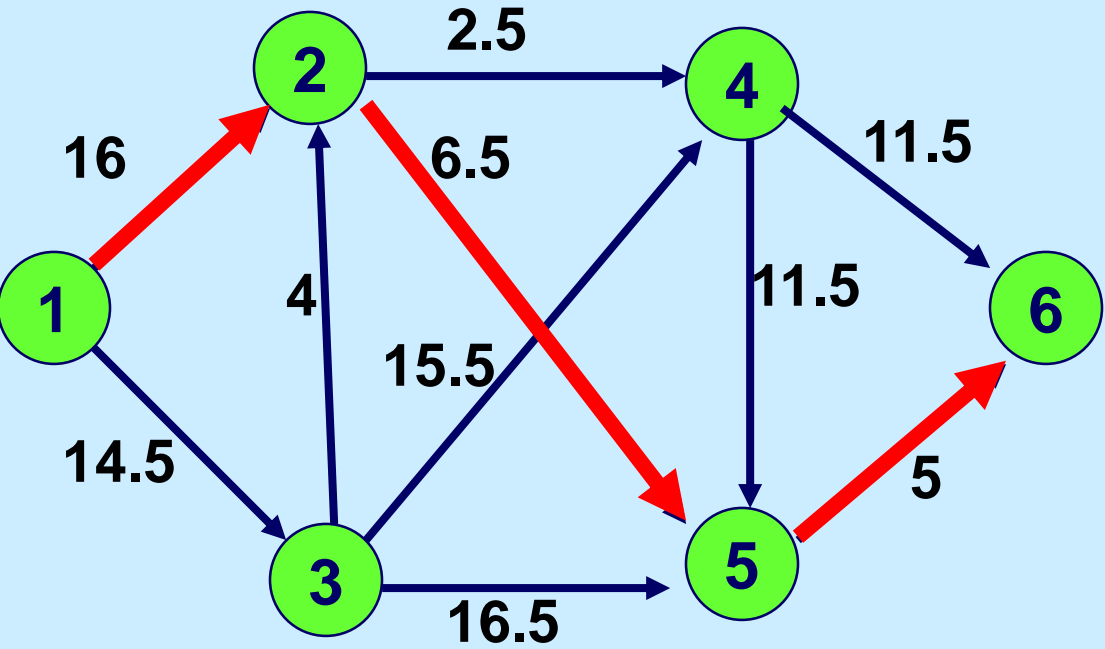
T. Transito = 10



Path(2.1) = 1-3-2-5-6. Add it to S and reoptimize.



Set $u(B) = 1.5$ and solve the CSP problem $(L(u(B)))$

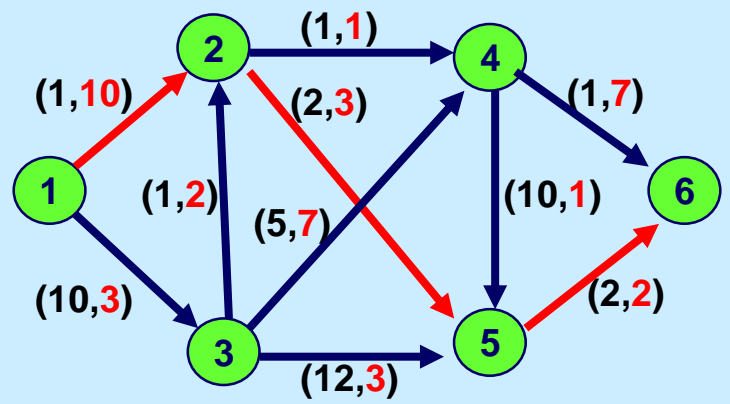


The optimum path P^* is 1-2-5-6.

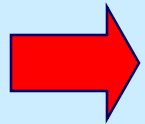
Costo modificato = 27.5
Costo = 5
T. Transito = 15

$$L(u(B)) = 5 + 15 u(B) - 14 u(B)$$

$$5 + 22.5 - 21 = 6.5$$

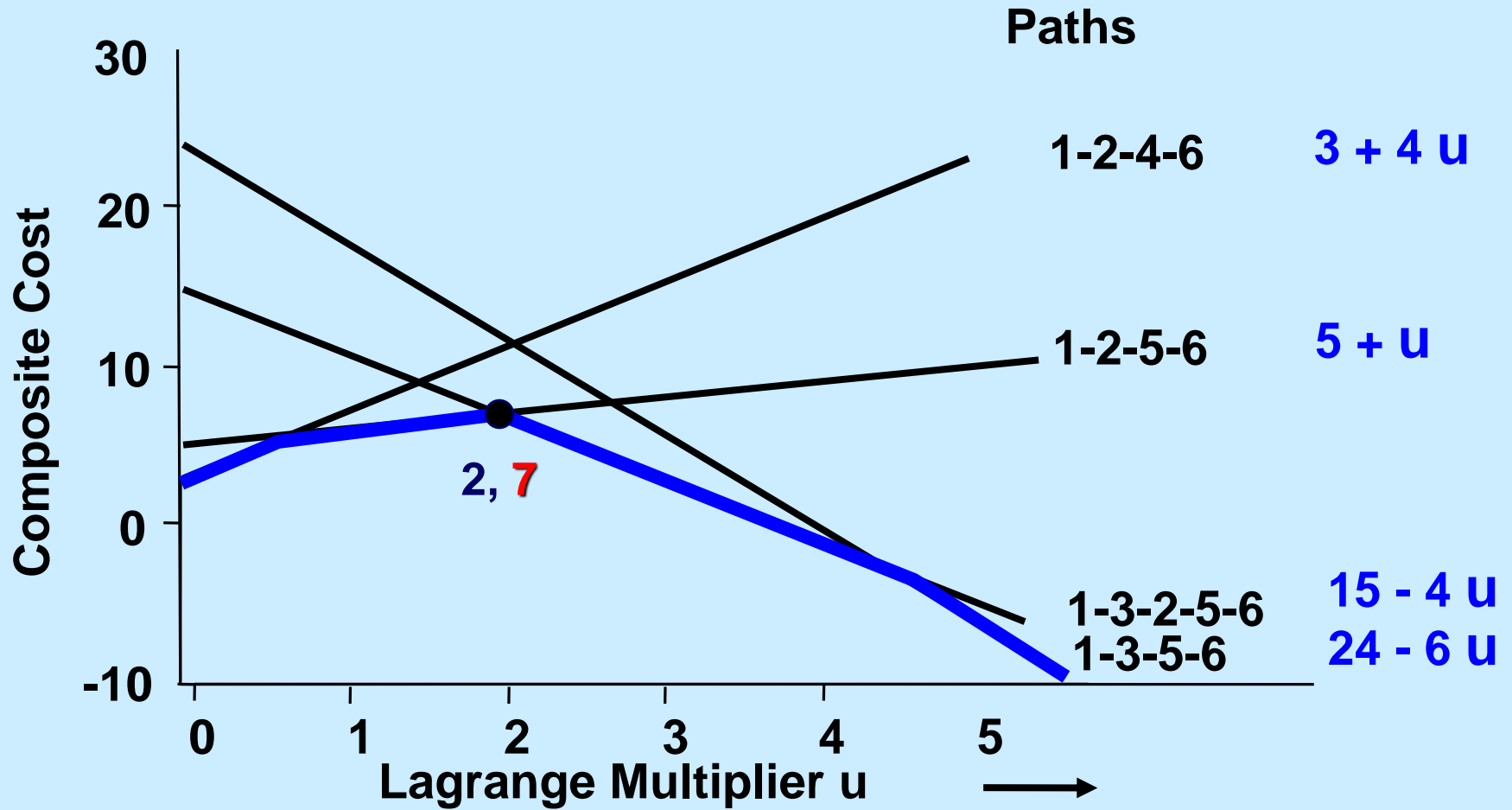


6.5 < 9

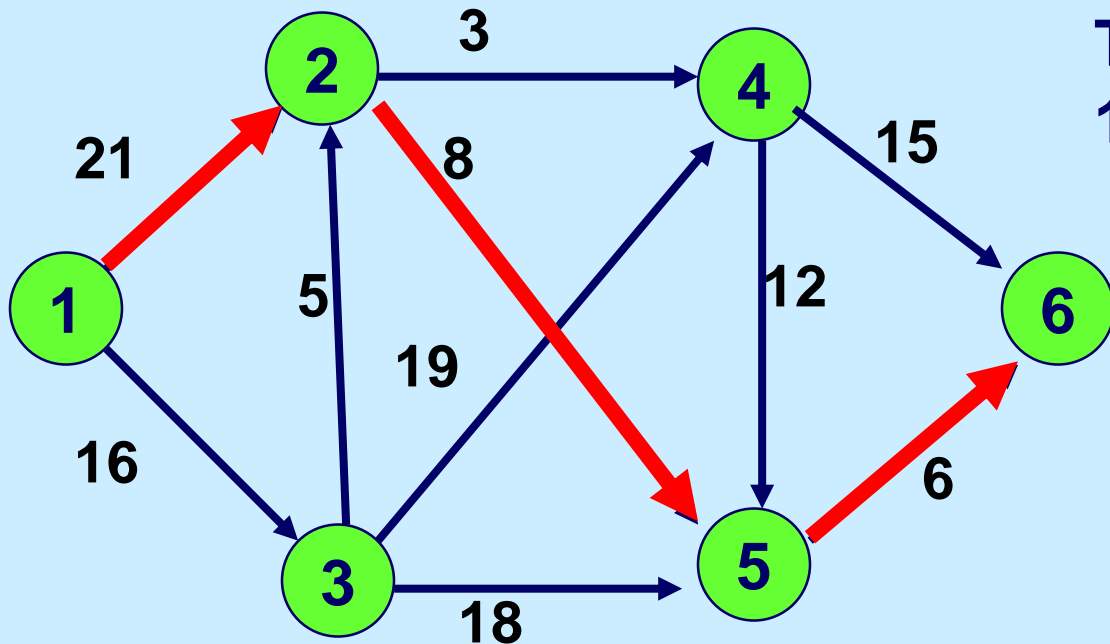


Aggiungi il path P^* e riottimizza

Add Path 1-2-5-6 and reoptimize



Set $u(B) = 2$ and solve the CSP problem $(L(u(B)))$



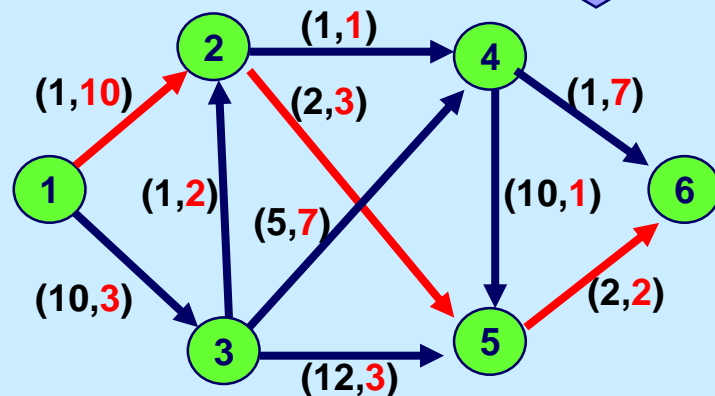
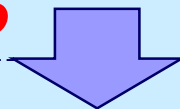
The optimum paths are 1-2-5-6 and 1-3-2-5-6

Scegliamo 1-2-5-6

Costo modificato = 35

Costo = 5

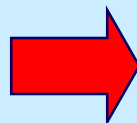
T. Transito = 15



$$L(u(B)) = 5 + 15 u(B) - 14 u(B)$$

$$= 5 + 30 - 28 = 7$$

$$7 = v(B) = 7$$



Ottimo del Duale
Lagrangiano

There are no new paths to add.

$u(B) = u^*$ is **optimal** for the multiplier problem

