

Transition semantics: intro

Idea: describe the result of executing a **single step** of the Golog program.

- *Given a Golog program δ and a situation s compute the situation s' and the program δ' that remains to be executed obtained by executing a single step of δ in s .*
- *Assert when a Golog program δ can be considered **successfully terminated** in a situation s .*

Transition semantics: intro

More formally:

- Define the **relation**, named *Trans* and denoted by “ \longrightarrow ”):

$$(\delta, s) \longrightarrow (\delta', s')$$

where δ is a program, s is the situation in which the program is executed, and s' is the situation obtained by executing a single step of δ and δ' is what remains to be executed of δ after such a single step.

- Define a **predicate**, named *Final* and denoted by “ \checkmark ”):

$$(\delta, s) \checkmark$$

where δ is a program that can be considered (successfully) terminated in the situation s .

Such a relation and predicate can be defined inductively in a standard way, using the so called **transition (structural) rules**

Transition semantics: references

The general approach we follow is the *structural operational semantics* approach [Plotkin81, Nielson&Nielson99].

This single-step semantics is often called: *transition semantics* or *computation semantics*.

Transition rules for Golog: deterministic constructs

$$\text{Act : } \frac{(a, s) \longrightarrow (\text{nil}, \text{do}(a[s], s))}{\text{true}} \quad \text{if } \text{Poss}(a[s], s)$$

$$\text{Test : } \frac{(\phi?, s) \longrightarrow (\text{nil}, s)}{\text{true}} \quad \text{if } \phi[s]$$

$$\text{Seq : } \frac{(\delta_1; \delta_2, s) \longrightarrow (\delta'_1; \delta_2, s')}{(\delta_1, s) \longrightarrow (\delta'_1; s')} \quad \frac{(\delta_1; \delta_2, s) \longrightarrow (\delta'_2, s')}{(\delta_2, s) \longrightarrow (\delta'_2; s')} \quad \text{if } (\delta_1, s)^\vee$$

$$\text{if : } \frac{(\text{if } \phi \text{ then } \delta_1 \text{ else } \delta_2, s) \longrightarrow (\delta'_1, s')}{(\delta_1, s) \longrightarrow (\delta'_1, s')} \quad \text{if } \phi[s] \quad \frac{(\text{if } \phi \text{ then } \delta_1 \text{ else } \delta_2, s) \longrightarrow (\delta'_2, s')}{(\delta_2, s) \longrightarrow (\delta'_2, s')} \quad \text{if } \neg\phi[s]$$

$$\text{while : } \frac{(\text{while } \phi \text{ do } \delta, s) \longrightarrow (\delta'; \text{while } \phi \text{ do } \delta, s)}{(\delta, s) \longrightarrow (\delta', s')} \quad \text{if } \phi[s]$$

Termination rules for Golog: deterministic constructs

$$Nil : \frac{(nil, s)^\checkmark}{true}$$

$$Seq : \frac{(\delta_1; \delta_2, s)^\checkmark}{(\delta_1, s)^\checkmark \wedge (\delta_2, s)^\checkmark}$$

$$if : \frac{(\mathbf{if} \ \phi \ \mathbf{then} \ \delta_1 \ \mathbf{else} \ \delta_2, s)^\checkmark}{(\delta_1, s)^\checkmark} \quad \text{if } \phi[s] \qquad \frac{(\mathbf{if} \ \phi \ \mathbf{then} \ \delta_1 \ \mathbf{else} \ \delta_2, s)^\checkmark}{(\delta_2, s)^\checkmark} \quad \text{if } \neg\phi[s]$$

$$while : \frac{(\mathbf{while} \ \phi \ \mathbf{do} \ \delta, s)^\checkmark}{true} \quad \text{if } \neg\phi[s] \qquad \frac{(\mathbf{while} \ \phi \ \mathbf{do} \ \delta, s)^\checkmark}{(\delta, s)^\checkmark} \quad \text{if } \phi[s]$$

Transition rules: nondeterministic constructs

$$\text{Nondetbranch : } \frac{(\delta_1 \mid \delta_2, s) \longrightarrow (\delta'_1, s')}{(\delta_1, s) \longrightarrow (\delta'_1, s')} \quad \frac{(\delta_1 \mid \delta_2, s) \longrightarrow (\delta'_2, s')}{(\delta_2, s) \longrightarrow (\delta'_2, s')}$$

$$\text{Nondetchoice : } \frac{(\pi x. \delta(x), s) \longrightarrow (\delta'(t), s')}{(\delta(t), s) \longrightarrow (\delta'(t), s')} \quad (\text{for any } t)$$

$$\text{Nondetiter : } \frac{(\delta^*, s) \longrightarrow (\delta'; \delta^*, s')}{(\delta, s) \longrightarrow (\delta', s')}$$

Termination rules: nondeterministic constructs

$$\text{Nondetbranch : } \frac{(\delta_1 \mid \delta_2, s)^\surd}{(\delta_1, s)^\surd \vee (\delta_2, s)^\surd}$$

$$\text{Nondetchoice : } \frac{(\pi x. \delta(x), s)^\surd}{(\delta(t), s)^\surd} \quad (\text{for some } t)$$

$$\text{Nondetiter : } \frac{(\delta^*, s)^\surd}{\text{true}}$$

Structural rules

The structural rules have the following schema:

$$\frac{\text{CONSEQUENT}}{\text{ANTECEDENT}} \text{ if SIDE-CONDITION}$$

which is to be interpreted logically as:

$$\forall(\text{ANTECEDENT} \wedge \text{SIDE-CONDITION} \supset \text{CONSEQUENT})$$

where $\forall Q$ stands for the universal closure of all free variables occurring in Q , and, typically, ANTECEDENT, SIDE-CONDITION and CONSEQUENT share free variables.

Given a model of the SitCalc action theory, the structural rules define inductively a relation, namely: **the smallest relation satisfying the rules.**

Examples

Compute the following assuming actions are always possible:

- $(a; b, S_0) \longrightarrow (nil; b, do(a, S_0)) \longrightarrow (nil, do(b(do(a, S_0)))$
- $((a \mid b); c, S_0) \longrightarrow ???$
- $((a \mid b); c; P?, S_0) \longrightarrow ???$
- $(a; (b \mid c), S_0) \longrightarrow ???$
- $((a; b \mid a; c), S_0) \longrightarrow ???$

where P true iff a is not performed yet.

Evaluation vs. transition semantics

How do we characterize a whole computation using single steps?

First we define the relation, named $Trans^*$, denoted by \longrightarrow^* by the following rules:

$$0steps : \frac{(\delta, s) \longrightarrow^* (\delta, s)}{true}$$

$$nsteps : \frac{(\delta, s) \longrightarrow^* (\delta'', s'')}{(\delta, s) \longrightarrow (\delta', s') \wedge (\delta', s') \longrightarrow^* (\delta'', s'')} \quad (for\ some\ \delta', s')$$

Then it can be shown that:

$$(\delta, s_0) \longrightarrow s_f \equiv (\delta, s_0) \longrightarrow^* (\delta_f, s_0) \wedge (\delta_f, s_0) \checkmark \quad for\ some\ \delta_f$$

Getting logical

Till now we have defined the relation $(\delta, s) \longrightarrow (\delta', s')$ and the predicate $(\delta, s)^\vee$ in a single model of the SitCalc action theory of interest.

But what about if the action theory has incomplete information and hence admits several models?

Idea: Define a logical predicates $Trans(\delta, s, \delta', s')$ and $Final(\delta, s)$ starting from the definitions of the relation $(\delta, s) \longrightarrow (\delta', s')$, and $(\delta, s)^\vee$.

Definition of Do: intro

How: do we define a logical predicate $Trans(\delta, s, \delta', s')$ starting from the definition of the relation $(\delta, s) \longrightarrow (\delta', s')$? and the predicate $(\delta, s) \checkmark$.

- Rules correspond to logical conditions;
- The minimal predicate satisfying the rules is expressible in 2nd-order logic by using the formulas of the following form (for $Trans$, similarly for $Final$):

$$\forall T. \{$$

logical formulas corresponding to the rules
that use the **predicate variable** T in place of the relation

$$\} \supset T(\delta, s, \delta', s').$$

Definition of Trans

$Trans(\delta, s, \delta', s') \equiv \forall T. [\dots \supset T(\delta, s, \delta', s')]$, where \dots stands for the conjunction of the universal closure of the following implications:

$$\begin{aligned}
 Poss(a[s], s) &\supset T(a, s, nil, do(a[s], s)) \\
 \phi[s] &\supset T(\phi?, s, nil, s) \\
 T(\delta, s, \delta', s') &\supset T(\delta; \gamma, s, \delta'; \gamma, s') \\
 Final(\gamma, s) \wedge T(\delta, s, \delta', s') &\supset T(\gamma; \delta, s, \delta', s') \\
 T(\delta, s, \delta', s') &\supset T(\delta \mid \gamma, s, \delta', s') \\
 T(\delta, s, \delta', s') &\supset T(\gamma \mid \delta, s, \delta', s') \\
 T(\delta_x^v, s, \delta', s') &\supset T(\pi v. \delta, s, \delta', s') \\
 T(\delta, s, \delta', s') &\supset T(\delta^*, s, \delta'; \delta^*, s') \\
 T(\delta_{[Env:P_i(\vec{t})]}^{P_i(\vec{t})}, s, \delta', s') &\supset T(\{Env; \delta\}, s, \delta', s') \\
 T(\{Env; \delta_{P_{\vec{t}[s]}}^{\vec{v}_P}\}, s, \delta', s') &\supset T([Env : P(\vec{t})], s, \delta', s')
 \end{aligned}$$

Definition of Final

$Final(\delta, s) \equiv \forall F.[\dots \supset F(\delta, s)]$, where \dots stands for the conjunction of the universal closure of the following implications:

$$\begin{aligned}
 True &\supset F(nil, s) \\
 F(\delta, s) \wedge F(\gamma, s) &\supset F(\delta; \gamma, s) \\
 F(\delta, s) &\supset F(\delta \mid \gamma, s) \\
 F(\delta, s) &\supset F(\gamma \mid \delta, s) \\
 F(\delta_x^v, s) &\supset F(\pi v. \delta, s) \\
 True &\supset F(\delta^*, s) \\
 F(\delta_{[Env:P_i(\vec{t})]}^{P_i(\vec{t})}, s) &\supset F(\{Env; \delta\}, s) \\
 F(\{Env; \delta_{P_{\vec{t}[s]}}^{\vec{v}_P}\}, s) &\supset F([Env : P(\vec{t})], s)
 \end{aligned}$$

Concurrency

ConGolog is an extension of Golog that incorporates a rich account of concurrency:

- concurrent processes,
- priorities,
- high-level interrupts.

We model concurrent processes by **interleaving**: *A concurrent execution of two processes is one where the primitive actions in both processes occur, interleaved in some fashion.*

It is OK for a process to remain **blocked** for a while, the other processes will continue and eventually unblock it.

Congolog

The ConGolog language is exactly like Golog except with the following additional constructs:

if ϕ then δ_1 else δ_2 ,	synchronized conditional
while ϕ do δ ,	synchronized loop
$(\delta_1 \parallel \delta_2)$,	concurrent execution
$(\delta_1 \gg \delta_2)$,	concurrency with different priorities
$\delta \parallel$,	concurrent iteration
$\langle \phi \rightarrow \delta \rangle$,	interrupt.

The constructs **if** ϕ **then** δ_1 **else** δ_2 and **while** ϕ **do** δ are the synchronized: *testing the condition ϕ does not involve a transition per se, the evaluation of the condition and the first action of the branch chosen are executed as an atomic unit.*

Similar to test-and-set atomic instructions used to build semaphores in concurrent programming.

Transition rules: concurrency

$$\begin{array}{l}
 \textit{Conc} : \quad \frac{(\delta_1 \parallel \delta_2, s) \longrightarrow (\delta'_1 \parallel \delta_2, s')}{(\delta_1, s) \longrightarrow (\delta'_1, s')} \quad \frac{(\delta_1 \parallel \delta_2, s) \longrightarrow (\delta_1 \parallel \delta'_2, s')}{(\delta_2, s) \longrightarrow (\delta'_2, s')} \\
 \\
 \textit{PriorConc} : \quad \frac{(\delta_1 \gg \delta_2, s) \longrightarrow (\delta'_1 \gg \delta_2, s')}{(\delta_1, s) \longrightarrow (\delta'_1, s')} \quad \frac{(\delta_1 \gg \delta_2, s) \longrightarrow (\delta_1 \gg \delta'_2, s')}{(\delta_2, s) \longrightarrow (\delta'_2, s') \wedge (\delta_1, s) \not\longrightarrow} \\
 \\
 \textit{IterConc} : \quad \frac{(\delta^\parallel, s) \longrightarrow (\delta' \parallel \delta^\parallel, s')}{(\delta, s) \longrightarrow (\delta', s')} \\
 \\
 \textit{Interrupts} : \quad \frac{(\langle \phi \rightarrow \delta \rangle, s) \longrightarrow (\delta'; \langle \phi \rightarrow \delta \rangle, s')}{(\delta, s) \longrightarrow (\delta', s')} \quad \text{if } \phi[s] \wedge \textit{Interrupts_running}[s]
 \end{array}$$

Termination rules: concurrency

$$\text{Conc} : \frac{(\delta_1 \parallel \delta_2, s)^\vee}{(\delta_1, s)^\vee \wedge (\delta_2, s)^\vee}$$

$$\text{PrioConc} : \frac{(\delta_1 \gg \delta_2, s)^\vee}{(\delta_1, s)^\vee \wedge (\delta_2, s)^\vee}$$

$$\text{IterConc} : \frac{(\delta \parallel, s)^\vee}{\text{true}}$$

$$\text{Interrupts} : \frac{(\langle \phi \rightarrow \delta \rangle, s)^\vee}{\text{true}} \quad \text{if } \neg \text{Interrupts_running}[s]$$

ConGolog Transition Semantics (cont.)

$$\text{Trans}(\text{nil}, s, \delta, s') \equiv \text{False}$$

$$\text{Trans}(\alpha, s, \delta, s') \equiv$$

$$\text{Poss}(\alpha[s], s) \wedge \delta = \text{nil} \wedge s' = \text{do}(\alpha[s], s)$$

$$\text{Trans}(\phi?, s, \delta, s') \equiv \phi[s] \wedge \delta = \text{nil} \wedge s' = s$$

$$\text{Trans}([\delta_1; \delta_2], s, \delta, s') \equiv$$

$$\text{Final}(\delta_1, s) \wedge \text{Trans}(\delta_2, s, \delta, s') \quad \vee$$

$$\exists \delta'. \delta = (\delta'; \delta_2) \wedge \text{Trans}(\delta_1, s, \delta', s')$$

$$\text{Trans}([\delta_1 \mid \delta_2], s, \delta, s') \equiv$$

$$\text{Trans}(\delta_1, s, \delta, s') \vee \text{Trans}(\delta_2, s, \delta, s')$$

$$\text{Trans}(\pi x \delta, s, \delta, s') \equiv \exists x. \text{Trans}(\delta, s, \delta, s')$$

In this semantics, *Trans* and *Final* are predicates that take programs as arguments. So need to introduce terms that denote programs (reify programs). In the third axiom, ϕ is a term that denotes a formula, and $\phi[s]$ stands for $\text{Holds}(\phi, s)$, which is true iff the formula denoted by ϕ is true in s . Details are in [DLL00].

ConGolog Transition Semantics (cont.)

$$\text{Trans}(\delta^*, s, \delta, s') \equiv \exists \delta'. \delta = (\delta'; \delta^*) \wedge \text{Trans}(\delta, s, \delta', s')$$

$$\text{Trans}(\mathbf{if} \phi \mathbf{then} \delta_1 \mathbf{else} \delta_2, s, \delta, s') \equiv$$

$$\phi(s) \wedge \text{Trans}(\delta_1, s, \delta, s') \vee \neg \phi(s) \wedge \text{Trans}(\delta_2, s, \delta, s')$$

$$\text{Trans}(\mathbf{while} \phi \mathbf{do} \delta, s, \delta', s') \equiv \phi(s) \wedge$$

$$\exists \delta''. \delta' = (\delta''; \mathbf{while} \phi \mathbf{do} \delta) \wedge \text{Trans}(\delta, s, \delta'', s')$$

$$\text{Trans}([\delta_1 \parallel \delta_2], s, \delta, s') \equiv \exists \delta'.$$

$$\delta = (\delta' \parallel \delta_2) \wedge \text{Trans}(\delta_1, s, \delta', s') \vee$$

$$\delta = (\delta_1 \parallel \delta') \wedge \text{Trans}(\delta_2, s, \delta', s')$$

$$\text{Trans}([\delta_1 \gg \delta_2], s, \delta, s') \equiv \exists \delta'.$$

$$\delta = (\delta' \gg \delta_2) \wedge \text{Trans}(\delta_1, s, \delta', s') \vee$$

$$\delta = (\delta_1 \gg \delta') \wedge \text{Trans}(\delta_2, s, \delta', s') \wedge$$

$$\neg \exists \delta'', s''. \text{Trans}(\delta_1, s, \delta'', s'')$$

$$\text{Trans}(\delta^{\parallel}, s, \delta', s') \equiv$$

$$\exists \delta''. \delta' = (\delta'' \parallel \delta^{\parallel}) \wedge \text{Trans}(\delta, s, \delta'', s')$$

ConGolog Transition Semantics (cont.)

$Final(nil, s) \equiv True$

$Final(\alpha, s) \equiv False$

$Final(\phi?, s) \equiv False$

$Final([\delta_1; \delta_2], s) \equiv Final(\delta_1, s) \wedge Final(\delta_2, s)$

$Final([\delta_1 \mid \delta_2], s) \equiv Final(\delta_1, s) \vee Final(\delta_2, s)$

$Final(\pi x \delta, s) \equiv \exists x. Final(\delta, s)$

$Final(\delta^*, s) \equiv True$

$Final(\mathbf{if} \phi \mathbf{then} \delta_1 \mathbf{else} \delta_2, s) \equiv$

$\phi(s) \wedge Final(\delta_1, s) \vee \neg\phi(s) \wedge Final(\delta_2, s)$

$Final(\mathbf{while} \phi \mathbf{do} \delta, s) \equiv$

$\phi(s) \wedge Final(\delta, s) \vee \neg\phi(s)$

$Final([\delta_1 \parallel \delta_2], s) \equiv Final(\delta_1, s) \wedge Final(\delta_2, s)$

$Final([\delta_1 \gg \delta_2], s) \equiv Final(\delta_1, s) \wedge Final(\delta_2, s)$

$Final(\delta^{\parallel}, s) \equiv True$

ConGolog Transition Semantics (cont.)

Then, define relation $Do(\delta, s, s')$ meaning that process δ , when executed starting in situation s , has s' as a legal terminating situation:

$$Do(\delta, s, s') \stackrel{\text{def}}{=} \exists \delta'. Trans^*(\delta, s, \delta', s') \wedge Final(\delta', s')$$

where $Trans^*$ is the transitive closure of $Trans$. That is, $Do(\delta, s, s')$ holds iff the starting configuration (δ, s) can evolve into a configuration (δ, s') by doing a finite number of transitions and $Final(\delta, s')$.

$$Trans^*(\delta, s, \delta', s') \stackrel{\text{def}}{=} \forall T[... \supset T(\delta, s, \delta', s')]$$

where the ellipsis stands for:

$$\begin{aligned} & \forall s. T(\delta, s, \delta, s) \quad \wedge \\ & \forall s, \delta', s', \delta'', s''. T(\delta, s, \delta', s') \wedge \\ & \quad Trans(\delta', s', \delta'', s'') \supset T(\delta, s, \delta'', s''). \end{aligned}$$

Induction principles

From such definitions, natural “induction principles” emerge:

These are principles saying that to prove that a property P holds for instances of $Trans$ and $Final$, it suffices to prove that the property P is closed under the assertions in the definition of $Trans$ and $Final$, i.e.:

$$\Phi_{Trans}(P, \delta_1, s_1, \delta_2, s_2) \equiv P(\delta_1, s_1, \delta_2, s_2)$$

$$\Phi_{Final}(P, \delta_1, s_1) \equiv P(\delta_1, s_1)$$

Theorem: The following sentences are consequences of the second-order definitions of $Trans$ and $Final$ respectively:

$$\begin{aligned} \forall P. [\forall \delta_1, s_1, \delta_2, s_2. \Phi_{Trans}(P, \delta_1, s_1, \delta_2, s_2) \equiv P(\delta_1, s_1, \delta_2, s_2)] \supset \\ \forall \delta, s, \delta', s'. Trans(\delta, s, \delta', s') \supset P(\delta, s, \delta', s') \end{aligned}$$

$$\begin{aligned} \forall P. [\forall \delta_1, s_1. \Phi_{Final}(P, \delta_1, s_1) \equiv P(\delta_1, s_1)] \supset \\ \forall \delta, s. Final(\delta, s, \delta', s') \supset P(\delta, s) \end{aligned}$$

Proof

We prove only the first sentence. The proof of the second sentence is analogous.

By definition we have:

$$\begin{aligned}\forall \delta, s, \delta', s'. Trans(\delta, s, \delta', s') &\equiv \\ \forall P. [\forall \delta_1, s_1, \delta_2, s_2. \Phi_{Trans}(P, \delta_1, s_1, \delta_2, s_2) &\equiv P(\delta_1, s_1, \delta_2, s_2)] \\ &\supset P(\delta, s, \delta', s')\end{aligned}$$

By considering the only-if part of the above equivalence, we get:

$$\begin{aligned}\forall \delta, s, \delta', s'. Trans(\delta, s, \delta', s') &\wedge \\ \forall P. [\forall \delta_1, s_1, \delta_2, s_2. \Phi_{Trans}(P, \delta_1, s_1, \delta_2, s_2) &\equiv P(\delta_1, s_1, \delta_2, s_2)] \\ &\supset P(\delta, s, \delta', s')\end{aligned}$$

So moving the quantifiers around we get:

$$\begin{aligned}\forall P. [\forall \delta_1, s_1, \delta_2, s_2. \Phi_{Trans}(P, \delta_1, s_1, \delta_2, s_2) &\equiv P(\delta_1, s_1, \delta_2, s_2)] \wedge \\ \forall \delta, s, \delta', s'. Trans(\delta, s, \delta', s') & \\ &\supset P(\delta, s, \delta', s')\end{aligned}$$

and hence the thesis.

Bisimulation

Bisimulation is a relation \sim satisfying the condition:

$$\begin{aligned}(\delta_1, s_1) \sim (\delta_2, s_2) \supset & \\ & (\delta_1, s_1)^\vee \equiv (\delta_2, s_2)^\vee \wedge \\ & \forall(\delta'_1, s'_1).(\delta_1, s_1) \longrightarrow (\delta'_1, s'_1) \supset \\ & \quad \exists(\delta'_2, s'_2).(\delta_2, s_2) \longrightarrow (\delta'_2, s'_2) \wedge (\delta'_1, s'_1) \sim (\delta'_2, s'_2) \wedge \\ & \forall(\delta'_2, s'_2).(\delta_2, s_2) \longrightarrow (\delta'_2, s'_2) \supset \\ & \quad \exists(\delta'_1, s'_1).(\delta_1, s_1) \longrightarrow (\delta'_1, s'_1) \wedge (\delta'_2, s'_2) \sim (\delta'_1, s'_1)\end{aligned}$$

(δ_1, s_1) and (δ_2, s_2) are **bisimilar** if there **exists a bisimulation** between the two.

Note: it can be shown that bisimilarity is an equivalence relation.